FUJITSU SEMICONDUCTOR
DATA SHEET

DS07-13735-2E

16-bit Microcontroller

CMOS

F²MC-16LX MB90335 Series

MB90337/F337/V330A

■ DESCRIPTION

The MB90335 series are 16-bit microcontrollers designed for applications, such as personal computer peripheral devices, that require USB communications. The USB feature supports not only 12-Mbps Function operation but also Mini-HOST operation. It is equipped with functions that are suitable for personal computer peripheral devices such as displays and audio devices, and control of mobile devices that support USB communications. While inheriting the AT architecture of the F²MC* family, the instruction set supports the C language and extended addressing modes and contains enhanced signed multiplication and division instructions as well as a substantial collection of improved bit manipulation instructions. In addition, long word processing is now available by introducing a 32-bit accumulator.

Note : F²MC is the abbreviation of FUJITSU Flexible Microcontroller.

■ FEATURES

- **Clock**
  - Built-in oscillation circuit and PLL clock frequency multiplication circuit
  - Oscillation clock
  - The main clock is the oscillation clock divided into 2 (for oscillation 6 MHz : 3 MHz)
  - Clock for USB is 48 MHz
  - Machine clock frequency of 6 MHz, 12 MHz or 24 MHz selectable
  - Minimum execution time of instruction : 41.6 ns (6 MHz oscillation clock, 4-time multiplied : machine clock 24 MHz and at operating V_{CC} = 3.3 V)
- **The maximum memory space:16 Mbytes**
- **24-bit addressing**
- **Bank addressing**

(Continued)

Be sure to refer to the “Check Sheet” for the latest cautions on development.

“Check Sheet” is seen at the following support page
URL : http://www.fujitsu.com/global/services/microelectronics/product/micom/support/index.html

“Check Sheet” lists the minimal requirement items to be checked to prevent problems beforehand in system development.

2007.10

(Continued)

- **Instruction system**
  - Data types: Bit, Byte, Word, Long word
  - Addressing mode (23 types)
  - Enhanced high-precision computing with 32-bit accumulator
  - Enhanced Multiply/Divide instructions with sign and the RETI instruction
- **Instruction system compatible with high-level language (C language) and multi-task**
  - Employing system stack pointer
  - Instruction set symmetry and barrel shift instructions
- **Program Patch Function (2 address pointer)**
- **4-byte instruction queue**
- **Interrupt function**
  - Priority levels are programmable
  - 20 interrupts function
- **Data transfer function**
  - Extended intelligent I/O service function (EI^{2}OS) : Maximum of 16 channels
  - μDMAC : Maximum 16 channels
- **Low Power Consumption Mode**
  - Sleep mode (with the CPU operating clock stopped)
  - Time-base timer mode (with the oscillator clock and time-base timer operating)
  - Stop mode (with the oscillator clock stopped)
  - CPU intermittent operation mode (with the CPU operating at fixed intervals of set cycles)
- **Package**
  - LQFP-64P (FPT-64P-M09 : 0.65 mm pin pitch)
- **Process : CMOS technology**
- **Operation guaranteed temperature: −40 °C to +85 °C (0 °C to +70 °C when USB is in use)**

■ INTERNAL PERIPHERAL FUNCTION (RESOURCE)

- **I/O port : Max 45 ports**
- **Time-base timer : 1channel**
- **Watchdog timer : 1 channel**
- **16-bit reload timer : 1 channel**
- **Multi-functional timer**
  - 8/16-bit PPG timer (8-bit × 4 channels or 16-bit × 2 channels) the period and duty of the output pulse can be set by the program.
  - 16-bit PWC timer : 1 channel
    Timer function and pulse width measurement function
- **UART : 2 channels**
  - Equipped with Full duplex double buffer with 8-bit length
  - Asynchronous transfer or clock-synchronous serial (extended I/O serial) transfer can be set.
- **Extended I/O serial interface : 1 channel**
- **DTP/External interrupt circuit (8 channels)**
  - Activate the extended intelligent I/O service by external interrupt input
  - Interrupt output by external interrupt input
- **Delayed interrupt output module**
  - Output an interrupt request for task switching
- **USB : 1 channel**
  - USB function (conform to USB 2.0 Full Speed)
  - Full Speed is supported/Endpoint are specifiable up to six.
  - Dual port RAM (The FIFO mode is supported).
  - Transfer type: Control, Interrupt, Bulk or Isochronous transfer possible
  - USB Mini-HOST function
- **I^2C* Interface : 1 channel**
  - Supports Intel SM bus standards and Phillips I^2C bus standards
  - Two-wire data transfer protocol specification
  - Master and slave transmission/reception

* : I^2C license :
Purchase of Fujitsu I^2C components conveys a license under the Philips I^2C Patent Rights to use, these components in an I^2C system provided that the system conforms to the I^2C Standard Specification as defined by Phillips.

■ PRODUCT LINEUP

Part number	MB90V330A	MB90F337	MB90337
Type	For evaluation	Built-in Flash Memory	Built-in MASK ROM
ROM capacity	No	64 Kbytes	
RAM capacity	28 Kbytes	4 Kbytes	
Emulator-specific power supply *	Used bit	—	
CPU functions	Number of basic instructions : 351 instructions Minimum instruction execution time : 41.6 ns / at oscillation of 6 MHz (When 4 times are used : Machine clock of 24 MHz) Addressing type : 23 types Program Patch Function : For 2 address pointers Maximum memory space : 16 Mbytes		
Ports	I/O Ports(CMOS) 45 ports		
UART	Equipped with full-duplex double buffer Clock synchronous or asynchronous operation selectable. It can also be used for I/O serial. Built-in special baud-rate generator Built-in 2 channels		
16-bit reload timer	16-bit reload timer operation Built-in 1 channel		
Multi-functional timer	8/16-bit PPG timer (8-bit mode × 4 channels, 16-bit mode × 2 channels) 16-bit PWC timer × 1 channel		
DTP/External interrupt	8 channels Interrupt factor : “L”→“H” edge /“H”→“L” edge /“L” level /“H” level selectable		
I²C	1 channel		
Extended I/O serial interface	1 channel		
USB	1 channel USB function (conform to USB 2.0 Full Speed) USB Mini-HOST function		
Withstand voltage of 5 V	8 ports (Excluding UTEST and I/O for I²C)		
Low Power Consumption Mode	Sleep mode/Timebase timer mode/Stop mode/CPU intermittent mode		
Process	CMOS		
Operating voltage V_{CC}	3.3 V ± 0.3 V (at maximum machine clock 24 MHz)		

* : It is setting of Jumper switch (TOOL VCC) when Emulator (MB2147-01) is used. Please refer to the MB2147-01 or MB2147-20 hardware manual (3.3 Emulator-dedicated Power Supply Switching) about details.

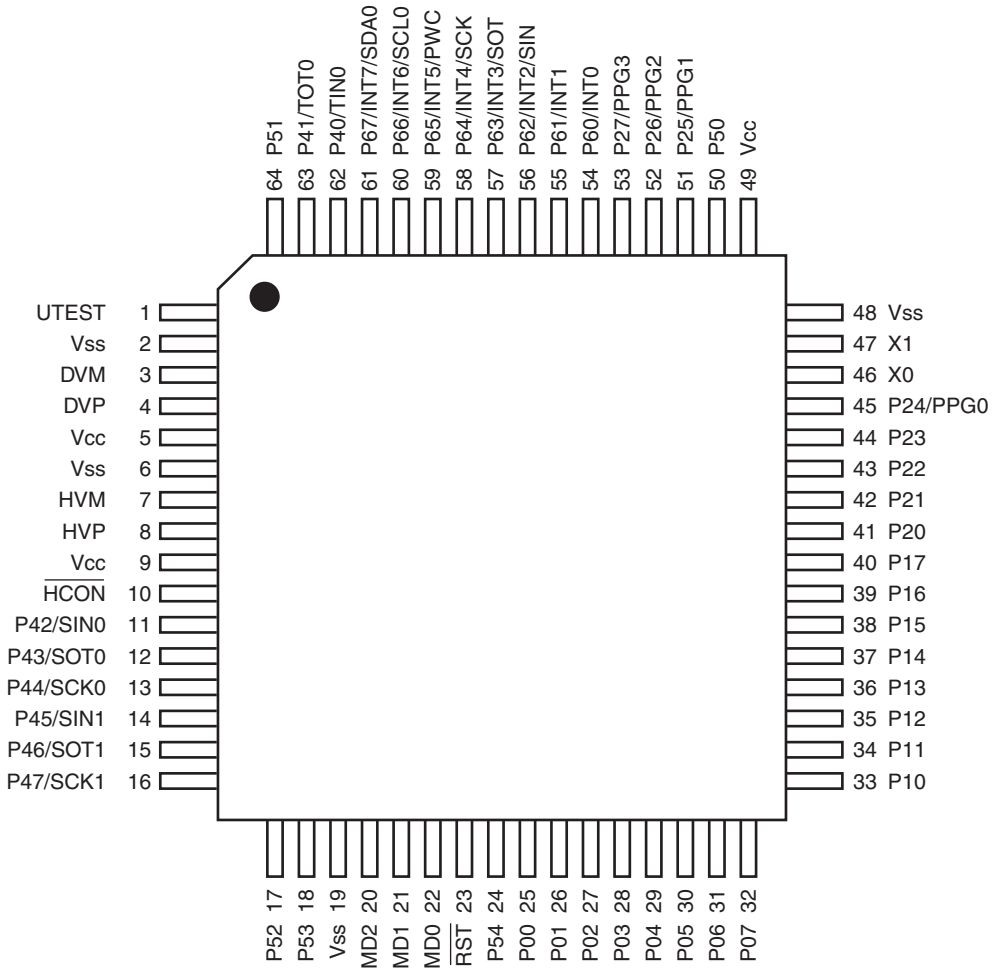
■ PACKAGES AND PRODUCT MODELS

Package	MB90337	MB90F337	MB90V330A
FPT-64P-M09 (LQFP-0.65 mm)	○	○	×
PGA-299C-A01 (PGA)	×	×	○

○ : Yes × : No

■ PIN ASSIGNMENT

(TOP VIEW)



(FPT-64P-M09)

■ PIN DESCRIPTION

Pin no.	Pin name	I/O Circuit type*	Status at reset/ function	Function
46 , 47	X0, X1	A	Oscillation status	It is a terminal which connects the oscillator. When connecting an external clock, leave the X1 pin side unconnected.
23	$\overline{RST}$	F	Reset input	External reset input pin.
25 to 32	P00 to P07	I	Port input (Hi-Z)	General purpose input/output port. The ports can be set to be added with a pull-up resistor (RD00 to RD07 = 1) by the pull-up resistor setting register (RDR0). (When the power output is set, it is invalid.)
33 to 40	P10 to P17	I		General purpose input/output port. The ports can be set to be added with a pull-up resistor (RD10 to RD17 = 1) by the pull-up resistor setting register (RDR1). (When the power output is set, it is invalid.)
41 to 44	P20 to P23	D		General purpose input/output port.
45	P24	D		General purpose input/output port.
	PPG0			Functions as output pins of PPG timers ch.0.
51 to 53	P25 to P27	D		General purpose input/output port.
	PPG1 to PPG3			Functions as output pins of PPG timers ch.1 to ch.3.
62	P40	H		General purpose input/output port.
	TIN0			Function as event input pin of 16-bit reload timer.
63	P41	H		General purpose input/output port.
	TOT0			Function as output pin of 16-bit reload timer.
11	P42	H		General purpose input/output port.
	SIN0			Functions as a data input pin for UART ch.0.
12	P43	H		General purpose input/output port.
	SOT0			Functions as a data output pin for UART ch.0.
13	P44	H		General purpose input/output port.
	SCK0			Functions as a clock I/O pin for UART ch.0.
14	P45	H		General purpose input/output port.
	SIN1			Functions as a data input pin for UART ch.1.
15	P46	H		General purpose input/output port.
	SOT1			Functions as a data output pin for UART ch.1.
16	P47	H		General purpose input/output port.
	SCK1			Functions as a clock I/O pin for UART ch.1.
50	P50	K		General purpose input/output port.
64	P51	K		General purpose input/output port.
17, 18	P52, P53	K		General purpose input/output port.
24	P54	K		General purpose input/output port.

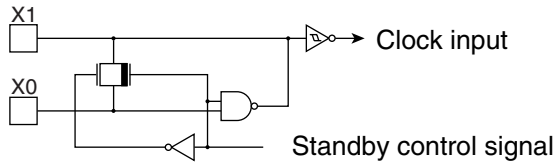
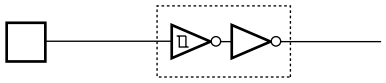
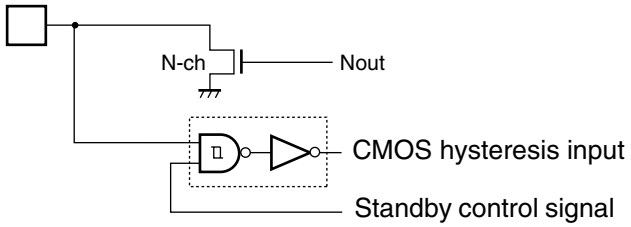
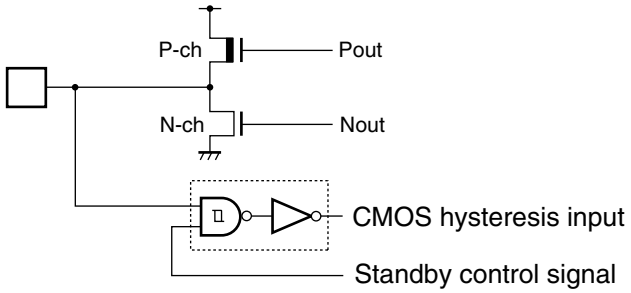
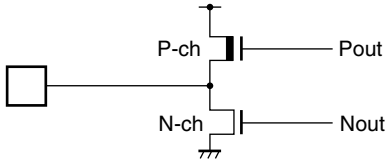
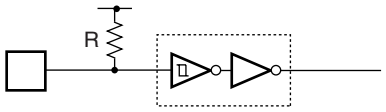
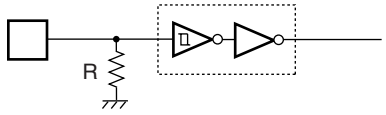
(Continued)

(Continued)

Pin no.	Pin name	I/O Circuit type*	Status at reset/ function	Function
54, 55	P60, P61	C	Port input (Hi-Z)	General purpose input/output port (withstand voltage of 5 V) .
	INT0, INT1			Functions as the input pin for external interrupt ch.0 and ch.1.
56	P62	C		General purpose input/output port (withstand voltage of 5 V) .
	INT2			Functions as the input pin for external interrupt ch.2.
	SIN			Data input pin for extended I/O serial interface.
57	P63	C		General purpose input/output port (withstand voltage of 5 V) .
	INT3			Functions as the input pin for external interrupt ch.3.
	SOT			Data output pin for extended I/O serial interface.
58	P64	C		General purpose input/output port (withstand voltage of 5 V) .
	INT4			Functions as the input pin for external interrupt ch.4.
	SCK			Clock I/O pin for extended I/O serial interface.
59	P65	C		General purpose input/output port (withstand voltage of 5 V) .
	INT5			Functions as the input pin for external interrupt ch.5.
	PWC			Functions as the PWC input pin.
60	P66	C		General purpose input/output port (withstand voltage of 5 V) .
	INT6			Functions as the input pin for external interrupt ch.6.
	SCL0			Functions as the input/output pin for I²C interface clock. The port output must be placed in Hi-Z state during I²C interface operation.
61	P67	C		General purpose input/output port (withstand voltage of 5 V) .
	INT7			Functions as the input pin for external interrupt ch.7.
	SDA0			Functions as the I²C interface data input/output pin. The port output must be placed in Hi-Z state during I²C interface operation.
1	UTEST	C	UTEST input	USB test pin. Connect this to a pull-down resistor during normal usage.
3	DVM	J	USB input (SUSPEND)	USB function D – pin.
4	DVP	J		USB function D + pin.
7	HVM	J		USB Mini-HOST D – pin.
8	HVP	J		USB Mini-HOST D + pin.
10	$\overline{\text{HCON}}$	E	High output	External pull-up resistor connection pin.
21, 22	MD1, MD0	B	Mode input	Input pin for selecting operation mode.
20	MD2	G		
5	Vcc	—	Power supply	Power supply pin.
9	Vcc	—		Power supply pin.
49	Vcc	—		Power supply pin.
2	Vss	—		Power supply pin (GND).
6	Vss	—		Power supply pin (GND).
19	Vss	—		Power supply pin (GND).
48	Vss	—		Power supply pin (GND).

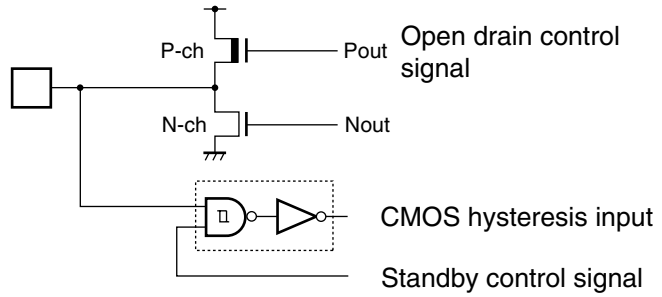
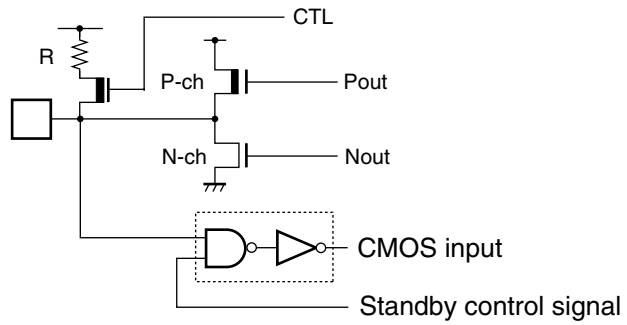
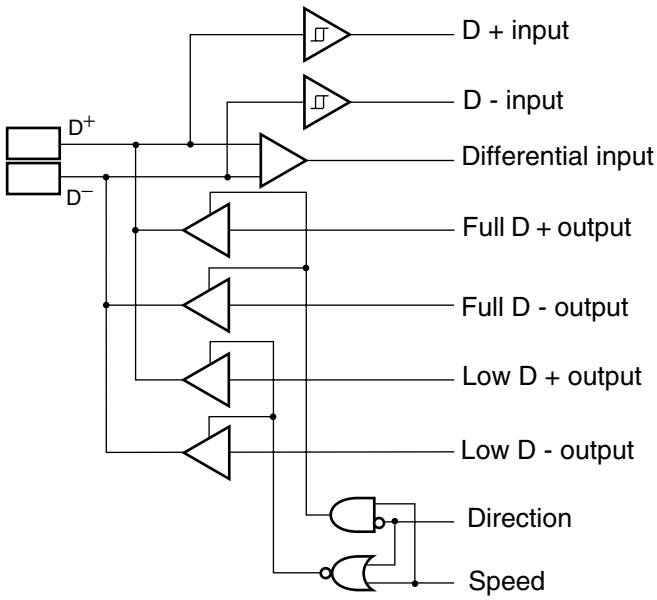
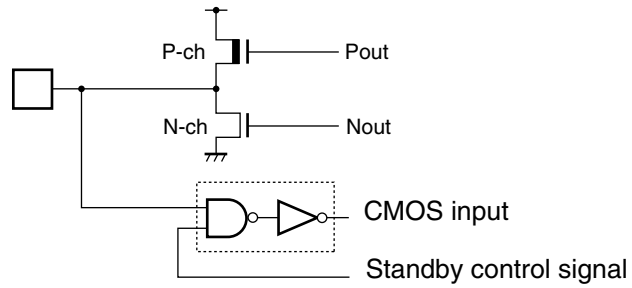
* : For circuit information, refer to “■ I/O CIRCUIT TYPE”.

■ I/O CIRCUIT TYPE

Type	Circuit	Remarks
A		• Oscillation feedback resistor of approx. 1 MΩ • With standby control
B		CMOS hysteresis input
C		• CMOS hysteresis input • N-ch open drain output
D		• CMOS output • CMOS hysteresis input (With input interception function at standby) Notes : • Share one output buffer because both output of I/O port and internal resource are used. • Share one input buffer because both input of I/O port and internal resource are used.
E		CMOS output
F		CMOS hysteresis input with pull-up resistor
G		• CMOS hysteresis input with pull-down resistor of approx. 50 kΩ • Flash product is not provided with pull-down resistor.

(Continued)

(Continued)

Type	Circuit	Remarks
H		• CMOS output • CMOS hysteresis input (With input interception function at standby) With open drain control signal
I		• CMOS output • CMOS input (With input interception function at standby) • Programmable input pull-up resistor
J		USB I/O pin
K		• CMOS output • CMOS input (With input interception function at standby)

■ HANDLING DEVICES

1. Preventing latch-up and turning on power supply

latch-up may occur on CMOS IC under the following conditions:

- If a voltage higher than V_{CC} or lower than V_{SS} is applied to input and output pins.
- A voltage higher than the rated voltage is applied between V_{CC} and V_{SS}.

When latch-up occurs, power supply current increases rapidly and might thermally damage elements. When using CMOS IC, take great care to prevent the occurrence of latch-up.

2. Treatment of unused pins

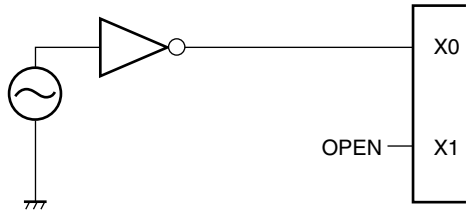
Leaving unused input pins unconnected can cause abnormal operation or latch-up, leading to permanent damage. Unused input pins should always be pulled up or down through resistance of at least 2 kΩ. Any unused input/output pins may be set to output mode and left open, or set to input mode and treated the same as unused input pins. If there is unused output pin, make it to open.

3. About the attention when the external clock is used

Even when using an external clock signal, an oscillation stabilization delay is applied after a power-on reset or when recovering from sub-clock or stop mode. When suing an external clock, 25 MHz should be the upper frequency limit.

The following figure shows a sample use of external clock signals.

- Using external clock



4. Treatment of power supply pins (V_{CC}/V_{SS})

In products with multiple V_{CC} or V_{SS} pins, the pins of the same potential are internally connected in the device to avoid abnormal operations including latch-up. However, you must connect the pins to external power supply and a ground line to lower the electro-magnetic emission level, to prevent abnormal operation of strobe signals caused by the rise in the ground level, and to conform to the total output current rating.

Moreover, connect the current supply source with the V_{CC} and V_{SS} pins of this device at the low impedance.

It is also advisable to connect a ceramic bypass capacitor of approximately 0.1 µF between V_{CC} and V_{SS} pins near this device.

5. About crystal oscillator circuit

Noise near the X0 and X1 pins may cause the device to malfunction. Design the printed circuit board so that X0, X1, the crystal oscillator (or ceramic oscillator) , and the bypass capacitor to ground are located as close to the device as possible.

It is strongly recommended to design the PC board artwork with the X0 and X1 pins surrounded by ground plane because stable operation can be expected with such a layout.

Please ask the crystal maker to evaluate the oscillational characteristics of the crystal and this device.

6. Caution on Operations during PLL Clock Mode

On this microcontroller, if in case the crystal oscillator breaks off or an external reference clock input stops while the PLL clock mode is selected, a self-oscillator circuit contained in the PLL may continue its operation at its self-running frequency. However, Fujitsu will not guarantee results of operations if such failure occurs.

7. Stabilization of supply voltage

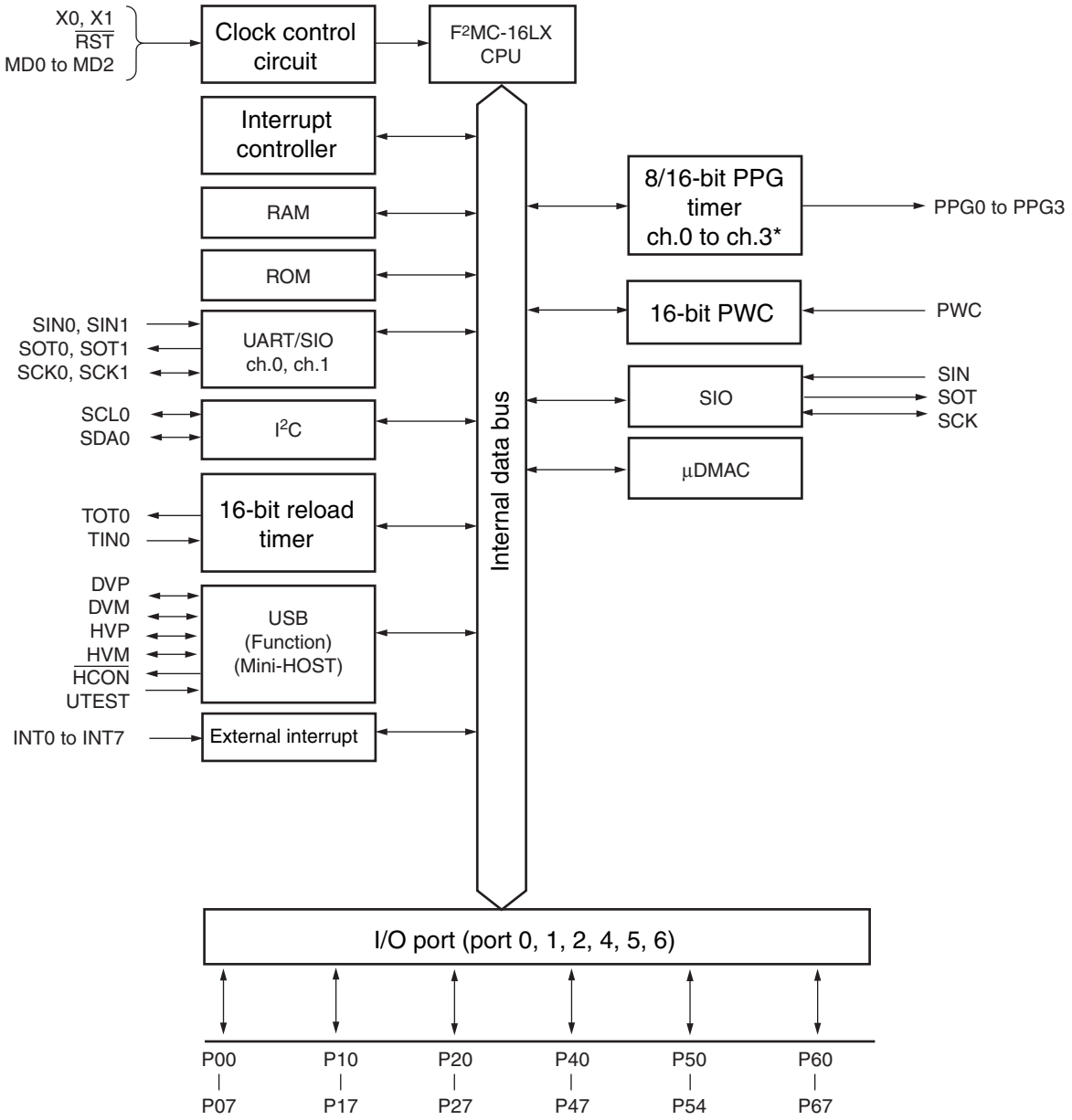
A sudden change in the supply voltage may cause the device to malfunction even within the V_{CC} supply voltage operating range. For stabilization reference, the supply voltage should be stabilized so that V_{CC} ripple variations (peak-to-peak value) at commercial frequencies (50 MHz to 60 MHz) fall below 10% of the standard V_{CC} supply voltage and the transient regulation does not exceed 0.1 V/ms at temporary changes such as power supply switching.

8. Writing to flash memory

For serial writing to flash memory, always make sure that the operating voltage V_{CC} is between 3.13 V and 3.6 V.

For normal writing to flash memory, always make sure that the operating voltage V_{CC} is between 3.0 V and 3.6 V.

■ BLOCK DIAGRAM

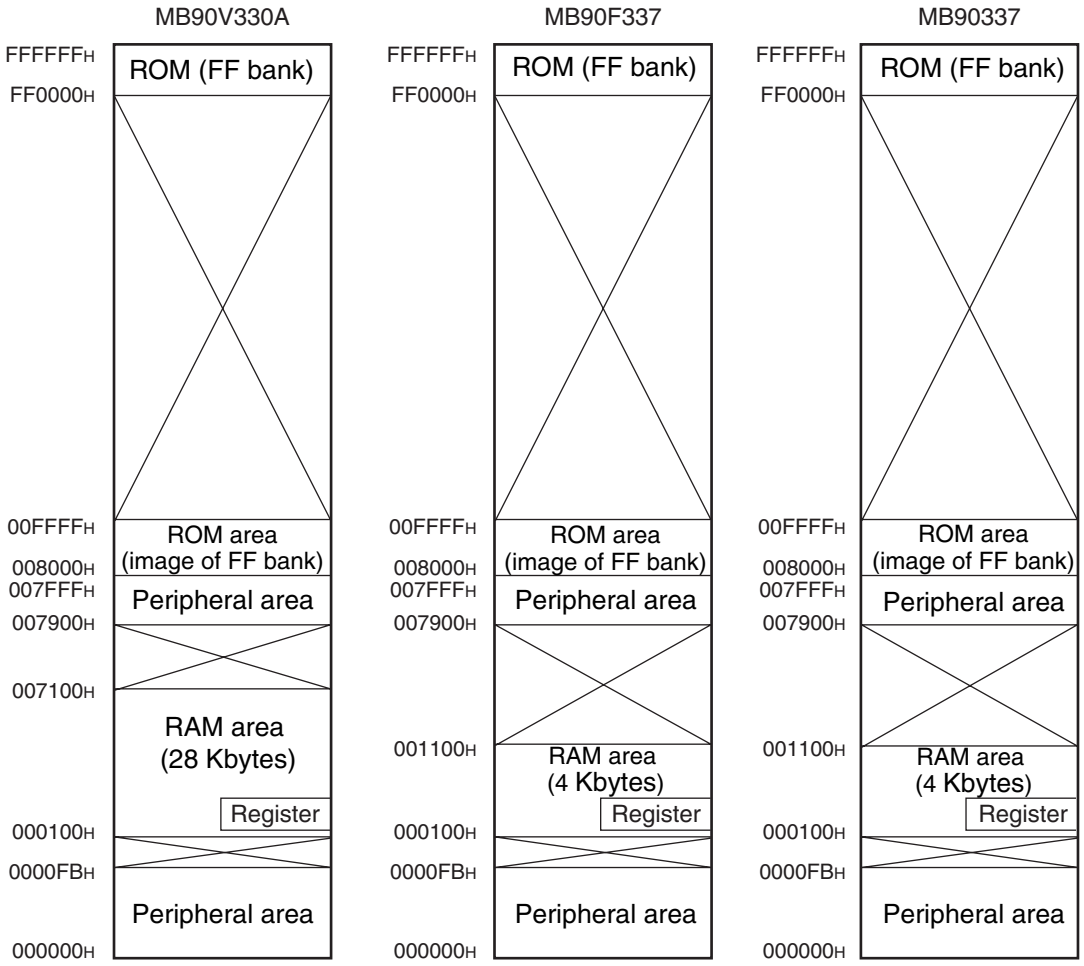


* : Channel for use in 8-bit mode. 2 channels (ch.1, ch.3) are used in 16-bit mode.

Note : I/O ports share pins with peripheral function (resources) .
For details, refer to “■ PIN ASSIGNMENT” and “■ PIN DESCRIPTION”.
Note also that pins used for peripheral function (resources) cannot serve as I/O ports.

■ MEMORY MAP

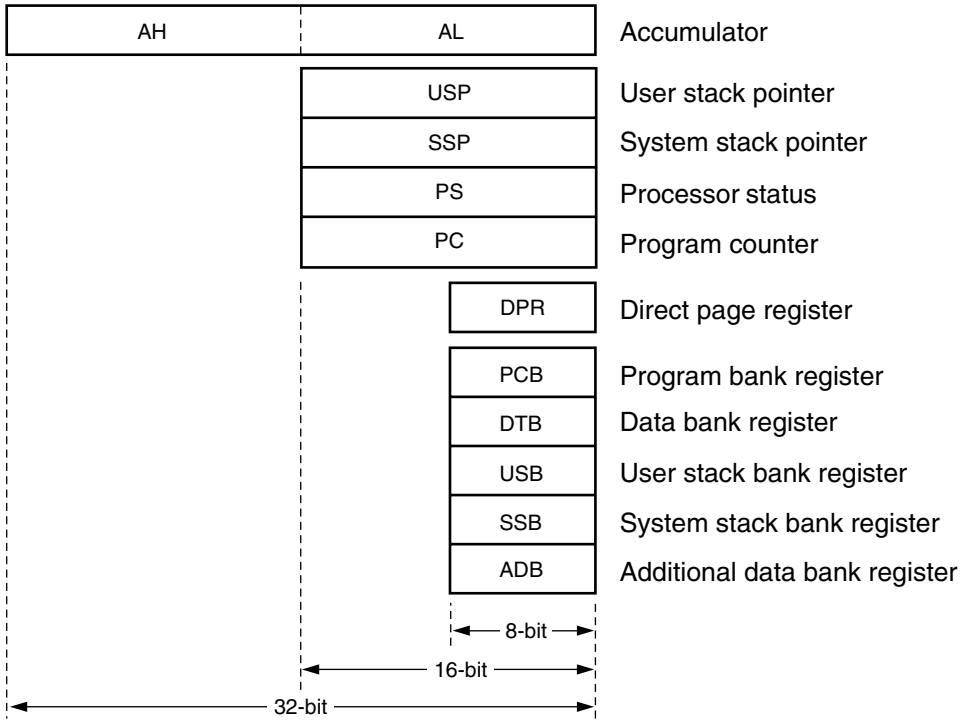
Single chip mode (with ROM mirror function)



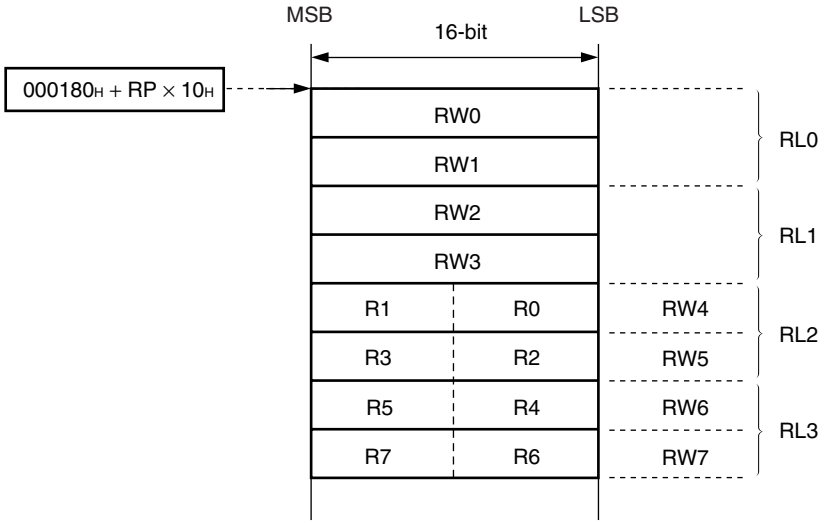
Notes :
- When the ROM mirror function register has been set, the mirror image data at upper addresses ("FF8000H to FFFFFFH") of bank FF is visible from the upper addresses ("008000H to 00FFFFH") of bank 00.
- The ROM mirror function is effective for using the C compiler small model.
- The lower 16-bit addresses of bank FF are equivalent to those of bank 00. Since the ROM area in bank FF exceeds 48 Kbytes, however, the mirror image of all the data in the ROM area cannot be reproduced in bank 00.
- When the C compiler small model is used, the data table mirror image can be shown at "008000H to 00FFFFH" by storing the data table at "FF8000H to FFFFFFH".
  Therefore, data tables in the ROM area can be referred without declaring the far addressing with the pointer.

■ F²MC-16L CPU PROGRAMMING MODEL

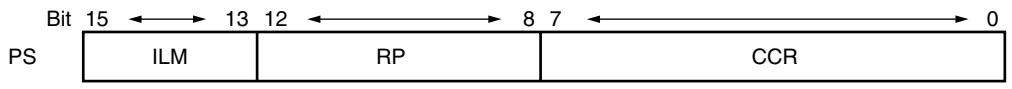
• Dedicated register



• General purpose registers



• Processor status



■ I/O MAP

Address	Register abbreviation	Register	Read/ Write	Resource name	Initial Value
000000H	PDR0	Port 0 Data Register	R/W	Port 0	XXXXXXXXB
000001H	PDR1	Port 1 Data Register	R/W	Port 1	XXXXXXXXB
000002H	PDR2	Port 2 Data Register	R/W	Port 2	XXXXXXXXB
000003H	Prohibited				
000004H	PDR4	Port 4 Data Register	R/W	Port 4	XXXXXXXXB
000005H	PDR5	Port 5 Data Register	R/W	Port 5	- - - XXXXXB
000006H	PDR6	Port 6 Data Register	R/W	Port 6	XXXXXXXXB
000007H to 00000FH	Prohibited				
000010H	DDR0	Port 0 Direction Register	R/W	Port 0	0 0 0 0 0 0 0 0B
000011H	DDR1	Port 1 Direction Register	R/W	Port 1	0 0 0 0 0 0 0 0B
000012H	DDR2	Port 2 Direction Register	R/W	Port 2	0 0 0 0 0 0 0 0B
000013H	Prohibited				
000014H	DDR4	Port 4 Direction Register	R/W	Port 4	0 0 0 0 0 0 0 0B
000015H	DDR5	Port 5 Direction Register	R/W	Port 5	- - - 0 0 0 0 0B
000016H	DDR6	Port 6 Direction Register	R/W	Port 6	0 0 0 0 0 0 0 0B
000017H to 00001AH	Prohibited				
00001BH	ODR4	Port 4 Output Pin Register	R/W	Port 4 (Open-drain control)	0 0 0 0 0 0 0 0B
00001CH	RDR0	Port 0 Pull-up Resistance Register	R/W	Port 0 (PULL-UP)	0 0 0 0 0 0 0 0B
00001DH	RDR1	Port 1 Pull-up Resistance Register	R/W	Port 1 (PULL-UP)	0 0 0 0 0 0 0 0B
00001EH	Prohibited				
00001FH					
000020H	SMR0	Serial Mode Register 0	R/W	UART0	0 0 1 0 0 0 0 0B
000021H	SCR0	Serial Control Register 0	R/W		0 0 0 0 0 1 0 0B
000022H	SIDR0	Serial Input Data Register 0	R		XXXXXXXXB
	SODR0	Serial Output Data Register 0	W		
000023H	SSR0	Serial Status Register 0	R/W		0 0 0 0 1 0 0 0B
000024H	UTRLR0	UART Prescaler Reload Register 0	R/W	Communication Prescaler (UART0)	0 0 0 0 0 0 0 0B
000025H	UTCR0	UART Prescaler Control Register 0	R/W		0 0 0 0 - 0 0 0B
000026H	SMR1	Serial Mode Register 1	R/W	UART1	0 0 1 0 0 0 0 0B
000027H	SCR1	Serial Control Register 1	R/W		0 0 0 0 0 1 0 0B
000028H	SIDR1	Serial Input Data Register 1	R		XXXXXXXXB
	SODR1	Serial Output Data Register 1	W		
000029H	SSR1	Serial Status Register 1	R/W		0 0 0 0 1 0 0 0B

(Continued)

Address	Register abbreviation	Register	Read/ Write	Resource name	Initial Value
00002A$_H$	UTRLR1	UART Prescaler Reload Register 1	R/W	Communication Prescaler (UART1)	0 0 0 0 0 0 0 0$_B$
00002B$_H$	UTCR1	UART Prescaler Control Register 1	R/W		0 0 0 0 - 0 0 0$_B$
00002C$_H$ to 00003B$_H$	Prohibited				
00003C$_H$	ENIR	DTP/Interrupt Enable Register	R/W	DTP/External interrupt	0 0 0 0 0 0 0 0$_B$
00003D$_H$	EIRR	DTP/Interrupt source Register	R/W		0 0 0 0 0 0 0 0$_B$
00003E$_H$	ELVR	Request Level Setting Register Lower	R/W		0 0 0 0 0 0 0 0$_B$
00003F$_H$		Request Level Setting Register Upper	R/W		0 0 0 0 0 0 0 0$_B$
000040$_H$ to 000045$_H$	Prohibited				
000046$_H$	PPGC0	PPG0 Operation Mode Control Register	R/W	PPG ch.0	0X0 0 0XX1$_B$
000047$_H$	PPGC1	PPG1 Operation Mode Control Register	R/W	PPG ch.1	0X0 0 0 0 0 1$_B$
000048$_H$	PPGC2	PPG2 Operation Mode Control Register	R/W	PPG ch.2	0X0 0 0XX1$_B$
000049$_H$	PPGC3	PPG3 Operation Mode Control Register	R/W	PPG ch.3	0X0 0 0 0 0 1$_B$
00004A$_H$	Prohibited				
00004B$_H$					
00004C$_H$	PPG01	PPG0 and PPG1 Output Control Register	R/W	PPG ch.0/ch.1	0 0 0 0 0 0XX$_B$
00004D$_H$	Prohibited				
00004E$_H$	PPG23	PPG2 and PPG3 Output Control Register	R/W	PPG ch.2/ch.3	0 0 0 0 0 0 XX$_B$
00004F$_H$ to 000057$_H$	Prohibited				
000058$_H$	SMCS	Serial Mode Control Status Register	R/W	Extended Serial I/O	XXXX0 0 0 0$_B$
000059$_H$					0 0 0 0 0 0 1 0$_B$
00005A$_H$	SDR	Serial Data Register	R/W		XXXXXXXX$_B$
00005B$_H$	SDCR	Communication Prescaler Control Register	R/W	Communication Prescaler	0XXX0 0 0 0$_B$
00005C$_H$	PWCSR	PWC Control Status Register	R/W	16-bit PWC Timer	0 0 0 0 0 0 0 0$_B$
00005D$_H$					0 0 0 0 0 0 0 X$_B$
00005E$_H$	PWCR	PWC Data Buffer Register	R/W		0 0 0 0 0 0 0 0$_B$
00005F$_H$					0 0 0 0 0 0 0 0$_B$
000060$_H$	DIVR	PWC Dividing Ratio Control Register	R/W		- - - - - - 0 0$_B$
000061$_H$	Prohibited				
000062$_H$	TMCSR0	Timer Control Status Register	R/W	16-bit Reload Timer	0 0 0 0 0 0 0 0$_B$
000063$_H$					XXXX 0 0 0 0$_B$
000064$_H$	TMR0	16-bit Timer Register Lower	R		XXXXXXXX$_B$
	TMRLR0	16-bit Reload Register Lower	W		XXXXXXXX$_B$
000065$_H$	TMR0	16-bit Timer Register Upper	R		XXXXXXXX$_B$
	TMRLR0	16-bit Reload Register Upper	W		XXXXXXXX$_B$

(Continued)

Address	Register abbreviation	Register	Read/ Write	Resource name	Initial Value
000066H to 00006EH	Prohibited				
00006FH	ROMM	ROM Mirroring Function Selection Register	W	ROM Mirror Function Selection Module	- - - - - - 1 1B
000070H	IBSR0	I²C Bus Status Register	R	I²C Bus Interface	0 0 0 0 0 0 0 0B
000071H	IBCR0	I²C Bus Control Register	R/W		0 0 0 0 0 0 0 0B
000072H	ICCR0	I²C Bus Clock Control Register	R/W		XX 0 XXXXXB
000073H	IADR0	I²C Bus Address Register	R/W		XXXXXXXXB
000074H	IDAR0	I²C Bus Data Register	R/W		XXXXXXXXB
000075H to 00009AH	Prohibited				
00009BH	DCSR	DMA Descriptor Channel Specification Register	R/W	µDMAC	0 0 0 0 0 0 0 0B
00009CH	DSRL	DMA Status Register Lower	R/W		0 0 0 0 0 0 0 0B
00009DH	DSRH	DMA Status Register Upper	R/W		0 0 0 0 0 0 0 0B
00009EH	PACSR	Program Address Detection Control Status Register	R/W	Address Match Detection	0 0 0 0 0 0 0 0B
00009FH	DIRR	Delayed Interrupt Source generate/ release Register	R/W	Delayed Interrupt	- - - - - - - 0B
0000A0H	LPMCR	Low Power Consumption Mode Control Register	R/W	Low Power Consumption control circuit	0 0 0 1 1 0 0 0B
0000A1H	CKSCR	Clock Selection Register	R/W	Clock	1 1 1 1 1 1 0 0B
0000A2H	Prohibited				
0000A3H					
0000A4H	DSSR	DMA Stop Status Register	R/W	µDMAC	0 0 0 0 0 0 0 0B
0000A5H to 0000A7H	Prohibited				
0000A8H	WDTC	Watchdog Timer Control Register	R/W	Watchdog Timer	X - XXX 1 1 1B
0000A9H	TBTC	Time-base Timer Control Register	R/W	Time-base Timer	1 - - 0 0 1 0 0B
0000AAH	Prohibited				
0000ABH					
0000ACH	DERL	DMA Enable Register Lower	R/W	µDMAC	0 0 0 0 0 0 0 0B
0000ADH	DERH	DMA Enable Register Upper	R/W		0 0 0 0 0 0 0 0B
0000AEH	FMCS	Flash Memory Control Status Register	R/W	Flash Memory I/F	0 0 0 X 0 0 0 0B
0000AFH	Prohibited				

(Continued)

Address	Register abbreviation	Register	Read/ Write	Resource name	Initial Value
0000B0H	ICR00	Interrupt Control Register 00	R/W	Interrupt Controller	0 0 0 0 0 1 1 1B
0000B1H	ICR01	Interrupt Control Register 01	R/W		0 0 0 0 0 1 1 1B
0000B2H	ICR02	Interrupt Control Register 02	R/W		0 0 0 0 0 1 1 1B
0000B3H	ICR03	Interrupt Control Register 03	R/W		0 0 0 0 0 1 1 1B
0000B4H	ICR04	Interrupt Control Register 04	R/W		0 0 0 0 0 1 1 1B
0000B5H	ICR05	Interrupt Control Register 05	R/W		0 0 0 0 0 1 1 1B
0000B6H	ICR06	Interrupt Control Register 06	R/W		0 0 0 0 0 1 1 1B
0000B7H	ICR07	Interrupt Control Register 07	R/W		0 0 0 0 0 1 1 1B
0000B8H	ICR08	Interrupt Control Register 08	R/W		0 0 0 0 0 1 1 1B
0000B9H	ICR09	Interrupt Control Register 09	R/W		0 0 0 0 0 1 1 1B
0000BAH	ICR10	Interrupt Control Register 10	R/W		0 0 0 0 0 1 1 1B
0000BBH	ICR11	Interrupt Control Register 11	R/W		0 0 0 0 0 1 1 1B
0000BCH	ICR12	Interrupt Control Register 12	R/W		0 0 0 0 0 1 1 1B
0000BDH	ICR13	Interrupt Control Register 13	R/W		0 0 0 0 0 1 1 1B
0000BEH	ICR14	Interrupt Control Register 14	R/W		0 0 0 0 0 1 1 1B
0000BFH	ICR15	Interrupt Control Register 15	R/W		0 0 0 0 0 1 1 1B
0000C0H	HCNT0	Host Control Register 0	R/W	USB Mini-HOST	0 0 0 0 0 0 0 0B
0000C1H	HCNT1	Host Control Register 1	R/W		0 0 0 0 0 0 0 1B
0000C2H	HIRQ	Host Interruption Register	R/W		0 0 0 0 0 0 0 0B
0000C3H	HERR	Host Error Status Register	R/W		0 0 0 0 0 0 1 1B
0000C4H	HSTATE	Host State Status Register	R/W		XX 0 1 0 0 1 0B
0000C5H	HFCOMP	SOF Interrupt FRAME Compare Register	R/W		0 0 0 0 0 0 0 0B
0000C6H	HRTIMER	Retry Timer Setting Register	R/W		0 0 0 0 0 0 0 0B
0000C7H			R/W		0 0 0 0 0 0 0 0B
0000C8H			R/W		XXXXXX 0 0B
0000C9H	HADR	Host Address Register	R/W		X 0 0 0 0 0 0 0B
0000CAH	HEOF	EOF Setting Register	R/W		0 0 0 0 0 0 0 0B
0000CBH			R/W		XX 0 0 0 0 0 0B
0000CCH	HFRAME	FRAME Setting Register	R/W		0 0 0 0 0 0 0 0B
0000CDH			R/W		XXXXX 0 0 0B
0000CEH	HTOKEN	Host Token End Point Register	R/W		0 0 0 0 0 0 0 0B
0000CFH	Prohibited				
0000D0H	UDCC	UDC Control Register	R/W	USB Function	1 0 1 0 0 0 0 0B
0000D1H			R/W		0 0 0 0 0 0 0 0B

(Continued)

Address	Register abbreviation	Register	Read/ Write	Resource name	Initial Value
0000D2H	EP0C	EP0 Control Register	R/W	USB Function	0 1 0 0 0 0 0 0B
0000D3H			R/W		XXXX 0 0 0 0B
0000D4H	EP1C	EP1 Control Register	R/W		0 0 0 0 0 0 0 0B
0000D5H			R/W		0 1 1 0 0 0 0 1B
0000D6H	EP2C	EP2 Control Register	R/W		0 1 0 0 0 0 0 0B
0000D7H			R/W		0 1 1 0 0 0 0 0B
0000D8H	EP3C	EP3 Control Register	R/W		0 1 0 0 0 0 0 0B
0000D9H			R/W		0 1 1 0 0 0 0 0B
0000DAH	EP4C	EP4 Control Register	R/W		0 1 0 0 0 0 0 0B
0000DBH			R/W		0 1 1 0 0 0 0 0B
0000DCH	EP5C	EP5 Control Register	R/W		0 1 0 0 0 0 0 0B
0000DDH			R/W		0 1 1 0 0 0 0 0B
0000DEH	TMSP	Time Stamp Register	R		0 0 0 0 0 0 0 0B
0000DFH			R		XXXXX0 0 0B
0000E0H	UDCS	UDC Status Register	R/W		XX0 0 0 0 0 0B
0000E1H	UDCIE	UDC Interrupt Enable Register	R/W		0 0 0 0 0 0 0 0B
0000E2H	EP0IS	EP0I Status Register	R/W		XXXXXXXXB
0000E3H			R/W		1 0 XXX 1 XXB
0000E4H	EP0OS	EP0O Status Register	R/W, R		0 XXXXXXXB
0000E5H			R/W		1 0 0 XX 0 0 0B
0000E6H	EP1S	EP1 Status Register	R		XXXXXXXXB
0000E7H			R/W		1 0 0 0 0 0 0 XB
0000E8H	EP2S	EP2 Status Register	R		XXXXXXXXB
0000E9H			R/W		1 0 0 0 0 0 0 0B
0000EAH	EP3S	EP3 Status Register	R		XXXXXXXXB
0000EBH			R/W		1 0 0 0 0 0 0 0B
0000ECH	EP4S	EP4 Status Register	R		XXXXXXXXB
0000EDH			R/W		1 0 0 0 0 0 0 0B
0000EEH	EP5S	EP5 Status Register	R		XXXXXXXXB
0000EFH			R/W		1 0 0 0 0 0 0 0B
0000F0H	EP0DT	EP0 Data Register	R/W		XXXXXXXXB
0000F1H			R/W		XXXXXXXXB
0000F2H	EP1DT	EP1 Data Register	R/W		XXXXXXXXB
0000F3H			R/W		XXXXXXXXB
0000F4H	EP2DT	EP2 Data Register	R/W		XXXXXXXXB
0000F5H			R/W		XXXXXXXXB
0000F6H	EP3DT	EP3 Data Register	R/W		XXXXXXXXB
0000F7H			R/W		XXXXXXXXB
0000F8H	EP4DT	EP4 Data Register	R/W		XXXXXXXXB
0000F9H			R/W		XXXXXXXXB

(Continued)

Address	Register abbreviation	Register	Read/ Write	Resource name	Initial Value
0000FA$_H$	EP5DT	EP5 Data Register	R/W	USB Function	XXXXXXXX$_B$
0000FB$_H$			R/W		XXXXXXXX$_B$
0000FC$_H$ to 0000FF$_H$	Prohibited				
000100$_H$ to 001100$_H$	RAM Area				
001FF0$_H$	PADR0	Program Address Detection Register ch.0 Lower	R/W	Address Match Detection	XXXXXXXX$_B$
001FF1$_H$		Program Address Detection Register ch.0 Middle	R/W		XXXXXXXX$_B$
001FF2$_H$		Program Address Detection Register ch.0 Upper	R/W		XXXXXXXX$_B$
001FF3$_H$	PADR1	Program Address Detection Register ch.1 Lower	R/W		XXXXXXXX$_B$
001FF4$_H$		Program Address Detection Register ch.1 Middle	R/W		XXXXXXXX$_B$
001FF5$_H$		Program Address Detection Register ch.1 Upper	R/W		XXXXXXXX$_B$
007900$_H$	PRLL0	PPG Reload Register Lower ch.0	R/W	PPG ch.0	XXXXXXXX$_B$
007901$_H$	PRLH0	PPG Reload Register Upper ch.0	R/W		XXXXXXXX$_B$
007902$_H$	PRLL1	PPG Reload Register Lower ch.1	R/W	PPG ch.1	XXXXXXXX$_B$
007903$_H$	PRLH1	PPG Reload Register Upper ch.1	R/W		XXXXXXXX$_B$
007904$_H$	PRLL2	PPG Reload Register Lower ch.2	R/W	PPG ch.2	XXXXXXXX$_B$
007905$_H$	PRLH2	PPG Reload Register Upper ch.2	R/W		XXXXXXXX$_B$
007906$_H$	PRLL3	PPG Reload Register Lower ch.3	R/W	PPG ch.3	XXXXXXXX$_B$
007907$_H$	PRLH3	PPG Reload Register Upper ch.3	R/W		XXXXXXXX$_B$
007908$_H$ to 00790B$_H$	Prohibited				
00790C$_H$	FWR0	Flash Memory Program Control Register 0	R/W	Flash	0 0 0 0 0 0 0 0$_B$
00790D$_H$	FWR1	Flash Memory Program Control Register 1	R/W	Flash	0 0 0 0 0 0 0 0$_B$
00790E$_H$	SSR0	Sector Conversion Setting Register	R/W	Flash	0 0 XXXXX0$_B$
00790F$_H$ to 00791F$_H$	Prohibited				

(Continued)

(Continued)

Address	Register abbreviation	Register	Read/ Write	Resource name	Initial Value
007920H	DBAPL	DMA Buffer Address Pointer Lower 8-bit	R/W	μDMAC	XXXXXXXXB
007921H	DBAPM	DMA Buffer Address Pointer Middle 8-bit	R/W		XXXXXXXXB
007922H	DBAPH	DMA Buffer Address Pointer Upper 8-bit	R/W		XXXXXXXXB
007923H	DMACS	DMA Control Register	R/W		XXXXXXXXB
007924H	DIOAL	DMA I/O Register Address Pointer Lower 8-bit	R/W		XXXXXXXXB
007925H	DIOAH	DMA I/O Register Address Pointer Upper 8-bit	R/W		XXXXXXXXB
007926H	DDCTL	DMA Data Counter Lower 8-bit	R/W		XXXXXXXXB
007927H	DDCTH	DMA Data Counter Upper 8-bit	R/W		XXXXXXXXB
007928H to 007FFFH	Prohibited				

- Explanation on read/write
  R/W : Readable and Writable
  R : Read only
  W : Write only

- Explanation of initial values
  0 : Initial value is “0”.
  1 : Initial value is “1”.
  X : Initial value is undefined.
  - : Initial value is undefined (None).

Note : No I/O instruction can be used for registers located between 007900H and 007FFFH.

■ INTERRUPT SOURCES, INTERRUPT VECTORS, AND INTERRUPT CONTROL REGISTERS

Interrupt source	EI²OS support	µDMAC	Interrupt vector			Interrupt control register		Priority
			Number*1		Address	ICR	Address	
Reset	×	×	#08	08H	FFFFDCH	—	—	High
INT 9 instruction	×	×	#09	09H	FFFFD8H	—	—	
Exceptional treatment	×	×	#10	0AH	FFFFD4H	—	—	
USB Function1	×	0, 1	#11	0BH	FFFFD0H	ICR00	0000B0H	
USB Function2	×	2 to 6*2	#12	0CH	FFFFCCH			
USB Function3	×	×	#13	0DH	FFFFC8H	ICR01	0000B1H	
USB Function4	×	×	#14	0EH	FFFFC4H			
USB Mini-HOST1	×	×	#15	0FH	FFFFC0H	ICR02	0000B2H	
USB Mini-HOST2	×	×	#16	10H	FFFFBCH			
I²C ch.0	×	×	#17	11H	FFFFB8H	ICR03	0000B3H	
DTP/External interrupt ch.0/ch.1	○	×	#18	12H	FFFFB4H			
No	—	—	#19	13H	FFFFB0H	ICR04	0000B4H	
DTP/External interrupt ch.2/ch.3	○	×	#20	14H	FFFFACH			
No	—	—	#21	15H	FFFFA8H	ICR05	0000B5H	
DTP/External interrupt ch.4/ch.5	○	×	#22	16H	FFFFA4H			
PWC/Reload timer ch.0	△	14	#23	17H	FFFFA0H	ICR06	0000B6H	
DTP/External interrupt ch.6/ch.7	△	×	#24	18H	FFFF9CH			
No	—	—	#25	19H	FFFF98H	ICR07	0000B7H	
No	—	—	#26	1AH	FFFF94H			
No	—	—	#27	1BH	FFFF90H	ICR08	0000B8H	
No	—	—	#28	1CH	FFFF8CH			
No	—	—	#29	1DH	FFFF88H	ICR09	0000B9H	
PPG ch.0/ch.1	×	×	#30	1EH	FFFF84H			
No	—	—	#31	1FH	FFFF80H	ICR10	0000BAH	
PPG ch.2/ch.3	×	×	#32	20H	FFFF7CH			
No	—	—	#33	21H	FFFF78H	ICR11	0000BBH	
No	—	—	#34	22H	FFFF74H			
No	—	—	#35	23H	FFFF70H	ICR12	0000BCH	
No	—	—	#36	24H	FFFF6CH			
UART (Send completed) ch.0/ch.1	○	13	#37	25H	FFFF68H	ICR13	0000BDH	
Extended serial I/O	×	9	#38	26H	FFFF64H			
UART(Reception completed) ch.0/ch.1	◎	12	#39	27H	FFFF60H	ICR14	0000BEH	
Time-base timer	×	×	#40	28H	FFFF5CH			
Flash memory status	×	×	#41	29H	FFFF58H	ICR15	0000BFH	
Delay interrupt output module	×	×	#42	2AH	FFFF54H			Low

(Continued)

(Continued)

◎ : Available. EI²OS stop function provided (The interrupt request flag is cleared by the interrupt clear signal. With a stop request).
○ : Available (The interrupt request flag is cleared by the interrupt clear signal).
△ : Available when any interrupt source sharing ICR is not used.
× : Unavailable

*1 : If the same level interrupt is output simultaneously, the lower interrupt factor of interrupt vector number has priority.

*2 : Ch.2 and ch.3 can be used in Mini-HOST operation.

Notes :
- If the same interrupt control register (ICR) has two interrupt factors and the use of the EI²OS is permitted, the EI²OS is activated when either of the factors is detected. As any interrupt other than the activation factor is masked while the EI²OS is running, it is recommended that you should mask either of the interrupt requests when using the EI²OS.
- The interrupt flag is cleared by the EI²OS interrupt clear signal for the resource that has two interrupt factors in the same interrupt control register (ICR).
- If a resource has two interrupt sources for the same interrupt number, both of the interrupt request flags are cleared by the μDMAC interrupt clear signal. Therefore, when you use either of two interrupt factors for the DMAC function, another interrupt function is disabled. Set the interrupt request permission bit to " 0 " in the appropriate resource, and take measures by software polling.

■ Content of USB Interruption Factor

USB interrupt factor	Details
USB function 1	End Point0-IN, EndPoint 0-OUT
USB function 2	End Point 1-5 *
USB function 3	SUSP, SOF, BRST, WKOP, COHF
USB function 4	SPIT
USB Mini-HOST1	DIRQ, CHHIRQ, URIRQ, RWKIRQ
USB Mini-HOST2	SOFIRQ, CMPIRQ

* : End Point 1and 2 can be used in Mini-HOST operation.

■ PERIPHERAL RESOURCES

1. I/O port

The I/O ports are used as general-purpose input/output ports (parallel I/O ports). MB90335 series model is provided with 6 ports (45 inputs) . The ports function as input/output pins for peripheral functions also.

An I/O port, using port data register (PDR) , outputs the output data to I/O pin and input a signal input to I/O port. The port direction register (DDR) specifies direction of input/output of I/O pins on a bit-by-bit basis.

The following table lists the I/O ports and the peripheral functions with which they share pins.

	Port pin name	Pin Name (Peripheral)	Peripheral Function that Shares Pin
Port 0	P00 to P07	—	
Port 1	P10 to P17	—	
Port 2	P20 to P23	—	
	P24 to P27	PPG0 to PPG3	8/16-bit PPG timer 0, 1
Port 4	P40, P41	TIN0, TOT0	16-bit reload timer
	P42 to P47	SIN0, SOT0, SCK0, SIN1, SOT1, SCK1	UART0, 1
Port 5	P50 to P54	—	
Port 6	P60, P61	INT0, INT1	External interrupt
	P62 to P64	INT2 to INT4, SIN, SOT, SCK	External interrupt, serial I/O
	P65	INT5, PWC	External interrupt, PWC
	P66, P67	INT6, INT7, SCL0, SDA0	External interrupt, I^2C

• Register list (port data register)

	7	6	5	4	3	2	1	0	Initial Value	Access
PDR0 Address : 000000H	P07	P06	P05	P04	P03	P02	P01	P00	XXXXXXXXB	R/W*
PDR1 Address : 000001H	15	14	13	12	11	10	9	8	XXXXXXXXB	R/W*
	P17	P16	P15	P14	P13	P12	P11	P10		
PDR2 Address : 000002H	7	6	5	4	3	2	1	0	XXXXXXXXB	R/W*
	P27	P26	P25	P24	P23	P22	P21	P20		
PDR4 Address : 000004H	7	6	5	4	3	2	1	0	XXXXXXXXB	R/W*
	P47	P46	P45	P44	P43	P42	P41	P40		
PDR5 Address : 000005H	15	14	13	12	11	10	9	8	- - - XXXXXB	R/W*
	—	—	—	P54	P53	P52	P51	P50		
PDR6 Address : 000006H	7	6	5	4	3	2	1	0	XXXXXXXXB	R/W*
	P67	P66	P65	P64	P63	P62	P61	P60		

* : R/W access to I/O ports is a bit different in behavior from R/W access to memory as follows:

- Input mode

  Read : The level at the relevant pin is read.
  Write : Data is written to the output latch.

- Output mode

  Read : The data register latch value is read.
  Write : Data is output to the relevant pin.

• Register list (port direction register)

		7	6	5	4	3	2	1	0	Initial Value	Access
DDR0	Address : 000010H	D07	D06	D05	D04	D03	D02	D01	D 00	00000000B	R/W
		15	14	13	12	11	10	9	8		
DDR1	Address : 000011H	D17	D16	D15	D14	D13	D12	D11	D10	00000000B	R/W
		7	6	5	4	3	2	1	0		
DDR2	Address : 000012H	D27	D26	D25	D24	D23	D22	D21	D20	00000000B	R/W
		7	6	5	4	3	2	1	0		
DDR4	Address : 000014H	D47	D46	D45	D44	D43	D42	D41	D40	00000000B	R/W
		15	14	13	12	11	10	9	8		
DDR5	Address : 000015H	—	—	—	D54	D53	D52	D51	D50	- - - 00000B	R/W
		7	6	5	4	3	2	1	0		
DDR6	Address : 000016H	D67	D66	D65	D64	D63	D62	D61	D60	00000000B	R/W

- When each pin is serving as a port, the corresponding pin is controlled as follows:
  0 : Input mode
  1 : Output mode
  This bit becomes 0 after a reset.

Note : If these registers are accessed by a read modify write instruction (such as a bit set instruction) , the bits manipulated by the instruction are set to prescribed values but those other bits in output registers which have been set for input are rewritten to current input values of the pins. When switching a pin from input port to output port, therefore, write a desired value in the PDR first, then set the DDR to switch the pin for output.

• Register list (Port pull-up register)

		7	6	5	4	3	2	1	0	Initial Value	Access
RDR0	Address : 00001CH	RD07	RD06	RD05	RD04	RD03	RD02	RD01	RD00	00000000B	R/W
		15	14	13	12	11	10	9	8		
RDR1	Address : 00001DH	RD17	RD16	RD15	RD14	RD13	RD12	RD11	RD10	00000000B	R/W

Controls the pull-up resistor in input mode.

0 : Without pull-up resistor in input mode.

1 : With Pull-up resistor in input mode.

Meaningless in output mode (without pull-up resistor) ./ The input/output register is decided by the setting of the direction register (DDR) .

No pull-up resistor is used in stop mode (SPL = 1).

• Register list (output pin register)

ODR4

Address : 00001B$_H$

7	6	5	4	3	2	1	0	Initial Value	Access
OD47	OD46	OD45	OD44	OD43	OD42	OD41	OD40	00000000$_B$	R/W

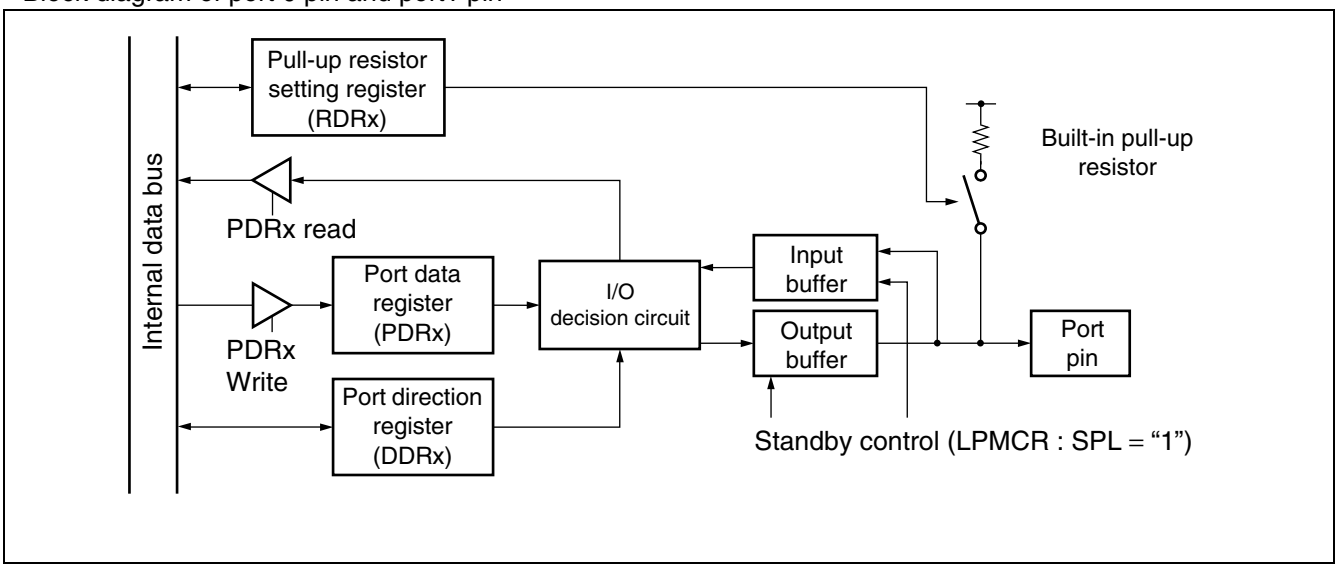
Controls open-drain output in output mode.

0 : Serves as a standard output port in output mode.

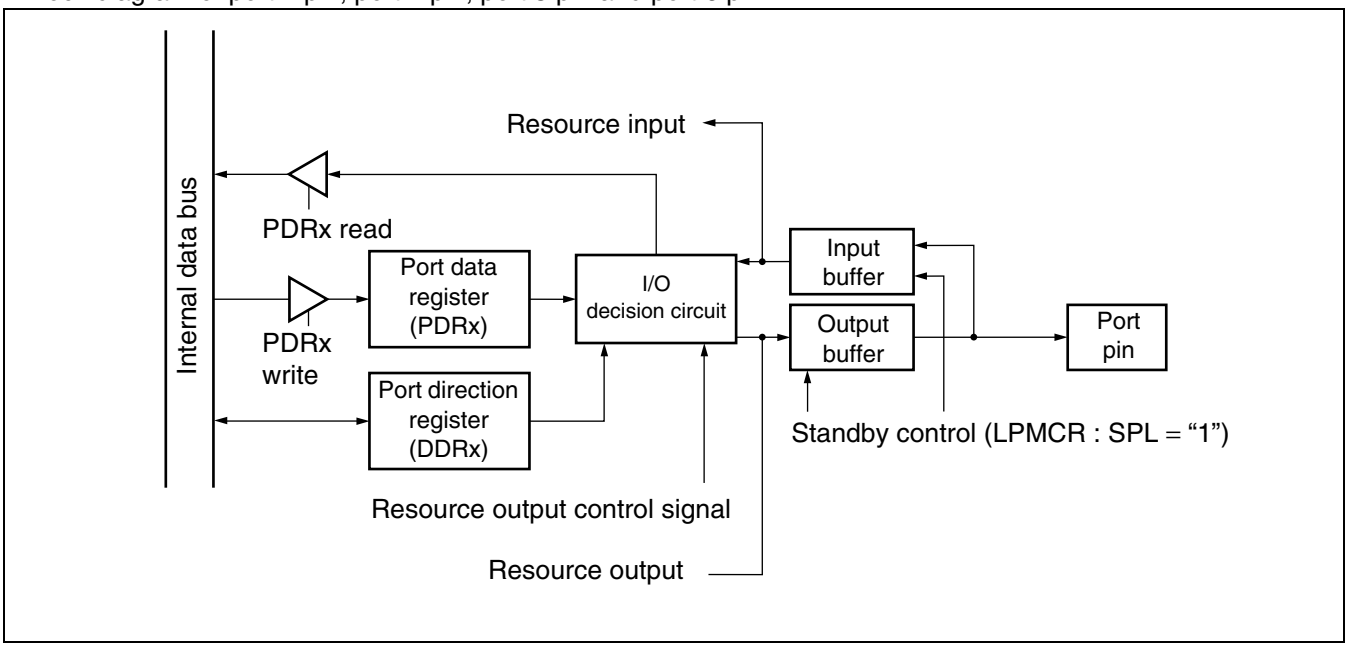
1 : Serves as an open-drain output port in output mode.

Meaningless in input mode. (output Hi-Z) / The input/output register is decided by the setting of the direction register (DDR) .

• Block diagram of port 0 pin and port1 pin



• Block diagram of port 2 pin, port 4 pin, port 5 pin and port 6 pin



2. Time-base timer

The time-base timer is an 18-bit free-running counter (time-base timer counter) that counts in synchronization with the main clock (2 cycles of the oscillation clock HCLK). Four different time intervals can be selected, for each of which an interrupt request can be generated. Operating clock signals are supplied to peripheral resources such as the oscillation stabilization wait timer and watchdog timer.

• Interval time of time-base timer

Internal count clock cycle	Interval time
2/HCLK (0.33 μs)	2^{12}/HCLK (Approx. 0.68 ms)
	2^{14}/HCLK (Approx. 2.7 ms)
	2^{16}/HCLK (Approx. 10.9 ms)
	2^{19}/HCLK (Approx. 87.4 ms)

Notes : • HCLK : Oscillation clock frequency
• The parenthesized values assume an oscillator clock frequency of 6 MHz.

• Clock cycles supplied from time-base timer

Where to supply clock	Clock cycle
Main clock oscillation stabilization wait	2^{13}/HCLK (Approx. 1.36 ms)
	2^{15}/HCLK (Approx. 5.46 ms)
	2^{17}/HCLK (Approx. 21.84 ms)
Watch dog timer	2^{12}/HCLK (Approx. 0.68 ms)
	2^{14}/HCLK (Approx. 2.7 ms)
	2^{16}/HCLK (Approx. 10.9 ms)
	2^{19}/HCLK (Approx. 87.4 ms)

Notes : • HCLK : Oscillation clock frequency
• The parenthesized values assume an oscillator clock frequency of 6 MHz.

• Register list

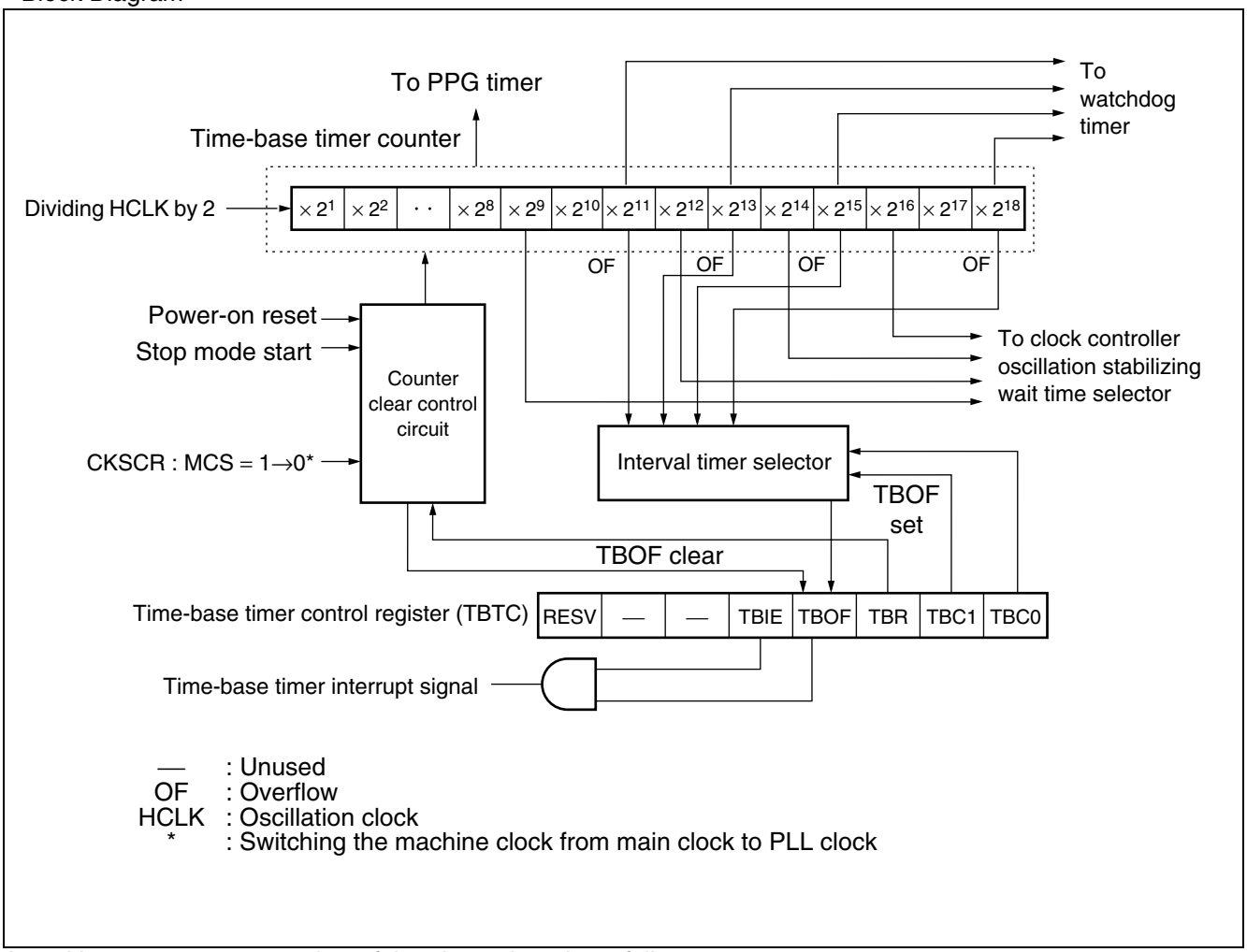
Time-base timer control register (TBTC)

Address : $0000A9_H$

15	14	13	12	11	10	9	8
RESV	—	—	TBIE	TBOF	TBR	TBC1	TBC0
(R/W)	(—)	(—)	(R/W)	(R/W)	(W)	(R/W)	(R/W)

Initial Value
$1\text{--}00100_B$

• Block Diagram



Actual interrupt request number of time-base timer is as follows:
Interrupt request number:#40 (28H)

3. Watchdog timer

The watchdog timer is timer counter provided for measure of program runaway. It is a 2-bit counter operating with an output of the timebase timer or watch timer as the count clock and resets the CPU when the counter is not cleared for a preset period of time after start.

• Interval time of watchdog timer

HCLK: Oscillation clock (6 MHz)		
Min	**Max**	**Clock cycle**
Approx. 2.39 ms	Approx. 3.07 ms	$2^{14} \pm 2^{11}$ / HCLK
Approx. 9.56 ms	Approx. 12.29 ms	$2^{16} \pm 2^{13}$ / HCLK
Approx. 38.23 ms	Approx. 49.15 ms	$2^{18} \pm 2^{15}$ / HCLK
Approx. 305.83 ms	Approx. 393.22 ms	$2^{21} \pm 2^{18}$ / HCLK

Notes :
- The maximum and minimum time intervals for the watchdog timer depend on the counter clear timing.
- The watchdog timer contains a 2-bit counter that counts the carry signals of the time-base timer.
- Interval time of watchdog timer is longer than the set time during the following conditions.
  - When clearing the timebase timer during operation on oscillation (HCLK)

• Event that stop the watchdog timer

- Stop due to a power-on reset
- Watchdog reset

• Clear factor of watchdog timer

- External reset input by $\overline{\text{RST}}$ pin
- Writing “0” to the software reset bit
- Writing “0” to the watchdog control bit (second and subsequent times)
- Transition to sleep mode (clearing the watchdog timer to suspend counting)
- Transition to time-base timer mode (clearing the watchdog timer to suspend counting)
- Transition to stop mode (clearing the watchdog timer to suspend counting)

• Register list

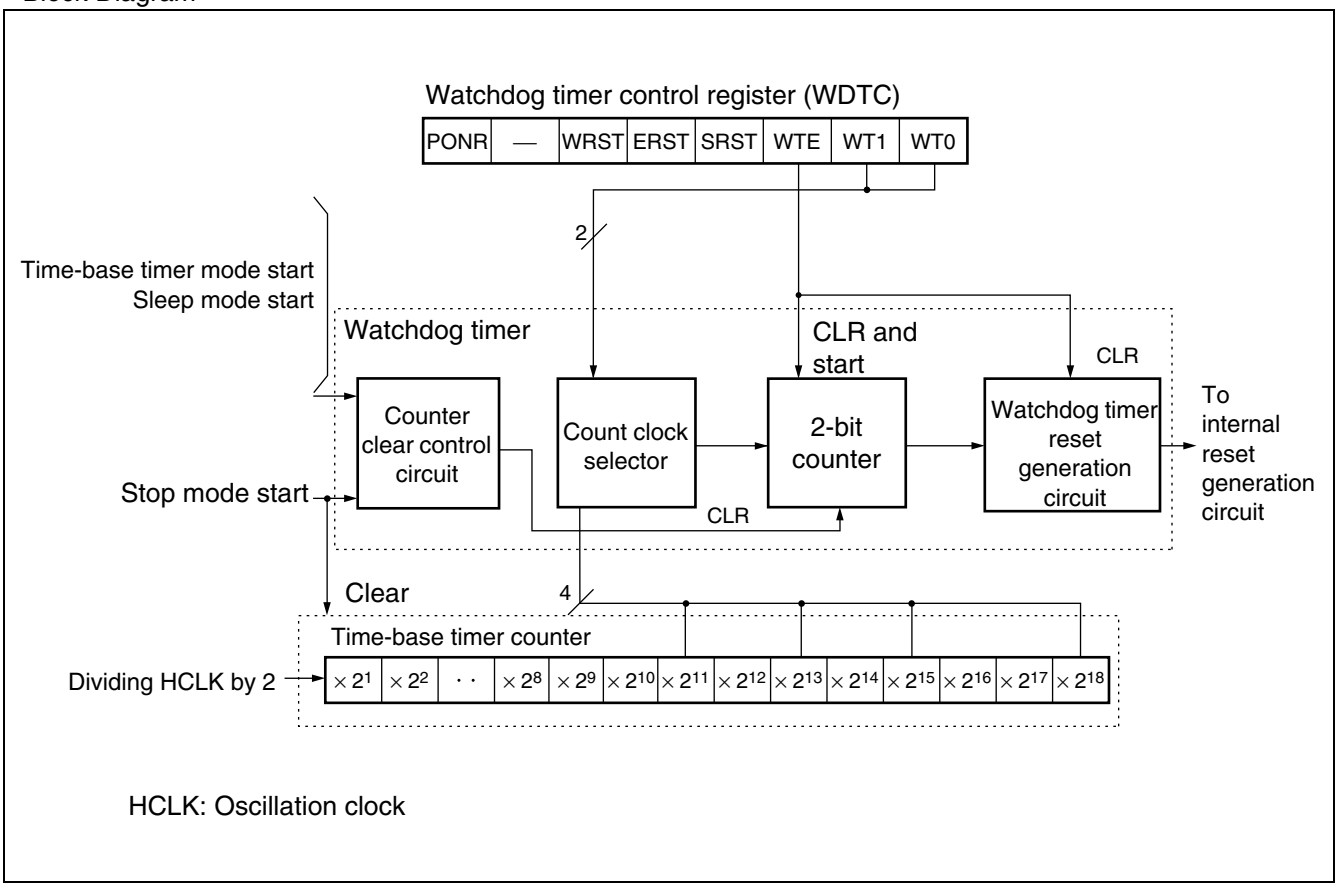
Watchdog timer control register (WDTC)

Address : 0000A8H

7	6	5	4	3	2	1	0
PONR	—	WRST	ERST	SRST	WTE	WT1	WT0
(R)	(—)	(R)	(R)	(R)	(W)	(W)	(W)

Initial Value
X-XXX111B

• Block Diagram



4. 16-bit reload timer

The 16-bit reload timer has the internal clock mode to be decrement in synchronization with 3 different internal clocks and the event count mode to decrement upon detection of an arbitrary edge of the pulse input to the external pin. Either can be selected. This timer defines when the count value changes from 0000_H to $FFFF_H$ as an underflow. The timer therefore causes an underflow when the count reaches [reload register setting +1]. Either mode can be selected for the count operation from the reload mode which repeats the count by reloading the count setting value at the underflow occurrence or the one-shot mode which stops the count at the underflow occurrence. The interrupt can be generated at the counter underflow occurrence so as to correspond to the DTC.

• Register list

• Timer control status register

Timer control status register (Upper) (TMCSR0)

Address : 000063_H

15	14	13	12	11	10	9	8
—	—	—	—	CSL1	CSL0	MOD2	MOD1
(—)	(—)	(—)	(—)	(R/W)	(R/W)	(R/W)	(R/W)

Initial Value $XXXX0000_B$

Timer control status register (Lower) (TMCSR0)

Address : 000062_H

7	6	5	4	3	2	1	0
MOD0	OUTE	OUTL	RELD	INTE	UF	CNTE	TRG
(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)

Initial Value 00000000_B

• 16-bit timer register/16-bit reload register

TMR0/TMRLR0 (Upper)

Address : 000065_H

15	14	13	12	11	10	9	8
D15	D14	D13	D12	D11	D10	D09	D08
(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)

Initial Value $XXXXXXXX_B$

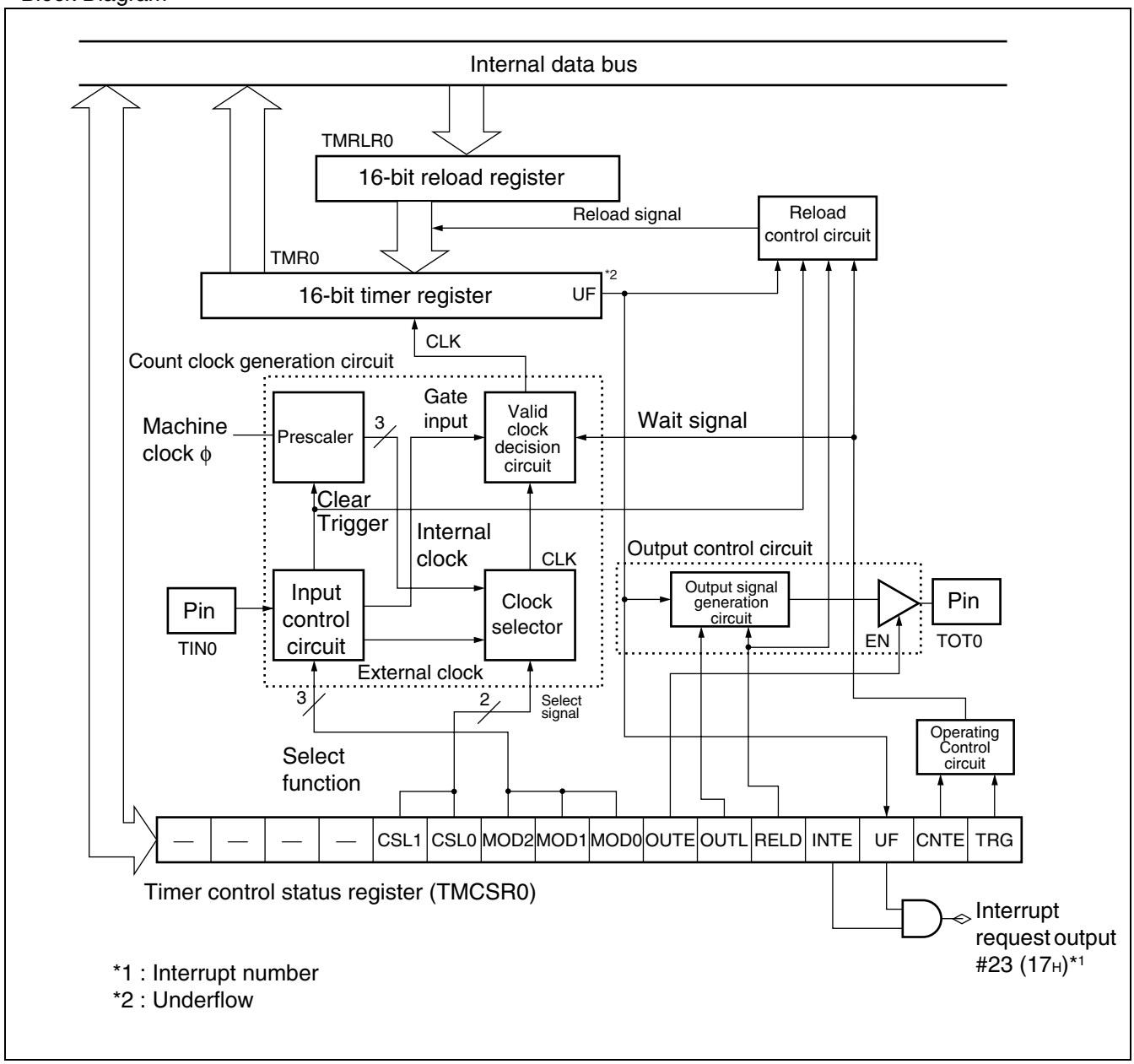
TMR0/TMRLR0 (Lower)

Address : 000064_H

7	6	5	4	3	2	1	0
D07	D06	D05	D04	D03	D02	D01	D00
(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)

Initial Value $XXXXXXXX_B$

• Block Diagram



5. Multifunction timer

The multifunction timer can be used for waveform output, input pulse width measurement, and external clock cycle measurement.

• Configuration of a multi-functional timer

8/16-bit PPG timer	16-bit PWC timer
8-bit × 4 channels (16-bit × 2 channels)	1 channel

• 8/16-bit PPG timer (8-bit : 4 channels, 16-bit : 2 channels)

8/16-bit PPG timer consists of a 8-bit down counter (PCNT) , PPG operation mode control register (PPGC0 to PPGC3) , PPG output control register (PPG01, PPG23) and PPG reload register (PRLL0 to PRLL3, PRLH0 to PRLH3) .

When used as an 8/16-bit reload timer, the PPG timer serves as an event timer. It can also output pulses of an arbitrary duty ratio at an arbitrary frequency.

- 8-bit PPG mode
  Each channel operates as an independent 8-bit PPG.
- 8-bit prescaler + 8-bit PPG mode
  Operates as an arbitrary-cycle 8-bit PPG with ch.0 (ch.2) operating as an 8-bit prescaler and ch.2 (ch.3) counted by the borrow output of ch.0 (ch.2).
- 16-bit PPG mode
  Operates as a 16-bit PPG with ch.0 (ch.2) and ch.1 (ch.3) connected.
- PPG Operation
  The PPG timer outputs pulses of an arbitrary duty ratio (the ratio between the High and Low level periods of pulse waveform) at an arbitrary frequency. Can also be used as a D/A converter by an external circuit.

• Register list

PPG operation mode control register
(PPGC1/PPGC3)

Address : 000047H, 000049H

15	14	13	12	11	10	9	8
PEN1	—	PE10	PIE1	PUF1	MD1	MD0	Reserved
(R/W)	(—)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)

Initial Value
0X000001B

(PPGC0/PPGC2)

Address : 000046H, 000048H

7	6	5	4	3	2	1	0
PEN0	—	PE0O	PIE0	PUF0	—	—	Reserved
(R/W)	(—)	(R/W)	(R/W)	(R/W)	(—)	(—)	(R/W)

Initial Value
0X000XX1B

PPG output control register (PPG01/PPG23)

Address : 00004CH, 00004EH

7	6	5	4	3	2	1	0
PCS2	PCS1	PCS0	PCM2	PCM1	PCM0	Reserved	Reserved
(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)

Initial Value
000000XXB

PPG reload register
(PRLH0 to PRLH3)

Address : 007901H, 007903H, 007905H, 007907H

15	14	13	12	11	10	9	8
D15	D14	D13	D12	D11	D10	D09	D08
(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)

Initial Value
XXXXXXXXB

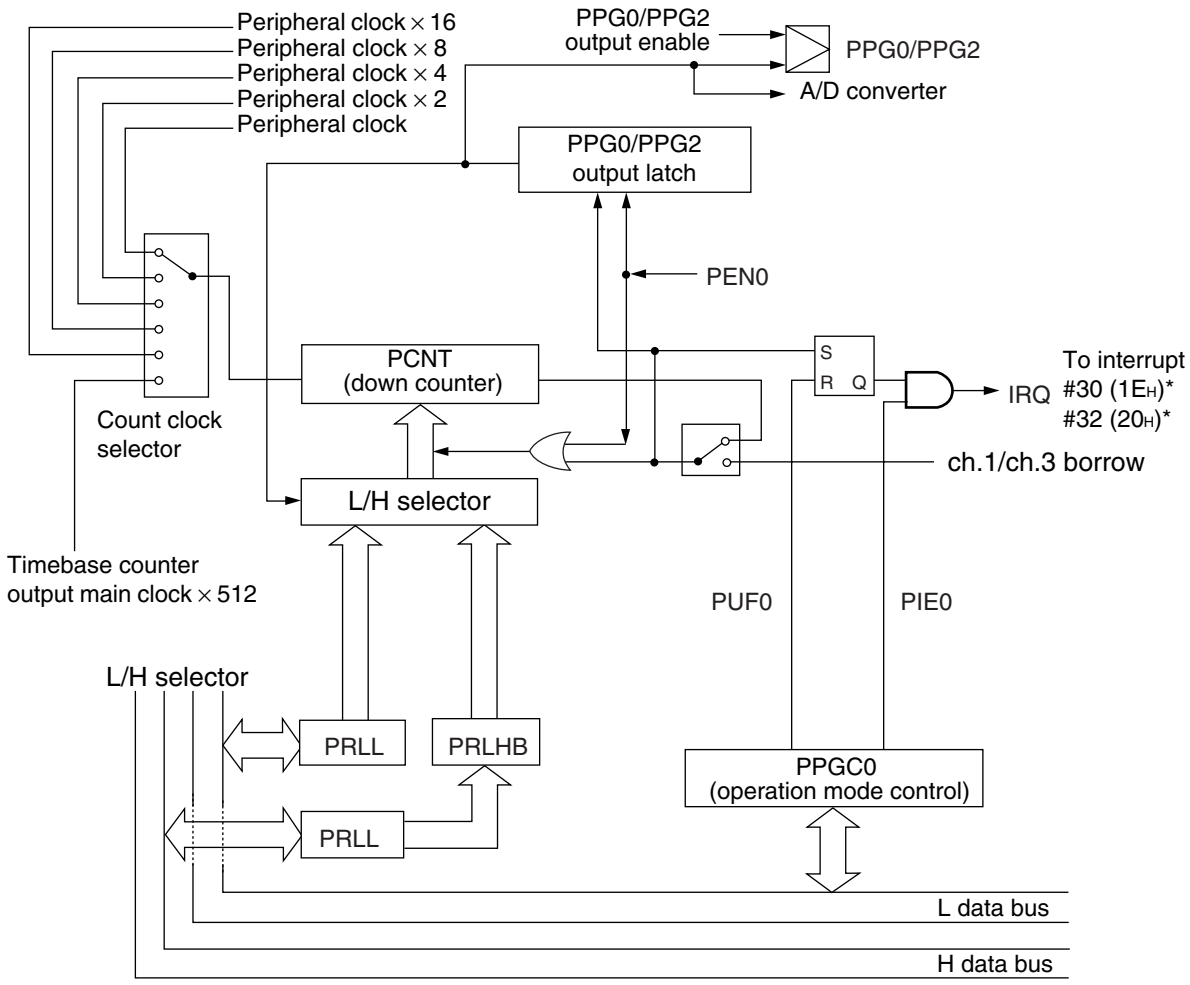
(PRLL0 to PRLL3)

Address : 007900H, 007902H, 007904H, 007906H

7	6	5	4	3	2	1	0
D07	D06	D05	D04	D03	D02	D01	D00
(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)

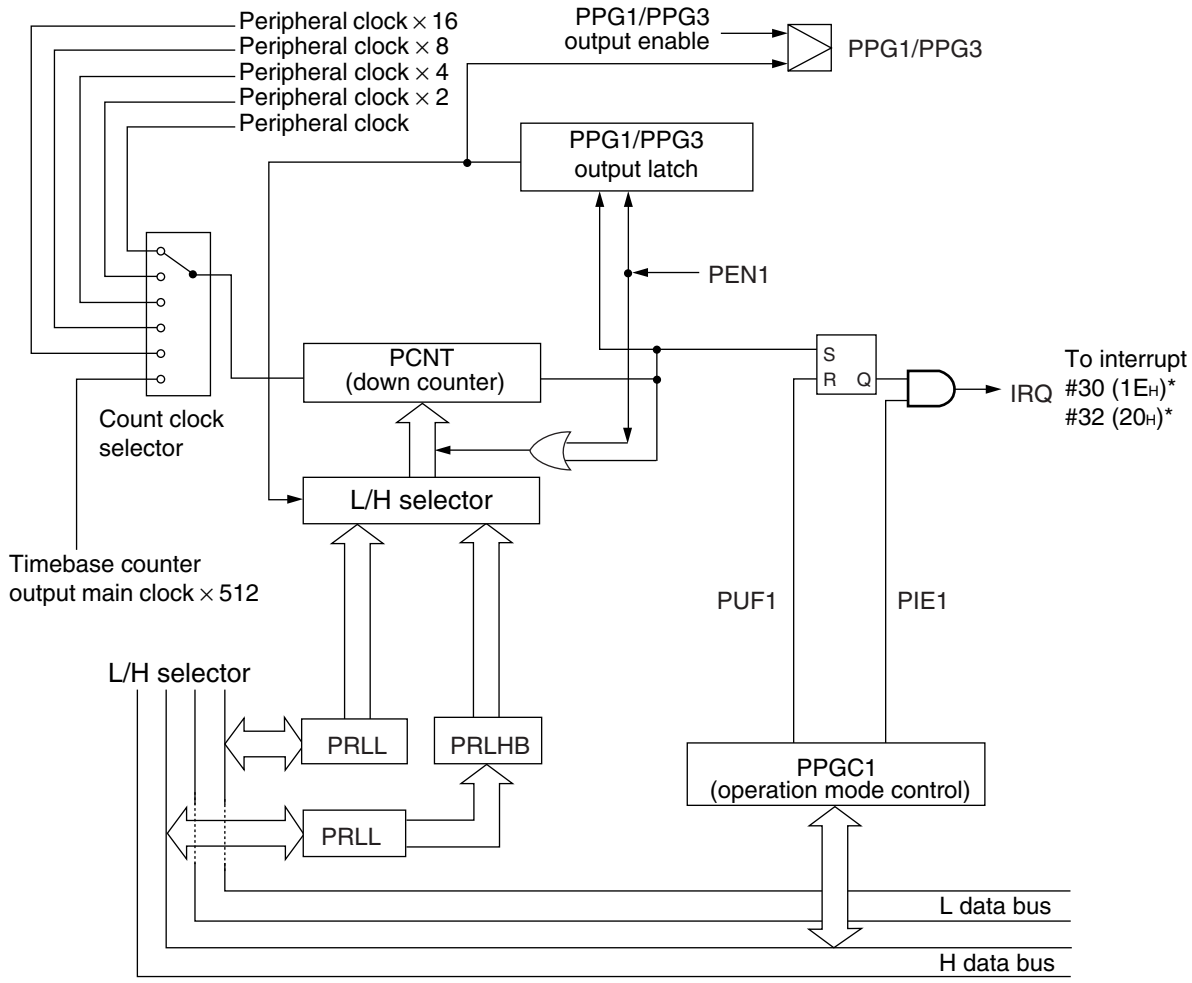
Initial Value
XXXXXXXXB

• 8/16-bit PPG ch.0/ch.2 block diagram



* : Interrupt number

• 8/16-bit PPG ch.1/ch.3 block diagram



* : Interrupt number

• PWC timer

The PWC timer is a 16-bit multi-function up-count timer capable of measuring the input signal pulse width.

• Register list

PWC control status register (PWCSR)

Address : 00005D$_H$

15	14	13	12	11	10	9	8
STRT	STOP	EDIR	EDIE	OVIR	OVIE	ERR	Reserved
(R/W)	(R/W)	(R)	(R/W)	(R/W)	(R/W)	(R)	(R/W)

Initial Value
0000000X$_B$

Address : 00005C$_H$

7	6	5	4	3	2	1	0
CKS1	CKS0	PIS1	PIS0	S/C	MOD2	MOD1	MOD0
(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)

Initial Value
00000000$_B$

PWC data buffer register (PWCR)

Address : 00005F$_H$

15	14	13	12	11	10	9	8
D15	D14	D13	D12	D11	D10	D9	D8
(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)

Initial Value
00000000$_B$

Address : 00005E$_H$

7	6	5	4	3	2	1	0
D7	D6	D5	D4	D3	D2	D1	D0
(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)

Initial Value
00000000$_B$

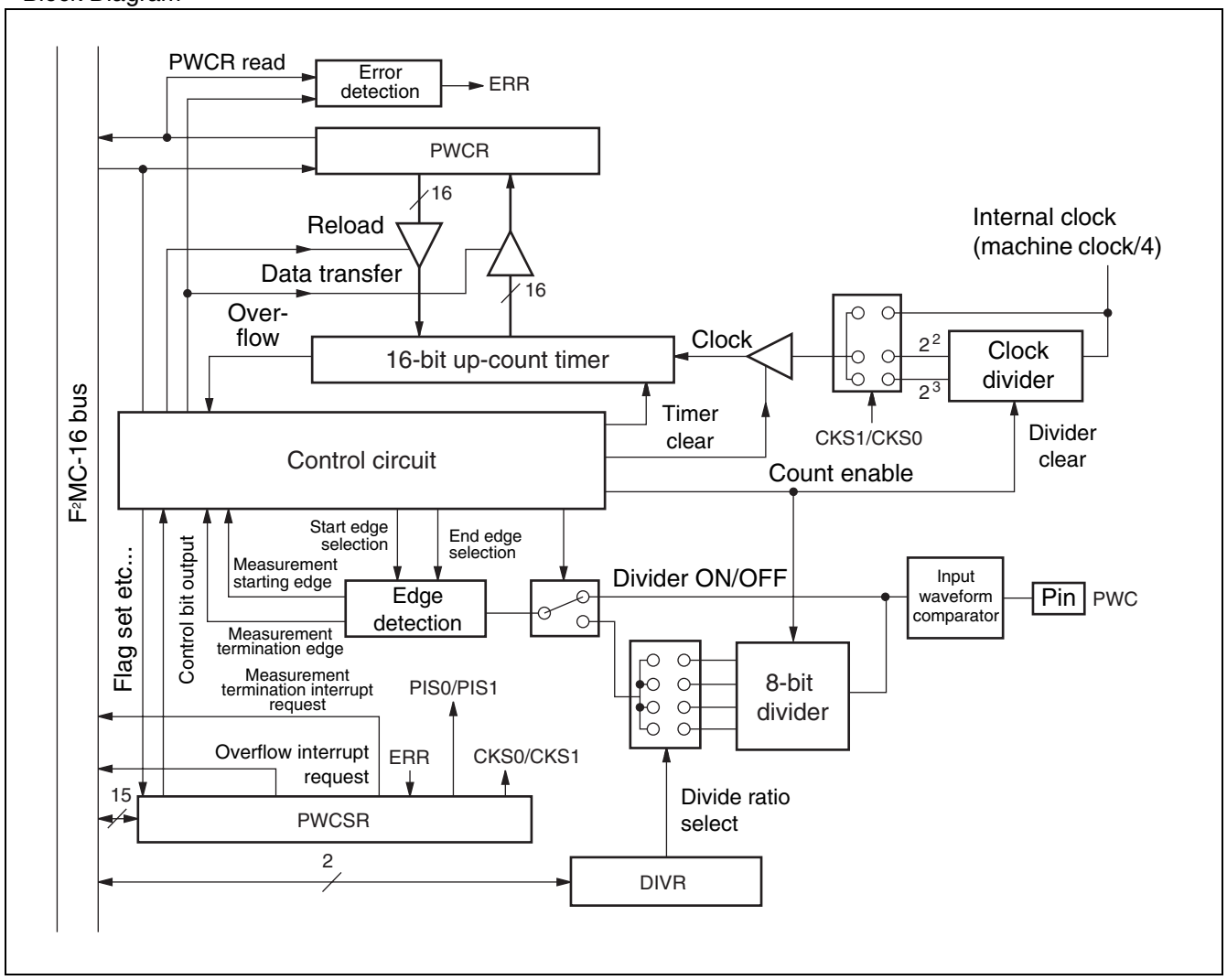
PWC ratio of dividing frequency control register (DIVR)

Address : 000060$_H$

7	6	5	4	3	2	1	0
—	—	—	—	—	—	DIV1	DIV0
(—)	(—)	(—)	(—)	(—)	(—)	(R/W)	(R/W)

Initial Value
------00$_B$

• Block Diagram



6. UART

UART is a general purpose serial communication interface for synchronous or asynchronous (start-stop synchronization) communications with external devices.

It supports bi-directional communication (normal mode) and master/slave communication (multi-processor mode: supported on master side only).

An interrupt can be generated upon completion of reception, detection of a reception error, or upon completion of transmission. EI^{2}OS is supported.

• UART functions

UART, or a generic serial data communication interface that sends and receives serial data to and from other CPU and peripherals, has the functions listed in following.

	Function
Data buffer	Full-duplex double-buffered
Transmission mode	• Clock synchronous (without start/stop bit) • Clock asynchronous (start-stop synchronous)
Baud rate	• Special-purpose baud-rate generator It is optional from 8 kinds. • Baud rate by external clock (clock of SCK0/SCK1 terminal input)
Data length	• 8-bit or 7-bit (in the asynchronous normal mode only) • 1 to 8 bits (in the synchronous mode only)
Signaling system	Non Return to Zero (NRZ) system
Reception error detection	• Framing error • Overrun error • Parity error (Not supported in operation mode 1)
Interrupt request	• Receive interrupt (reception completed, reception error detected) • Transmission interrupt (transmission completed) • Both the transmission and reception support EI^{2}OS.
Master/slave type communication function (multi processor mode)	Capable of 1 (master) to n (slaves) communication (available just as master)

Note : In clock synchronous transfer mode, the UART transfers only data with no start or stop bit added.

• UART operation modes

Operation mode		Data length		Synchronization	Stop bit length
		Without parity	With parity		
0	Normal mode	7-bit or 8-bit		Asynchronous	1-bit or 2-bit *2
1	Multi processor mode	8-bit + 1 *1	—	Asynchronous	
2	Normal mode	1 to 8-bit	—	Synchronous	No

— : Setting disabled

*1 : + 1 is an address/data setting bit (A/D) which is used for communication control.

*2 : Only one bit can be detected as a stop bit at reception.

• Register list

Serial mode register (SMR0, SMR1)

Address : 000020H / 000026H

7	6	5	4	3	2	1	0
MD1	MD0	SCKL	M2L2	M2L1	M2L0	SCKE	SOE
(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)

Initial Value 00100000B

Serial control register (SCR0, SCR1)

Address : 000021H / 000027H

15	14	13	12	11	10	9	8
PEN	P	SBL	CL	A/D	REC	RXE	TXE
(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(W)	(R/W)	(R/W)

Initial Value 00000100B

Serial input/output data register (SIDR0, SIDR1 / SODR0, SODR1)

Address : 000022H / 000028H

7	6	5	4	3	2	1	0
D7	D6	D5	D4	D3	D2	D1	D0
(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)

Initial Value XXXXXXXXB

Serial status register (SSR0, SSR1)

Address : 000023H / 000029H

15	14	13	12	11	10	9	8
PE	ORE	FRE	RDRF	TDRE	BDS	RIE	TIE
(R)	(R)	(R)	(R)	(R)	(R/W)	(R/W)	(R/W)

Initial Value 00001000B

UART prescaler reload register (UTRLR0, UTRLR1)

Address : 000024H / 00002AH

7	6	5	4	3	2	1	0
D7	D6	D5	D4	D3	D2	D1	D0
(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)

Initial Value 00000000B

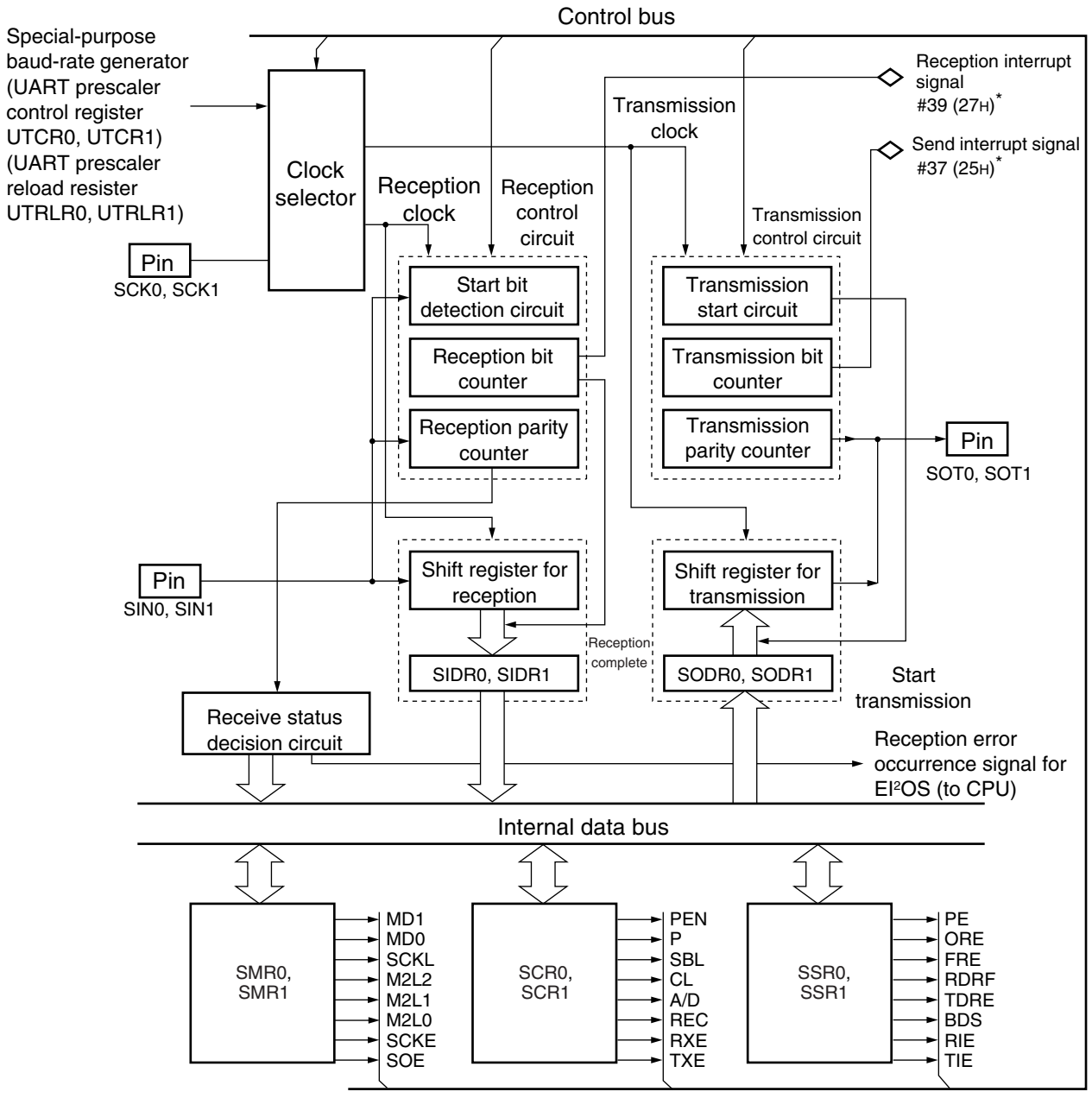
UART prescaler control register (UTCR0, UTCR1)

Address : 000025H / 00002BH

15	14	13	12	11	10	9	8
MD	SRST	CKS	Reserved	—	D10	D9	D8
(R/W)	(R/W)	(R/W)	(R/W)	(—)	(R/W)	(R/W)	(R/W)

Initial Value 0000-000B

• Block Diagram



* : Interrupt number

7. Extended I/O serial interface

The extended I/O serial interface is a serial I/O interface that can transfer data through the adoption of 8-bit × 1 channel configured clock synchronization scheme. LSB-first or MSB-first transfer mode can be selected for data transfer.

There are 2 serial I/O operation modes available:

- Internal shift clock mode : Transfer data in synchronization with the internal clock.
- External shift clock mode : Transfer data in synchronization with the clock supplied via the external pin (SCK). By manipulating the general-purpose port sharing the external pin (SCK) in this mode, data can also be transferred by a CPU instruction.

• Register list

Serial mode control status register (SMCS)

Address : 000059H

15	14	13	12	11	10	9	8
SMD2	SMD1	SMD0	SIE	SIR	BUSY	STOP	STRT
(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R)	(R/W)	(R/W)

Initial Value 00000010B

Address : 000058H

7	6	5	4	3	2	1	0
—	—	—	—	MODE	BDS	SOE	SCOE
(—)	(—)	(—)	(—)	(R/W)	(R/W)	(R/W)	(R/W)

Initial Value XXXX0000B

Serial data register (SDR)

Address : 00005AH

7	6	5	4	3	2	1	0
D7	D6	D5	D4	D3	D2	D1	D0
(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)

Initial Value XXXXXXXXB

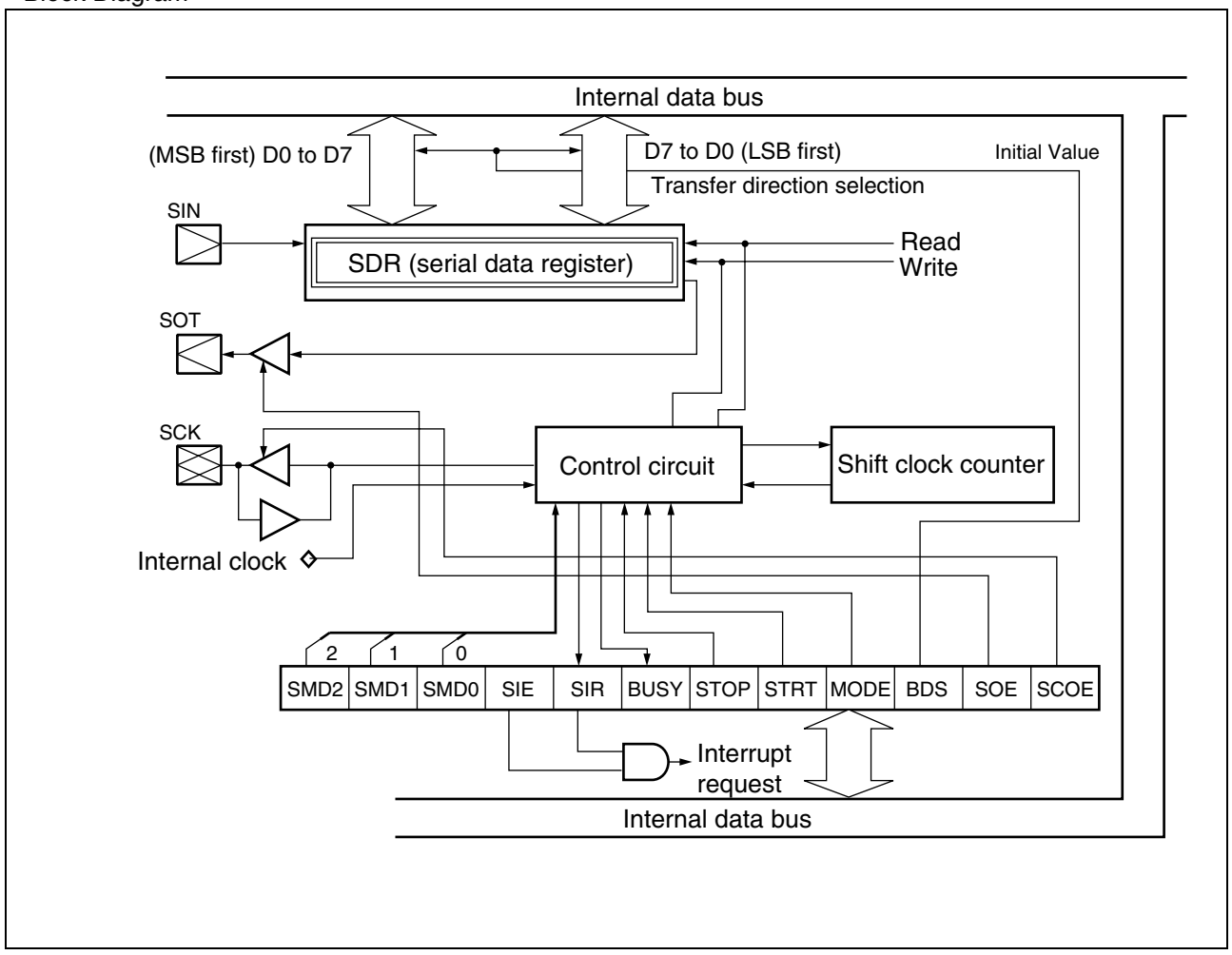
Communication prescaler control register (SDCR)

Address : 00005BH

15	14	13	12	11	10	9	8
MD	—	—	—	DIV3	DIV2	DIV1	DIV0
(R/W)	(—)	(—)	(—)	(R/W)	(R/W)	(R/W)	(R/W)

Initial Value 0XXX0000B

• Block Diagram



8. I²C Interface

The I²C interface is a serial I/O port supporting the Inter IC BUS. It serves as a master/slave device on the I²C bus and has the following features.

- Master/slave sending and receiving
- Arbitration function
- Clock synchronization function
- Slave address and general call address detection function
- Detecting transmitting direction function
- Start condition repeated generation and detection function
- Bus error detection function

• Register list

I²C bus status register (IBSR0)

Address : 000070H

7	6	5	4	3	2	1	0
BB	RSC	AL	LRB	TRX	AAS	GCA	FBT
(R)	(R)	(R)	(R)	(R)	(R)	(R)	(R)

Initial Value 00000000B

I²C bus control register (IBCR0)

Address : 000071H

15	14	13	12	11	10	9	8
BER	BEIE	SCC	MSS	ACK	GCAA	INTE	INT
(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)

Initial Value 00000000B

I²C bus clock control register (ICCR0)

Address : 000072H

7	6	5	4	3	2	1	0
—	—	EN	CS4	CS3	CS2	CS1	CS0
(—)	(—)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)

Initial Value XX0XXXXXB

I²C bus address register (IADR0)

Address : 000073H

15	14	13	12	11	10	9	8
—	A6	A5	A4	A3	A2	A1	A0
(—)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)

Initial Value XXXXXXXXB

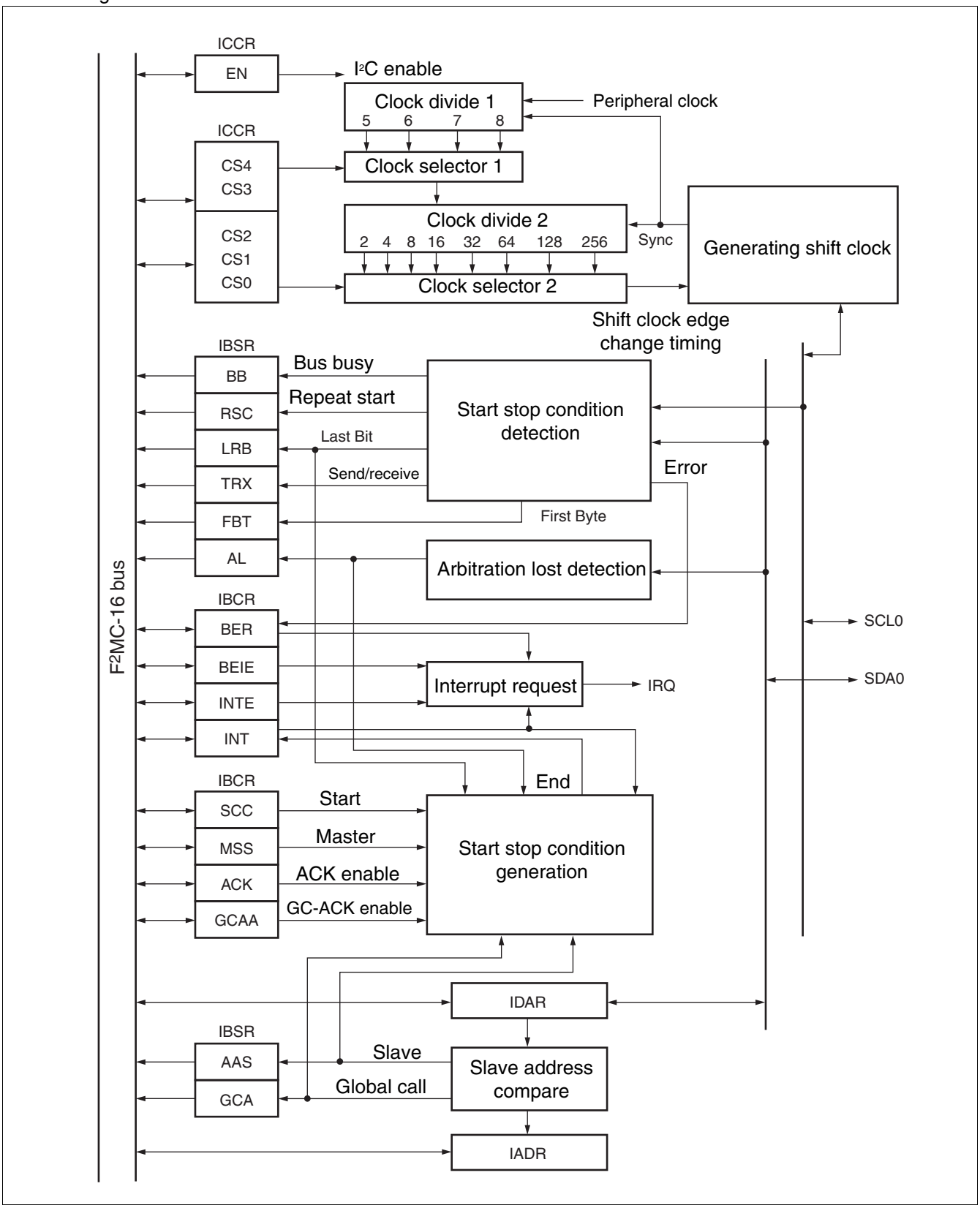
I²C bus data register (IDAR0)

Address : 000074H

7	6	5	4	3	2	1	0
D7	D6	D5	D4	D3	D2	D1	D0
(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)

Initial Value XXXXXXXXB

• Block Diagram



9. USB Function

The USB function is an interface supporting the USB (Universal Serial Bus) communications protocol.

Feature of USB function

- Conform to USB 2.0 Full Speed
- Full speed (12 Mbps) is supported.
- The device status is auto-answer.
- Bit stripping, bit stuffing, and automatic generation and check of CRC5 and CRC16.
- Toggle check by data synchronization bit.
- Automatic response to all standard commands except Get/SetDescriptor and SynchFrame commands (these three commands can be processed the same way as the class vendor commands).
- The class vendor commands can be received as data and responded via firmware.
- Supports up to maximum six EndPoints (EndPoint0 is fixed to control transfer).
- Two transfer data buffers integrated for each end point (one IN buffer and one OUT buffer for end point 0).
- Supports automatic transfer mode for transfer data via DMA (except buffers for EndPoint0).

• Register list

UDC control register (UDCC)

Address : 0000D0H

7	6	5	4	3	2	1	0	Initial Value
RST	RESUM	$\overline{\text{HCON}}$	USTP	Reserved	Reserved	RFBK	PWC	10100000B
(R/W)	(R/W)	(R/W)	(R/W)	(—)	(—)	(R/W)	(R/W)	

Address : 0000D1H

15	14	13	12	11	10	9	8	Initial Value
Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	00000000B
(—)	(—)	(—)	(—)	(—)	(—)	(—)	(—)	

EP0 control register (EP0C)

Address : 0000D2H

7	6	5	4	3	2	1	0	Initial Value
Reserved	PKS0	PKS0	PKS0	PKS0	PKS0	PKS0	PKS0	01000000B
(—)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	

Address : 0000D3H

15	14	13	12	11	10	9	8	Initial Value
—	—	—	—	Reserved	Reserved	STAL	Reserved	XXXX0000B
(—)	(—)	(—)	(—)	(—)	(—)	(R/W)	(—)	

EP1 control register (EP1C)

Address : 0000D4H

7	6	5	4	3	2	1	0	Initial Value
PKS1	PKS1	PKS1	PKS1	PKS1	PKS1	PKS1	PKS1	00000000B
(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	

Address : 0000D5H

15	14	13	12	11	10	9	8	Initial Value
EPEN	TYPE	TYPE	DIR	DMAE	NULE	STAL	PKS1	01100001B
(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	

(Continued)

EP2/3/4/5 control register (EP2C to EP5C)

Address : 0000D6H, 0000D8H, 0000DAH, 0000DCH

7	6	5	4	3	2	1	0	Initial Value
Reserved	PKS2~5	PKS2~5	PKS2~5	PKS2~5	PKS2~5	PKS2~5	PKS2~5	01000000B
(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	

Address : 0000D7H, 0000D9H, 0000DBH, 0000DDH

15	14	13	12	11	10	9	8	Initial Value
EPEN	TYPE	TYPE	DIR	DMAE	NULE	STAL	Reserved	01100000B
(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	

Time stamp register (TMSP)

Address : 0000DEH

7	6	5	4	3	2	1	0	Initial Value
TMSP	TMSP	TMSP	TMSP	TMSP	TMSP	TMSP	TMSP	00000000B
(R)	(R)	(R)	(R)	(R)	(R)	(R)	(R)	

Address : 0000DFH

15	14	13	12	11	10	9	8	Initial Value
—	—	—	—	—	TMSP	TMSP	TMSP	XXXXX000B
(—)	(—)	(—)	(—)	(—)	(R)	(R)	(R)	

UDC status register (UDCS)

Address : 0000E0H

7	6	5	4	3	2	1	0	Initial Value
—	—	SUSP	SOF	BRST	WKUP	SETP	CONF	XX000000B
(—)	(—)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	

UDC Interrupt enable register (UDCIE)

Address : 0000E1H

15	14	13	12	11	10	9	8	Initial Value
Reserved	Reserved	SUSPIE	SOFIE	BRSTIE	WKUPIE	CONFN	CONFIE	00000000B
(—)	(—)	(R/W)	(R/W)	(R/W)	(R/W)	(R)	(R/W)	

EP0I status register (EP0IS)

Address : 0000E2H

7	6	5	4	3	2	1	0	Initial Value
—	—	—	—	—	—	—	—	XXXXXXXXB
(—)	(—)	(—)	(—)	(—)	(—)	(—)	(—)	

Address : 0000E3H

15	14	13	12	11	10	9	8	Initial Value
BFINI	DRQIIE	—	—	—	DRQI	—	—	10XXX1XXB
(R/W)	(R/W)	(—)	(—)	(—)	(R/W)	(—)	(—)	

(Continued)

(Continued)

EP0O status register (EP0OS)

Address : 0000E4H

7	6	5	4	3	2	1	0	Initial Value
Reserved	SIZE	SIZE	SIZE	SIZE	SIZE	SIZE	SIZE	0XXXXXXXB
(—)	(R)	(R)	(R)	(R)	(R)	(R)	(R)	

Address : 0000E5H

15	14	13	12	11	10	9	8	Initial Value
BFINI	DRQOIE	SPKIE	—	—	DRQO	SPK	Reserved	100XX000B
(R/W)	(R/W)	(R/W)	(—)	(—)	(R/W)	(R/W)	(—)	

EP1 status register (EP1S)

Address : 0000E6H

7	6	5	4	3	2	1	0	Initial Value
SIZE	SIZE	SIZE	SIZE	SIZE	SIZE	SIZE	SIZE	XXXXXXXXB
(R)	(R)	(R)	(R)	(R)	(R)	(R)	(R)	

Address : 0000E7H

15	14	13	12	11	10	9	8	Initial Value
BFINI	DRQIE	SPKIE	Reserved	BUSY	DRQ	SPK	SIZE	1000000XB
(R/W)	(R/W)	(R/W)	(—)	(R)	(R/W)	(R/W)	(R)	

EP2/3/4/5 status register (EP2S to EP5S)

Address : 0000E8H, 0000EAH, 0000ECH, 0000EEH

7	6	5	4	3	2	1	0	Initial Value
Reserved	SIZE	SIZE	SIZE	SIZE	SIZE	SIZE	SIZE	0XXXXXXXB
(—)	(R)	(R)	(R)	(R)	(R)	(R)	(R)	

Address : 0000E9H, 0000EBH, 0000EDH, 0000EFH

15	14	13	12	11	10	9	8	Initial Value
BFINI	DRQIE	SPKIE	Reserved	BUSY	DRQ	SPK	Reserved	10000000B
(R/W)	(R/W)	(R/W)	(—)	(R)	(R/W)	(R/W)	(—)	

EP0/1/2/3/4/5 data register (EP0DT to EP5DT)

Address : 0000F0H, 0000F2H, 0000F4H, 0000F6H, 0000F8H, 0000FAH

7	6	5	4	3	2	1	0	Initial Value
BFDT	BFDT	BFDT	BFDT	BFDT	BFDT	BFDT	BFDT	XXXXXXXXB
(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	

Address : 0000F1H, 0000F3H, 0000F5H, 0000F7H, 0000F9H, 0000FBH

15	14	13	12	11	10	9	8	Initial Value
BFDT	BFDT	BFDT	BFDT	BFDT	BFDT	BFDT	BFDT	XXXXXXXXB
(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	

10. USB Mini-HOST

USB Mini-HOST provides minimal host operations required and is a function that enables data to be transferred to and from Device without PC intervention.

- Feature of USB Mini-HOST
  - Automatic detection of Low Speed/Full Speed transfer
  - Low Speed/Full Speed transfer support
  - Automatic detection of connection and cutting device
  - Reset sending function support to USB-bus
  - Support of IN/OUT/SETUP/SOF token
  - In-token handshake packet automatic transmission (excluding STALL)
  - Handshake packet automatic detection at out-token
  - Supports a maximum packet length of 256 bytes
  - Error (CRC error/toggle error/time-out) various supports
  - Wake-Up function support

- Differences between the USB HOST and USB Mini-HOST

		HOST	Mini-HOST
Hub support		○	×
Transfer	Bulk transfer	○	○
	Control transfer	○	○
	Interrupt transfer	○	○
	ISO transfer	○	×
Transfer speed	Low Speed	○	○
	Full Speed	○	○
PRE packet support		○	×
SOF packet support		○	○
Error	CRC error	○	○
	Toggle error	○	○
	Time-out	○	○
	Maximum packet < receive data	○	○
Detection of connection and cutting of device		○	○
Transfer speed detection		○	○

○ : Supported
× : Not supported

• Register list

Host control register 0 (HCNT0)

Address : 0000C0H

7	6	5	4	3	2	1	0	Initial Value
RWKIRE	URIRE	CMPIRE	CNNIRE	DIRE	SOFIRE	URST	HOST	00000000B
(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	

Host control register 1 (HCNT1)

Address : 0000C1H

15	14	13	12	11	10	9	8	Initial Value
Reserved	Reserved	Reserved	Reserved	Reserved	SOFSTEP	CANCEL	RETRY	00000001B
(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	

Host interruption register (HIRQ)

Address : 0000C2H

7	6	5	4	3	2	1	0	Initial Value
TCAN	Reserved	RWKIRQ	URIRQ	CMPIRQ	CNNIRQ	DIRQ	SOFIRQ	00000000B
(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	

Host error status register (HERR)

Address : 0000C3H

15	14	13	12	11	10	9	8	Initial Value
LSTSOF	RERR	TOUT	CRC	TGERR	STUFF	HS	HS	00000011B
(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	

Host state status register (HSTATE)

Address : 0000C4H

7	6	5	4	3	2	1	0	Initial Value
—	—	ALIVE	CLKSEL	SOFBUSY	SUSP	TMODE	CSTAT	XX010010B
(—)	(—)	(R/W)	(R/W)	(R/W)	(R/W)	(R)	(R)	

SOF interruption FRAME comparison register (HFCOMP)

Address : 0000C5H

15	14	13	12	11	10	9	8	Initial Value
FRAME COMP	FRAME COMP	FRAME COMP	FRAME COMP	FRAME COMP	FRAME COMP	FRAME COMP	FRAME COMP	00000000B
(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	

Retry timer setting register (HRTIMER)

Address : 0000C6H

7	6	5	4	3	2	1	0	Initial Value
RTIMER0	RTIMER0	RTIMER0	RTIMER0	RTIMER0	RTIMER0	RTIMER0	RTIMER0	00000000B
(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	

Address : 0000C7H

15	14	13	12	11	10	9	8	Initial Value
RTIMER1	RTIMER1	RTIMER1	RTIMER1	RTIMER1	RTIMER1	RTIMER1	RTIMER1	00000000B
(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	

Address : 0000C8H

7	6	5	4	3	2	1	0	Initial Value
—	—	—	—	—	—	RTIMER2	RTIMER2	XXXXXX00B
(—)	(—)	(—)	(—)	(—)	(—)	(R/W)	(R/W)	

(Continued)

(Continued)

Host address register (HADR)

Address : 0000C9H

15	14	13	12	11	10	9	8
—	ADDRESS	ADDRESS	ADDRESS	ADDRESS	ADDRESS	ADDRESS	ADDRESS
(—)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)

Initial Value X0000000B

EOF setting register (HEOF)

Address : 0000CAH

7	6	5	4	3	2	1	0
EOF0	EOF0	EOF0	EOF0	EOF0	EOF0	EOF0	EOF0
(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)

Initial Value 00000000B

Address : 0000CBH

15	14	13	12	11	10	9	8
—	—	EOF1	EOF1	EOF1	EOF1	EOF1	EOF1
(—)	(—)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)

Initial Value XX000000B

FRAME setting register (HFRAME)

Address : 0000CCH

7	6	5	4	3	2	1	0
FRAME0	FRAME0	FRAME0	FRAME0	FRAME0	FRAME0	FRAME0	FRAME0
(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)

Initial Value 00000000B

Address : 0000CDH

15	14	13	12	11	10	9	8
—	—	—	—	—	FRAME1	FRAME1	FRAME1
(—)	(—)	(—)	(—)	(—)	(R/W)	(R/W)	(R/W)

Initial Value XXXXX000B

Host token end point register (HTOKEN)

Address : 0000CEH

7	6	5	4	3	2	1	0
TGGL	TKNEN	TKNEN	TKNEN	ENDPT	ENDPT	ENDPT	ENDPT
(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)

Initial Value 00000000B

11. DTP/external interrupt circuit

DTP (Data Transfer Peripheral)/external interrupt circuit detects the interrupt request input from the external interrupt input terminal INT7 to INT0, and outputs the interrupt request.

• DTP/external interrupt circuit function

The DTP/external interrupt function outputs an interrupt request upon detection of the edge or level signal input to the external interrupt input pins (INT7 to INT0).

If CPU accept the interrupt request, and if the extended intelligent I/O service (EI²OS) is enabled, branches to the interrupt handling routine after completing the automatic data transfer (DTP function) performed by EI²OS. And if EI²OS is disabled, it branches to the interrupt handling routine without activating the automatic data transfer (DTP function) performed by EI²OS.

• Feature of DTP/external interrupt circuit

	External interrupt	DTP function
Input pin	8 channels (P60/INT0, P61/INT1, P62/INT2/SIN, P63/INT3/SOT, P64/INT4/SCK, P65/INT5/PWC, P66/INT6/SCL0, P67/INT7/SDA0)	
Interrupt source	The detection level or the type of the edge for each terminals can be set in the request level setting register (ELVR)	
	Input of “H” level/ “L” level/rising edge/falling edge.	
Interrupt number	#18 (12_H) , #20 (14_H) , #22 (16_H) , #24 (18_H)	
Interrupt control	Enabling/Prohibit the interrupt request output using the DTP/interrupt enable register (ENIR)	
Interrupt flag	Holding the interrupt source using the DTP/interrupt cause register (EIRR)	
Process setting	Prohibit EI²OS (ICR: ISE=“0”)	Enable EI²OS (ICR: ISE=“1”)
Process	Branched to the interrupt handling routine	After an automatic data transfer by EI²OS, Branched to the interrupt handling routine

• Register list

DTP/Interrupt enable register (ENIR)

Address : $00003C_H$

7	6	5	4	3	2	1	0
EN7	EN6	EN5	EN4	EN3	EN2	EN1	EN0
(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)

Initial Value 00000000_B

DTP/Interrupt source register (EIRR)

Address : $00003D_H$

15	14	13	12	11	10	9	8
ER7	ER6	ER5	ER4	ER3	ER2	ER1	ER0
(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)

Initial Value 00000000_B

Request level setting register (ELVR)

Address : $00003E_H$

7	6	5	4	3	2	1	0
LB3	LA3	LB2	LA2	LB1	LA1	LB0	LA0
(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)

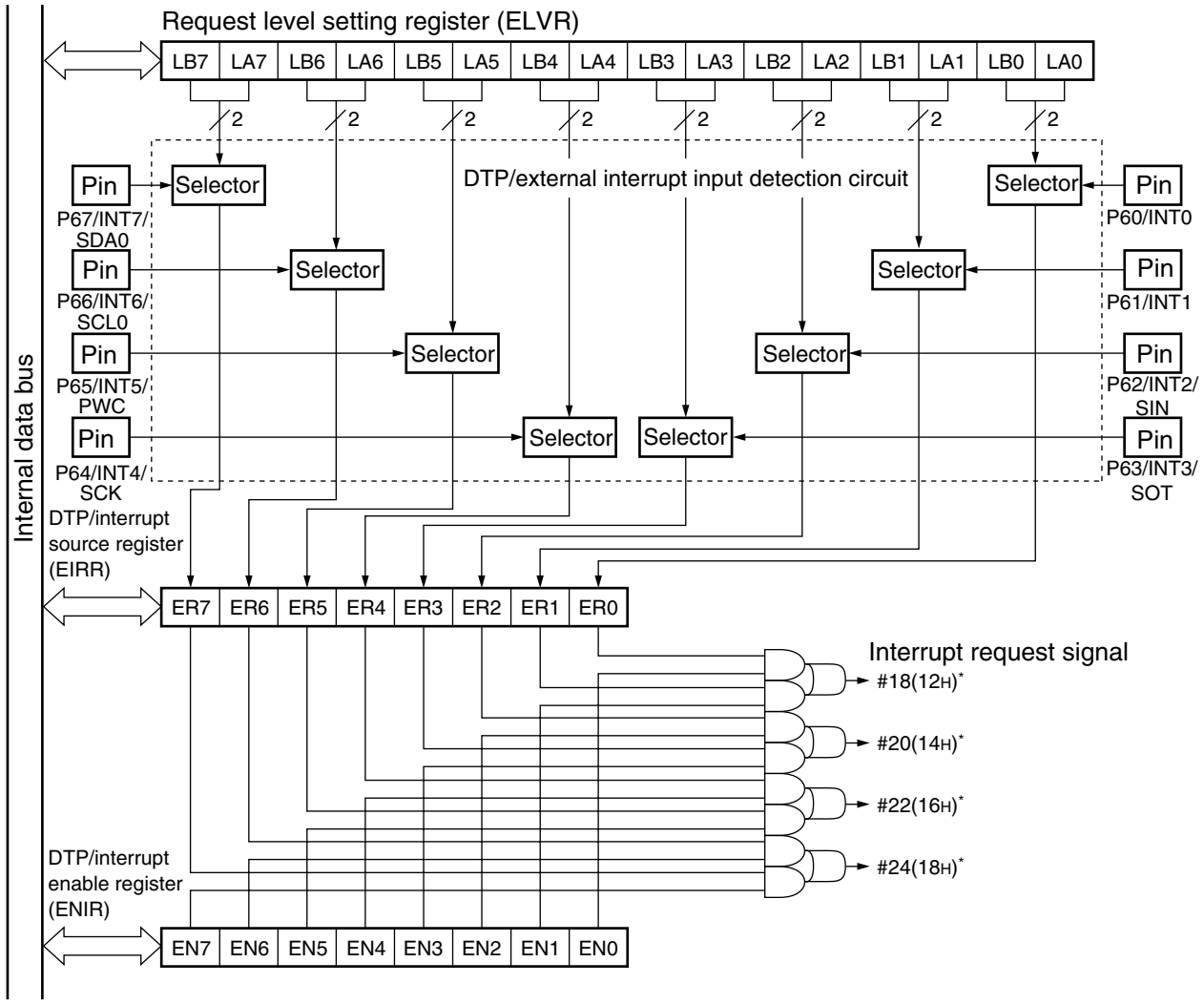
Initial Value 00000000_B

Address : $00003F_H$

15	14	13	12	11	10	9	8
LB7	LA7	LB6	LA6	LB5	LA5	LB4	LA4
(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)

Initial Value 00000000_B

• Block Diagram



* : Interrupt number

12. Interrupt controller

The interrupt control register is located inside the interrupt controller, it exists for every I/O having an interrupt function. This register has the following functions.

- Setting of the interrupt levels of relevant peripheral

• Register list

Interrupt control register (ICR01, ICR03, ICR05, ICR07, ICR09, ICR11, ICR13, ICR15)

Initial Value
00000111B

Address : ICR01 : 0000B1H
ICR03 : 0000B3H
ICR05 : 0000B5H
ICR07 : 0000B7H
ICR09 : 0000B9H
ICR11 : 0000BBH
ICR13 : 0000BDH
ICR15 : 0000BFH

15	14	13	12	11	10	9	8
ICS3	ICS2	ICS1	ICS0	ISE	IL2	IL1	IL0
(W)	(W)	(W)	(W)	(R/W)	(R/W)	(R/W)	(R/W)

Interrupt control register (ICR00, ICR02, ICR04, ICR06, ICR08, ICR10, ICR12, ICR14)

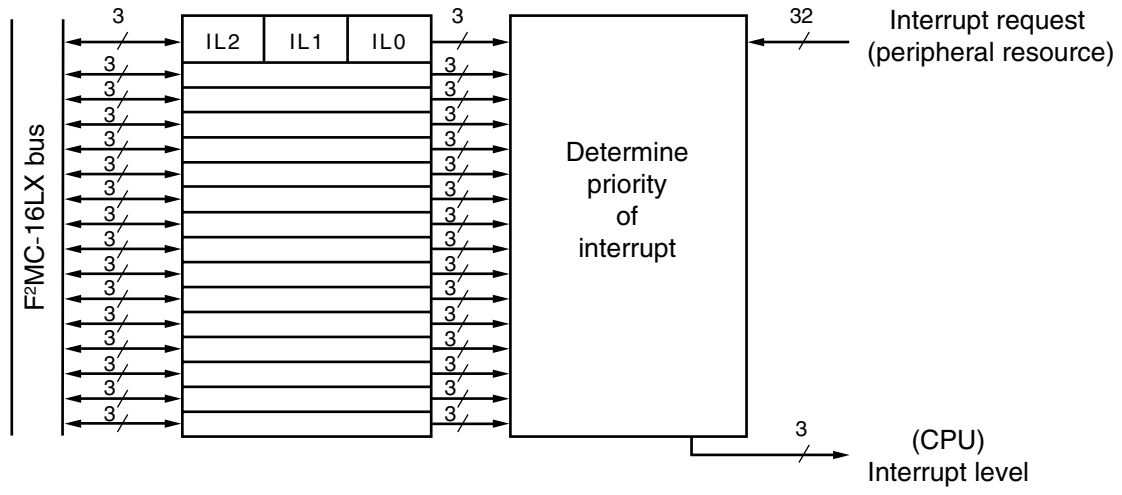
Initial Value
00000111B

Address : ICR00 : 0000B0H
ICR02 : 0000B2H
ICR04 : 0000B4H
ICR06 : 0000B6H
ICR08 : 0000B8H
ICR10 : 0000BAH
ICR12 : 0000BCH
ICR14 : 0000BEH

7	6	5	4	3	2	1	0
ICS3	ICS2	ICS1	ICS0	ISE	IL2	IL1	IL0
(W)	(W)	(W)	(W)	(R/W)	(R/W)	(R/W)	(R/W)

Note : Do not access interrupt control registers using any read modify write instruction because it causes a malfunction.

• Block Diagram



13. μDMAC

μDMAC is simple DMA with the function equal with EI²OS. It has 16 channels DMA transfer channels with the following features.

- Performs automatic data transfer between the peripheral resource (I/O) and memory
- The program execution of CPU stops in the DMA startup
- Capable of selecting whether to increment the transfer source and destination addresses
- DMA transfer is controlled by the DMA enable register, DMA stop status register, DMA status register and descriptor
- A STOP request is available for stopping DMA transfer from the resource
- Upon completion of DMA transfer, the flag bit corresponding to the transfer completed channel in the DMA status register is set and a termination interrupt is output to the transfer controller.

• Register list

DMA enable register upper (DERH)

Address : 0000AD$_H$

15	14	13	12	11	10	9	8
EN15	EN14	EN13	EN12	EN11	EN10	EN9	EN8
(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)

Initial Value 00000000$_B$

DMA enable register lower (DERL)

Address : 0000AC$_H$

7	6	5	4	3	2	1	0
EN7	EN6	EN5	EN4	EN3	EN2	EN1	EN0
(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)

Initial Value 00000000$_B$

DMA stop status register (DSSR)

Address : 0000A4$_H$

7	6	5	4	3	2	1	0
STP7 STP15	STP6 STP14	STP5 STP13	STP4 STP12	STP3 STP11	STP2 STP10	STP1 STP9	STP0 STP8
(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)

Initial Value 00000000$_B$ *

DMA status register upper (DSRH)

Address : 00009D$_H$

15	14	13	12	11	10	9	8
DTE15	DTE14	DTE13	DTE12	DTE11	DTE10	DTE9	DTE8
(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)

Initial Value 00000000$_B$

DMA status register lower (DSRL)

Address : 00009C$_H$

7	6	5	4	3	2	1	0
DTE7	DTE6	DTE5	DTE4	DTE3	DTE2	DTE1	DTE0
(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)

Initial Value 00000000$_B$

DMA descriptor channel specification register (DCSR)

Address : 00009B$_H$

7	6	5	4	3	2	1	0
STP	Reserved	Reserved	Reserved	DCSR3	DCSR2	DCSR1	DCSR0
(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)

Initial Value 00000000$_B$

* : The DSSR is lower when the STP bit of DCSR in the DSSR is “0”.
The DSSR is upper when the STP bit of DCSR in the DSSR is “1”.

(Continued)

(Continued)

DMA buffer address pointer lower 8 bit (DBAPL)

Address : 007920H

7	6	5	4	3	2	1	0	Initial Value
DBAPL	DBAPL	DBAPL	DBAPL	DBAPL	DBAPL	DBAPL	DBAPL	XXXXXXXXB
(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	

DMA buffer address pointer middle 8 bit (DBAPM)

Address : 007921H

15	14	13	12	11	10	9	8	Initial Value
DBAPM	DBAPM	DBAPM	DBAPM	DBAPM	DBAPM	DBAPM	DBAPM	XXXXXXXXB
(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	

DMA Buffer address pointer upper 8 bit (DBAPH)

Address : 007922H

7	6	5	4	3	2	1	0	Initial Value
DBAPH	DBAPH	DBAPH	DBAPH	DBAPH	DBAPH	DBAPH	DBAPH	XXXXXXXXB
(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	

DMA control register (DMACS)

Address : 007923H

15	14	13	12	11	10	9	8	Initial Value
RDY2	RDY1	BYTEL	IF	BW	BF	DIR	SE	XXXXXXXXB
(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	

DMA I/O register address pointer lower 8 bit (DIOAL)

Address : 007924H

7	6	5	4	3	2	1	0	Initial Value
A07	A06	A05	A04	A03	A02	A01	A00	XXXXXXXXB
(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	

DMA I/O register address pointer upper 8 bit (DIOAH)

Address : 007925H

15	14	13	12	11	10	9	8	Initial Value
A15	A14	A13	A12	A11	A10	A09	A08	XXXXXXXXB
(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	

DMA data counter lower 8 bit (DDCTL)

Address : 007926H

7	6	5	4	3	2	1	0	Initial Value
B07	B06	B05	B04	B03	B02	B01	B00	XXXXXXXXB
(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	

DMA data counter upper 8 bit (DDCTH)

Address : 007927H

15	14	13	12	11	10	9	8	Initial Value
B15	B14	B13	B12	B11	B10	B09	B08	XXXXXXXXB
(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	

Note : The above register is switched for each channel depending on the DCSR.

14. Address matching detection function

When the address is equal to the value set in the address detection register, the instruction code to be read into the CPU is forcibly replaced with the INT9 instruction code (01_H). As a result, the CPU executes the INT9 instruction when executing the set instruction. By performing processing by the INT#9 interrupt routine, the program patch function is enabled.
2 address detection registers are provided, for each of which there is an interrupt enable bit. When the address matches the value set in the address detection register with the interrupt enable bit set to 1, the instruction code to be read into the CPU is forcibly replaced with the INT9 instruction code.

• Register list

• Program address detect register 0 (PADR0)

PADR0 (lower)
Address : $001FF0_H$

7	6	5	4	3	2	1	0
(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)

Initial Value
$XXXXXXXX_B$

PADR0 (middle)
Address : $001FF1_H$

15	14	13	12	11	10	9	8
(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)

Initial Value
$XXXXXXXX_B$

PADR0 (upper)
Address : $001FF2_H$

7	6	5	4	3	2	1	0
(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)

Initial Value
$XXXXXXXX_B$

• Program address detect register 1 (PADR1)

PADR1 (lower)
Address : $001FF3_H$

15	14	13	12	11	10	9	8
(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)

Initial Value
$XXXXXXXX_B$

PADR1 (middle)
Address : $001FF4_H$

7	6	5	4	3	2	1	0
(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)

Initial Value
$XXXXXXXX_B$

PADR1 (upper)
Address : $001FF5_H$

15	14	13	12	11	10	9	8
(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)

Initial Value
$XXXXXXXX_B$

• Program address detect control status register (PACSR)

PACSR
Address : $00009E_H$

7	6	5	4	3	2	1	0
Reserved	Reserved	Reserved	Reserved	AD1E	Reserved	AD0E	Reserved
(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)

Initial Value
00000000_B

R/W : Readable and Writable
X : Undefined

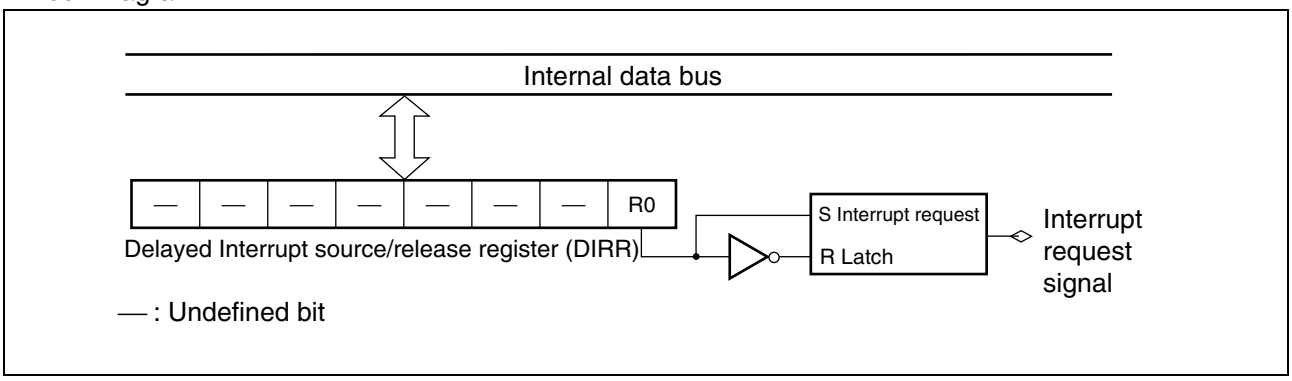
15. Delay interrupt generator module

The delay interrupt generation module is a module that generates interrupts for switching tasks. A hardware interrupt can be generated by software.

• Delay interrupt generator module function

	Function and control
Interrupt source	• Setting the R0 bit in the delayed interrupt request generation/release register to 1 (DIRR: R0 = 1) generates a delayed interrupt request. • Setting the R0 bit in the delayed interrupt request generation/release register to 0 (DIRR: R0 = 0) cancels the delayed interrupt request.
Interrupt control	No setting of permission register is provided.
Interrupt flag	Set in bit R0 of the delayed interrupt request generation /clear register (DIRR : R0)
EI²OS support	Not ready for extended intelligent I/O service (EI²OS).

• Block Diagram



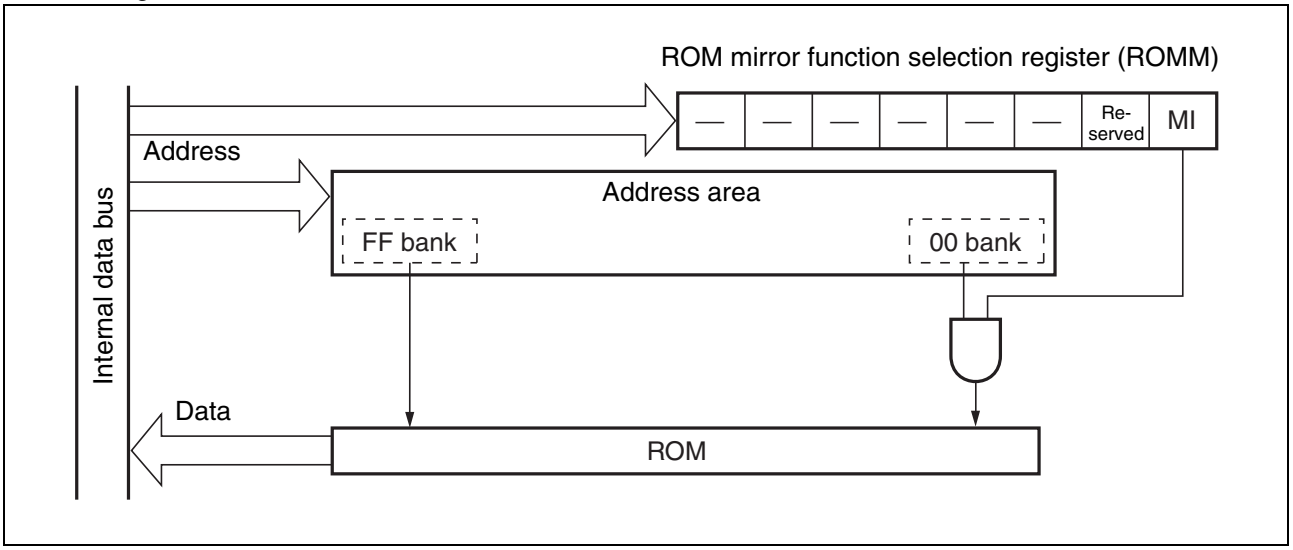
16. ROM mirroring function selection module

The ROM mirror function select module can make a setting so that ROM data located in bank FF can be read by accessing bank 00.

• ROM mirroring function selection module function

	Description
Mirror setting address	FFFFFF$_H$ to FF8000$_H$ in the FF bank can be read through 00FFFF$_H$ to 008000$_H$ in the 00 bank.
Interrupt source	None
EI^{2}OS support	Not ready for extended intelligent I/O service (EI^{2}OS).

• Block Diagram



17. Low power consumption (standby) mode

The F²MC-16LX can be set to save power consumption by selecting and setting the low power consumption mode.

• CPU operation mode and functional description

CPU operating clock	Operation mode	Description
PLL clock	Normal run	The CPU and peripheral resources operate at the clock frequency obtained by PLL multiplication of oscillator clock (HCLK) frequency.
	Sleep	Only peripheral resources operate at the clock frequency obtained by PLL multiplication of the oscillator clock (HCLK) frequency.
	Time-base timer	Only the time-base timer operates at the clock frequency obtained by PLL multiplication of the oscillator clock (HCLK) frequency.
	Stop	The CPU and peripheral resources are suspended with the oscillator clock stopped.
Main clock	Normal run	The CPU and peripheral resources operate at the clock frequency obtained by dividing the oscillator clock (HCLK) frequency by two.
	Sleep	Only peripheral resources operate at the clock frequency obtained by dividing the oscillator clock (HCLK) frequency by two.
	Time-base timer	Only the time-base timer operates at the clock frequency obtained by dividing the oscillator clock (HCLK) frequency by two.
	Stop	The CPU and peripheral resources are suspended with the oscillator clock stopped.
CPU intermittent operation mode	Normal run	The halved or PLL-multiplied oscillator clock (HCLK) frequency is used for operation while being decimated in a certain period.

• Register list

Low power consumption mode control register (LPMCR)

Address : 0000A0H

7	6	5	4	3	2	1	0
STP	SLP	SPL	RST	TMD	CG1	CG0	Reserved
(W)	(W)	(R/W)	(W)	(R/W)	(R/W)	(R/W)	(R/W)

Initial Value
00011000B

18. Clock

The clock generator controls the internal clock as the operating clock for the CPU and peripheral resources. The internal clock is referred to as machine clock whose one cycle is defined as machine cycle. The clock based on source oscillation is referred to as oscillator clock while the clock based on internal PLL oscillation as PLL clock.

• Register list

Clock selection register (CKSCR)

Address : 0000A1H

Initial Value
11111100B

15	14	13	12	11	10	9	8
SCM	MCM	WS1	WS0	SCS	MCS	CS1	CS0
(R)	(R)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)

19. 512 Kbits flash memory

The description that follows applies to the flash memory built in the MB90F337; it is not applicable to evaluation ROM or masked ROM.

The method of data write/erase to flash memory is following three types.

- Parallel writer
- Serial dedicated writer
- Write/erase by executing program

- Description of 512 Kbits flash memory

512 Kbits flash memory is located in FF_H bank in the CPU memory map. Function of flash memory interface circuit enables read and program access from CPU.
Write/erase to flash interface is executed by instruction from CPU via flash memory interface, so rewrite of program and data is carried on in the mounting state effectively.

Data can be reprogrammed not only by program execution in existing RAM but by program execution in flash memory by dual operation. Also, erase/write and read in the different bank (Upper Bank/Lower Bank) is executed simultaneously.

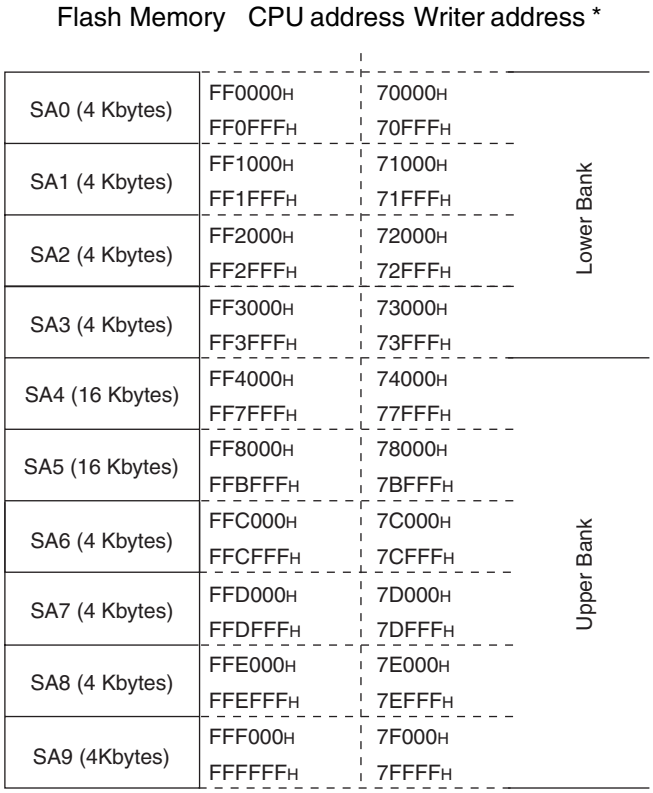
- Features of 512 Kbits flash memory
  - Sector configuration : 64 Kwords $\times$ 8 bits/32 words $\times$ 16 bits (4 K $\times$ 4 + 16 K $\times$ 2 + 4 K $\times$ 4)
  - Simultaneous execution of erase/write and read by 2-bank configuration
  - Automatic program algorithm (Embedded Algorithm™*)
  - Built-in deletion pause/deletion resume function
  - Detection of programming/erasure completion using data polling and the toggle bit
  - At least 10000 times guaranteed
  - Minimum flash read cycle time : 2 machine cycles

  * : Embedded Algorithm™ is a trade mark of Advanced Micro Devices Inc.

  Note : The read function of manufacture code and device code is not including.
  Also, these code is not accessed by the command.

  - Flash write/erase
  - Flash memory can not execute write/erase and read by the same bank simultaneously.
  - Data can be programmed/deleted into and erased from flash memory by executing either the program residing in the flash memory or the one copied to RAM from the flash memory.

• Sector configuration of flash memory



* : Flash memory writer address indicates the address equivalent to the CPU address when data is written to the flash memory using a parallel writer. Programming and erasing by the general-purpose parallel programmer are executed based on writer addresses.

• Register list

Flash memory control status register (FMCS)

Address : 0000AE$_H$

7	6	5	4	3	2	1	0
INTE	RDYINT	WE	RDY	Reserved	LPM1	Reserved	LPM0
(R/W)	(R/W)	(R/W)	(R)	(W)	(R/W)	(W)	(R/W)

Initial Value 000X0000$_B$

Flash memory program control register (FWR0)

Address : 00790C$_H$

7	6	5	4	3	2	1	0
SA7E	SA6E	SA5E	SA4E	SA3E	SA2E	SA1E	SA0E
(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)

Initial Value 00000000$_B$

Flash memory program control register (FWR1)

Address : 00790D$_H$

15	14	13	12	11	10	9	0
—	—	—	—	—	—	SA9E	SA8E
(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)	(R/W)

Initial Value 00000000$_B$

Sector conversion setting register (SSR0)

Address : 00790E$_H$

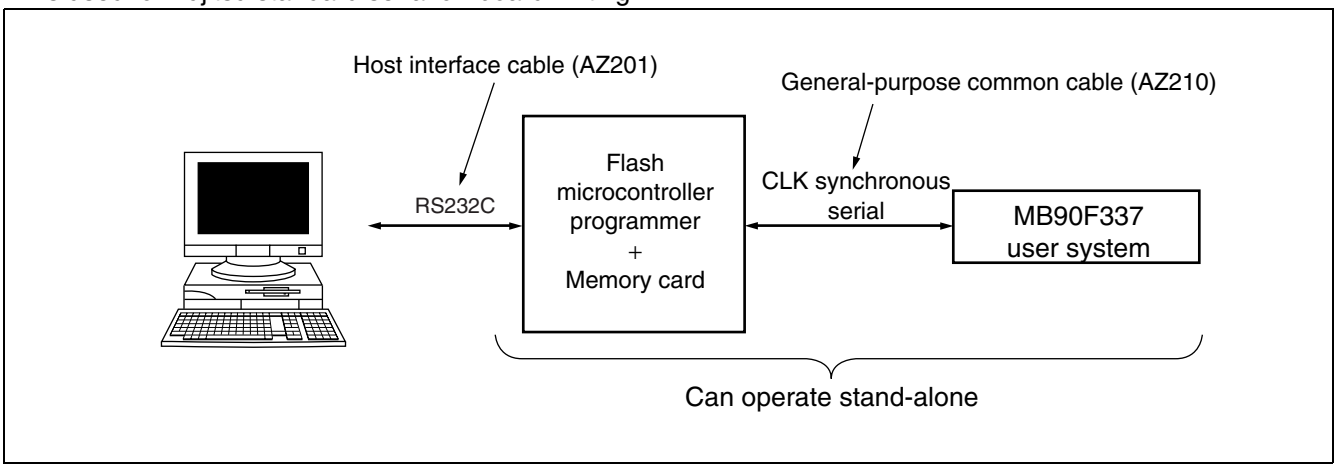
7	6	5	4	3	2	1	0
—	—	—	—	—	—	—	SEN0
(R/W)	(R/W)	(—)	(—)	(—)	(—)	(—)	(R/W)

Initial Value 00XXXXX0$_B$

Note : When writing to SSR0 register, write “0” except for SEN0.

• Standard configuration for Fujitsu standard serial on-board writing

The flash microcontroller programmer (AF220/AF210/AF120/AF110) made by Yokogawa Digital Computer Corp. is used for Fujitsu standard serial on-board writing.

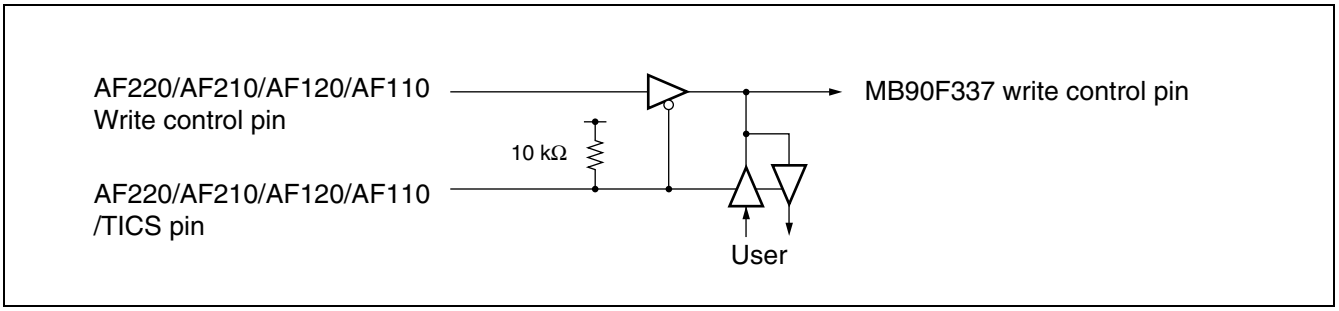


Note : Inquire of Yokogawa Digital Computer Corporation for details about the functions and operations of the flash microcontroller programmer (AF220, AF210, AF120 and AF110) , general-purpose common cable for connection (AZ210) and connectors.

• Pins Used for Fujitsu Standard Serial On-board Programming

Pin	Function	Description
MD2, MD1, MD0	Mode input pin	The device enters the serial program mode by setting MD2 = 1, MD1 = 1 and MD0 = 0.
X0, X1	Oscillation pin	Because the internal CPU operation clock is set to be the 1 multiplication PLL clock in the serial write mode, the internal operation clock frequency is the same as the oscillation clock frequency.
P60, P61	Write program start pins	Input a Low level to P60 and a High level to P61.
$\overline{RST}$	Reset input pin	—
SIN0	Serial data input pin	UART0 is used as CLK synchronous mode. In write mode, the pins used for the UART0 CLK synchronous mode are SIN0, SOT0, and SCK0.
SOT0	Serial data output pin	
SCK0	Serial clock input pin	
V_{CC}	Power source input pin	When supplying the write voltage (MB90F337 : 3.3 V±0.3 V) from the user system, connection with the flash microcontroller programmer is not necessary. When connecting, do not short-circuit with the user power supply.
V_{SS}	GND Pin	Share GND with the flash microcontroller programmer.

The control circuit shown in the figure is required for using the P60, P61, SIN0, SOT0 and SCK0 pins on the user system. Isolate the user circuit during serial on-board writing, with the /TICS signal of the flash microcontroller programmer.



Control circuit

The MB90F337 serial clock frequency that can be input is determined by the following expression. Use the flash microcontroller programmer to change the serial clock input frequency setting depending on the oscillator clock frequency to be used.

Inputable serial clock frequency = 0.125 × oscillation clock frequency.

• Maximum serial clock frequency

Oscillation clock frequency	Maximum serial clock frequency acceptable to the flash microcontroller	Maximum serial clock frequency that can be set with the AF220/AF210/ AF120/AF110	Maximum serial clock frequency that can be set with the AF200
At 6 MHz	750 kHz	500 kHz	500 kHz

• System configuration of the flash microcontroller programmer (AF220/AF210/AF120/AF110) (made by Yokogawa Digital Computer Corp.)

Part number		Function	
Unit	AF220/AC4P	Model with internal Ethernet interface	/100 V to 220 V power adapter
	AF210/AC4P	Standard model	/100 V to 220 V power adapter
	AF120/AC4P	Single key internal Ethernet interface mode	/100 V to 220 V power adapter
	AF110/AC4P	Single key model	/100 V to 220 V power adapter
AZ221		PC/AT RS232C cable for writer	
AZ210		Standard target probe (a) length : 1 m	
FF201		Control module for Fujitsu F²MC-16LX flash microcontroller control module	
AZ290		Remote controller	
/P2		2 MB PC Card (option) Flash memory capacity to respond to 128 KB	
/P4		4 MB PC Card (option) Flash memory capacity to respond to 512 KB	

Contact to : Yokogawa Digital Computer Corporation TEL : 81-423-33-6224

Note : The AF200 flash microcontroller programmer is a retired product, but it can be supported using control module FF201.

■ ELECTRICAL CHARACTERISTICS

1. Absolute Maximum Ratings

Parameter	Symbol	Rating		Unit	Remarks
		Min	Max		
Power supply voltage*1	V_{CC}	V_{SS} – 0.3	V_{SS} + 4.0	V	
Input voltage*1	V_I	V_{SS} – 0.3	V_{SS} + 4.0	V	*2
		V_{SS} – 0.3	V_{SS} + 6.0	V	N-ch open-drain (Withstand voltage I/O of 5 V)*3
		– 0.5	V_{SS} + 4.5	V	USB I/O
Output voltage*1	V_O	V_{SS} – 0.3	V_{SS} + 4.0	V	*2
		– 0.5	V_{SS} + 4.5	V	USB I/O
Maximum clamp current	I_{CLAMP}	– 2.0	+2.0	mA	*4
Total maximum clamp current	$\Sigma \lvert I_{CLAMP} \rvert$	—	20	mA	*4
"L" level maximum output current	I_{OL1}	—	10	mA	Other than USB I/O*5
	I_{OL2}	—	43	mA	USB I/O*5
"L" level average output current	I_{OLAV1}	—	4	mA	*6
	I_{OLAV2}	—	15/4.5	mA	USB-IO (Full speed/Low speed) *6
"L" level maximum total output current	ΣI_{OL}	—	100	mA	
"L" level average total output current	ΣI_{OLAV}	—	50	mA	*7
"H" level maximum output current	I_{OH1}	—	– 10	mA	Other than USB I/O*5
	I_{OH2}	—	– 43	mA	USB I/O*5
"H" level average output current	I_{OHAV1}	—	– 4	mA	*6
	I_{OHAV2}	—	–15/–4.5	mA	USB-IO (Full speed/Low speed) *6
"H" level maximum total output current	ΣI_{OH}	—	– 100	mA	
"H" level average total output current	ΣI_{OHAV}	—	– 50	mA	*7
Power consumption	Pd	—	270	mW	
Operating temperature	T_A	– 40	+ 85	°C	
Storage temperature	Tstg	– 55	+ 150	°C	
		– 55	+ 125	°C	USB I/O

*1 : The parameter is based on V_{SS} = 0.0 V.

*2 : V_I and V_O must not exceed V_{CC} + 0.3 V. However, if the maximum current to/from an input is limited by some means with external components, the I_{CLAMP} rating supersedes the V_I rating.

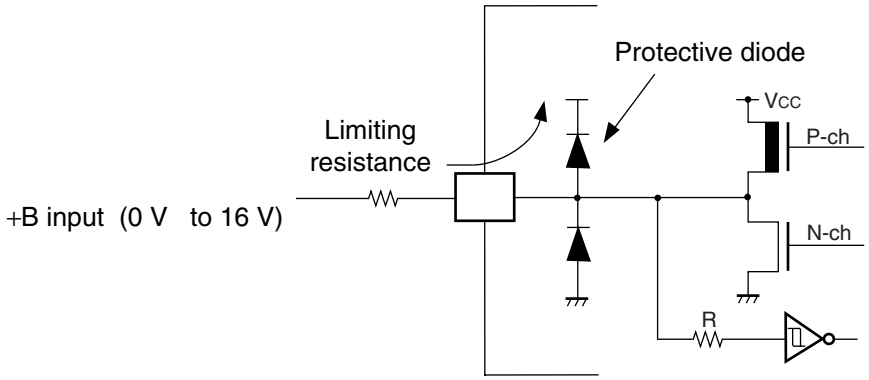
*3 : Applicable to pins : P60 to P67, UTEST

(Continued)

(Continued)

*4 :
- Applicable to pins: P00 to P07, P10 to P17, P20 to P27, P40 to P47, P50 to P54
- Use within recommended operating conditions.
- Use at DC voltage (current)
- The +B signal should always be applied a limiting resistance placed between the +B signal and the microcontroller.
- The value of the limiting resistance should be set so that when the +B signal is applied the input current to the microcontroller pin does not exceed rated values, either instantaneously or for prolonged periods.
- Note that when the microcontroller drive current is low, such as in the power saving modes, the +B input potential may pass through the protective diode and increase the potential at the V_{CC} pin, and this may affect other devices.
- Note that if a +B signal is input when the microcontroller power supply is off (not fixed at 0 V) , the power supply is provided from the pins, so that incomplete operation may result.
- Note that if the +B input is applied during power-on, the power supply is provided from the pins and the resulting supply voltage may not be sufficient to operate the power-on reset.
- Care must be taken not to leave the +B input pin open.
- Note that analog system input/output pins other than P60 to P67, DVP, DVM, HVP, HVM, UTEST, $\overline{HCON}$
- Sample recommended circuits:

• Input/output equivalent circuits



*5 : A peak value of an applicable one pin is specified as a maximum output current.

*6 : The average output current specifies the mean value of the current flowing in the relevant single pin during a period of 100 ms.

*7 : The average total output current specifies the mean value of the currents flowing in all of the relevant pins during a period of 100 ms.

WARNING: Semiconductor devices can be permanently damaged by application of stress (voltage, current, temperature, etc.) in excess of absolute maximum ratings. Do not exceed these ratings.

2. Recommended Operating Conditions

(V_{SS} = 0.0 V)

Parameter	Symbol	Value		Unit	Remarks
		Min	Max		
Power supply voltage	V_{CC}	3.0	3.6	V	At normal operation (When using USB)
		2.7	3.6	V	At normal operation (When not using USB)
		1.8	3.6	V	Hold state of stop operation
Input “H” voltage	V_{IH}	0.7 V_{CC}	V_{CC} + 0.3	V	CMOS input pin
	V_{IHS1}	0.8 V_{CC}	V_{CC} + 0.3	V	CMOS hysteresis input pin
	V_{IHS2}	0.8 V_{CC}	V_{SS} + 5.3	V	N-ch open-drain (Withstand voltage I/O of 5 V)*
	V_{IHM}	V_{CC} – 0.3	V_{CC} + 0.3	V	MD pin input
	V_{IHUSB}	2.0	V_{CC} + 0.3	V	USB pin input
Input “L” voltage	V_{IL}	V_{SS} – 0.3	0.3 V_{CC}	V	CMOS input pin
	V_{ILS}	V_{SS} – 0.3	0.2 V_{CC}	V	CMOS hysteresis input pin
	V_{ILM}	V_{SS} – 0.3	V_{SS} + 0.3	V	MD pin input
	V_{ILUSB}	V_{SS}	0.8	V	USB pin input
Differential input sensitivity	V_{DI}	0.2	—	V	USB pin input
Differential common mode input voltage range	V_{CM}	0.8	2.5	V	USB pin input
Operating temperature	T_A	– 40	+ 85	°C	When not using USB
		0	+ 70	°C	When using USB

* : Applicable to pins : P60 to P67, UTEST

WARNING: The recommended operating conditions are required in order to ensure the normal operation of the semiconductor device. All of the device’s electrical characteristics are warranted when the device is operated within these ranges.

Always use semiconductor devices within their recommended operating condition ranges. Operation outside these ranges may adversely affect reliability and could result in device failure.

No warranty is made with respect to uses, operating conditions, or combinations not represented on the data sheet. Users considering application outside the listed conditions are advised to contact their FUJITSU representatives beforehand.

3. DC Characteristics

(V_{CC} = 3.3 V ± 0.3 V, V_{SS} = 0.0 V, T_A = − 40 °C to +85 °C)

Parameter	Symbol	Pin name	Conditions	Value			Unit	Remarks
				Min	Typ	Max		
Output "H" voltage	V_{OH}	Output pins other than P60 to P67, HVP, HVM, DVP, DVM	I_{OH} = −4.0 mA	V_{CC} − 0.5	—	Vcc	V	
		HVP, HVM, DVP, DVM	R_L = 15 kΩ ± 5%	2.8	—	3.6	V	
Output "L" voltage	V_{OL}	Output pins other than HVP, HVM, DVP, DVM	I_{OL} = 4.0 mA	Vss	—	Vss + 0.4	V	
		HVP, HVM, DVP, DVM	R_L = 1.5 kΩ ± 5%	0	—	0.3	V	
Input leak current	I_{IL}	Output pins other than P60 to P67, HVP, HVM, DVP, DVM	V_{CC} = 3.3 V, Vss < V_I < V_{CC}	− 10	—	+ 10	µA	
		HVP, HVM, DVP, DVM	—	− 5	—	+ 5	µA	
Pull-up resistance	R_{PULL}	P00 to P07, P10 to P17	V_{CC} = 3.3 V, T_A = + 25 °C	25	50	100	kΩ	
Open drain output current	I_{LIOD}	P60 to P67	—	—	0.1	10	µA	
Power supply current	I_{CC}	V_{CC}	V_{CC} = 3.3 V, Internal frequency 24 MHz, At normal operating	—	55	65	mA	MB90F337
			At USB operating (USTP = 0)	—	50	60	mA	MB90337
			V_{CC} = 3.3 V, Internal frequency 24 MHz, At normal operating	—	50	60	mA	MB90F337
			At non-operating USB (USTP = 1)	—	45	55	mA	MB90337
	I_{CCS}		V_{CC} = 3.3 V, Internal frequency 24 MHz, At sleep mode	—	25	40	mA	
	I_{CTS}		V_{CC} = 3.3 V, Internal frequency 24 MHz, At timer mode	—	3.5	10	mA	
			V_{CC} = 3.3 V, Internal frequency 3 MHz, At timer mode	—	1.0	2.0	mA	
	I_{CCH}		T_A = +25 °C, At stop mode	—	1	40	µA	

(Continued)

(Continued)

(V_{CC} = 3.3 V ± 0.3 V, V_{SS} = 0.0 V, T_A = − 40 °C to +85 °C)

Parameter	Symbol	Pin name	Conditions	Value			Unit	Remarks
				Min	Typ	Max		
Input capacitance	C_{IN}	Other than Vcc and Vss	—	—	5	15	pF	
Pull-up resistor	R_{up}	$\overline{RST}$	—	25	50	100	kΩ	
Pull-down resistor	R_{down}	MD2	V_{CC} = 3.0 V At T_A = +25 °C	25	50	100	kΩ	MB90337
USB I/O output impedance	Z_{USB}	DVP, DVM HVP, HVM	—	3	—	14	Ω	

Note : P60 to P67 are N-ch open-drain pins usually used as CMOS.

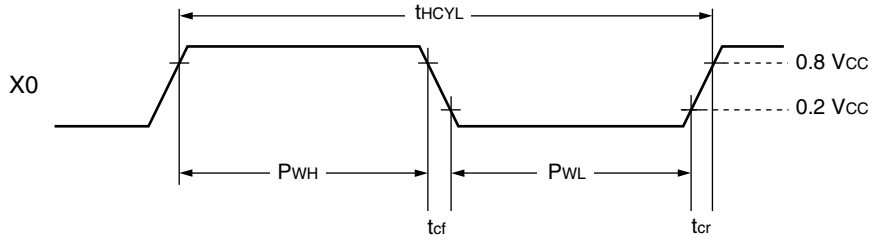
4. AC Characteristics

(1) Clock input timing

(V_{CC} = 3.3 V ± 0.3 V, V_{SS} = 0.0 V, T_A = − 40 °C to +85 °C)

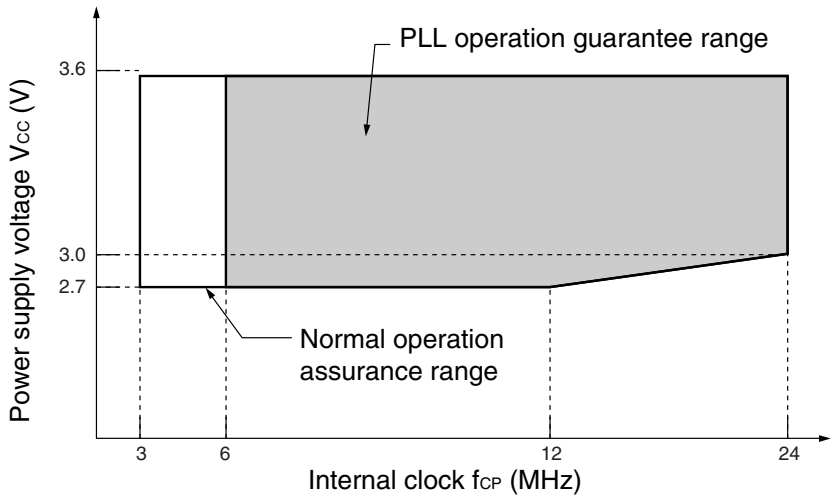
Parameter	Symbol	Pin name	Value			Unit	Remarks
			Min	Typ	Max		
Clock frequency	f_{CH}	X0, X1	—	6	—	MHz	When oscillator is used
			6	—	24	MHz	External clock input
Clock cycle time	t_{HCYL}	X0, X1	—	166.7	—	ns	When oscillator is used
			166.7	—	41.7	ns	External clock input
Input clock pulse width	P_{WH} P_{WL}	X0	10	—	—	ns	A reference duty ratio is 30% to 70%.
Input clock rise time and fall time	tcr tcf	X0	—	—	5	ns	At external clock
Internal operating clock frequency	f_{CP}	—	3	—	24	MHz	When main clock is used
Internal operating clock cycle time	t_{CP}	—	42	—	333	ns	When main clock is used

• Clock Timing



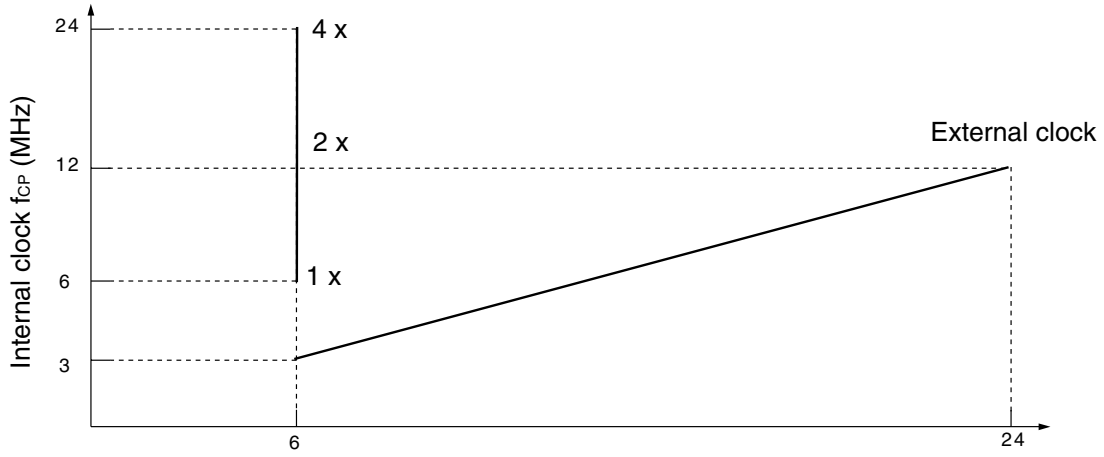
• PLL operation guarantee range

Relation between power supply voltage and internal operation clock frequency



Note : When the USB is used, operation is guaranteed at voltages between 3.0 V to 3.6 V.

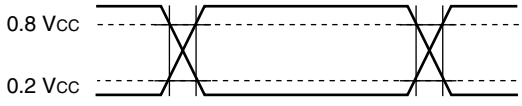
Relation between internal operation clock frequency and external clock frequency



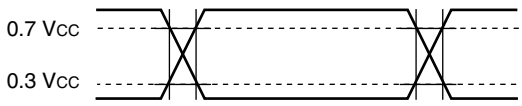
The AC standards provide that the following measurement reference voltages.

• Input signal waveform

Hysteresis input pin

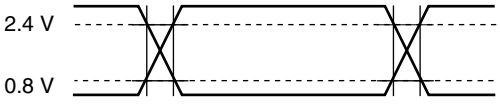


Hysteresis input/other than MD input pin



• Output signal waveform

Output pin



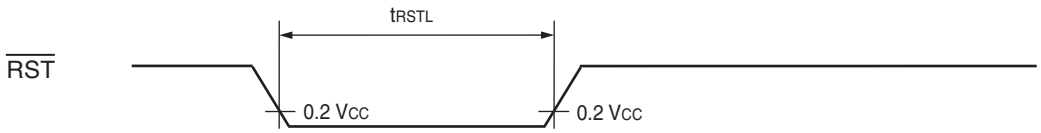
(2) Reset

(V_{CC} = 3.3 V ± 0.3 V, V_{SS} = 0.0 V, T_A = –40 °C to +85 °C)

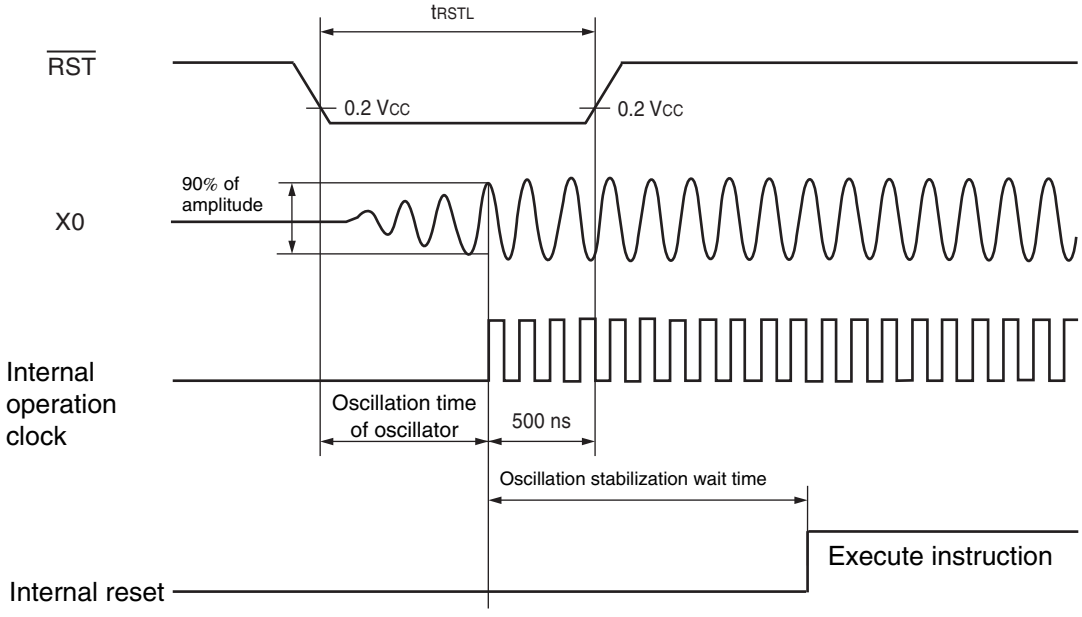
Parameter	Symbol	Pin name	Conditions	Value		Unit	Remarks
				Min	Max		
Reset input time	t_{RSTL}	$\overline{RST}$	—	500	—	ns	At normal operating, At time base timer mode, At main sleep mode, At PLL sleep mode
				Oscillation time of oscillator* + 500 ns	—	µs	At stop mode

* : Oscillation time of oscillator is the time that the amplitude reaches 90 %. It takes several milliseconds to several dozens of milliseconds on a crystal oscillator, several hundreds of microseconds to several milliseconds on a ceramic oscillator, and 0 milliseconds on an external clock.

• During normal operation, time-base timer mode, main sleep mode and PLL sleep mode



• During stop mode

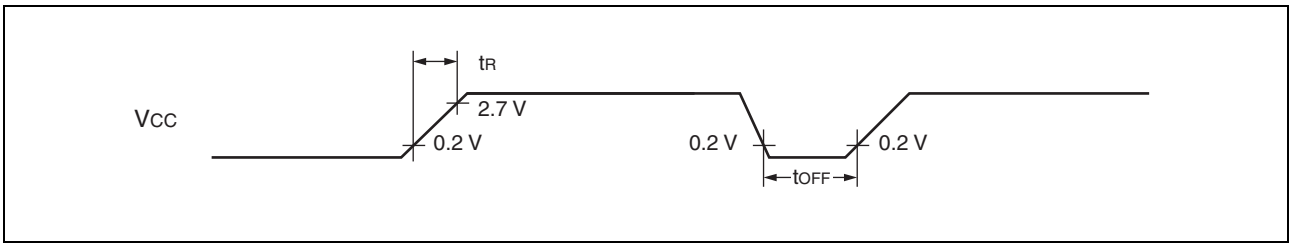


(3) Power-on reset

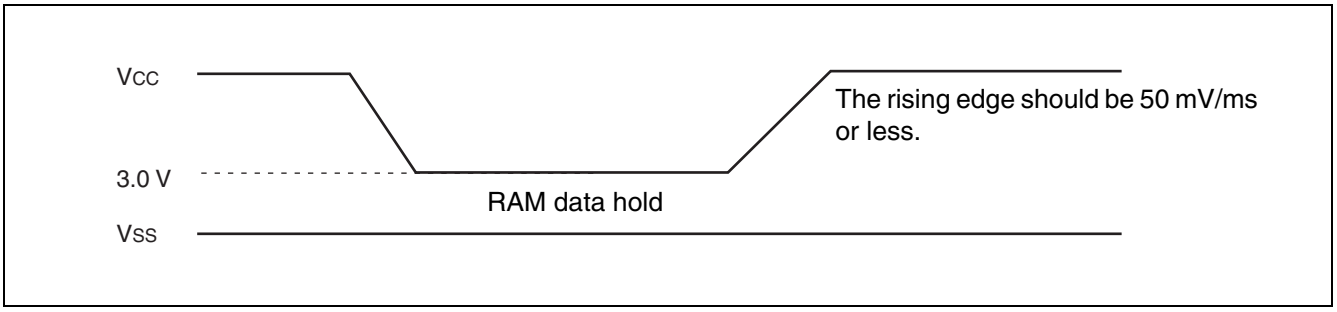
(V_{CC} = 3.3 V ± 0.3 V, V_{SS} = 0.0 V, T_A = –40 °C to +85 °C)

Parameter	Symbol	Pin name	Conditions	Value		Unit	Remarks
				Min	Max		
Power supply rising time	t_R	V_{CC}	—	0.05	30	ms	
Power supply shutdown time	t_{OFF}	V_{CC}		1	—	ms	Waiting time until power-on

Notes :
- V_{CC} must be lower than 0.2 V before the power supply is turned on.
- The above standard is a value for performing a power-on reset.
- In the device, there are internal registers which is initialized only by a power-on reset. When the initial ization of these items is expected, turn on the power supply according to the standards.



Note : Sudden change of power supply voltage may activate the power-on reset function.
When changing the power supply voltage during operation as illustrated below, voltage fluctuation should be minimized so that the voltage rises as smoothly as possible. When raising the power, do not use PLL clock. However, if voltage drop is 1 V/s or less, use of PLL clock is allowed during operation.



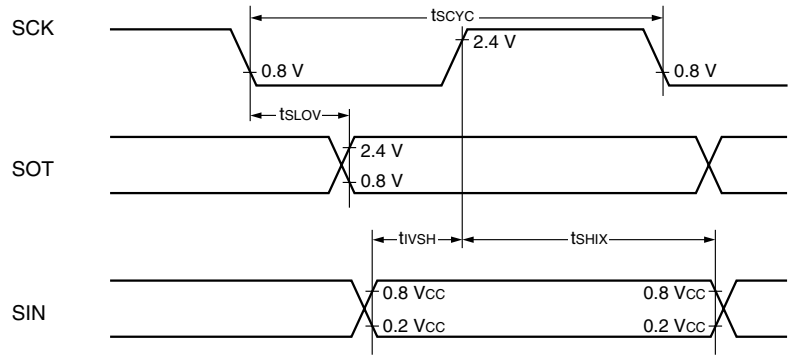
(4) UART0, UART1 I/O extended serial timing

(V_{CC} = 3.3 V ± 0.3 V, V_{SS} = 0.0 V, T_A = –40 °C to +85 °C)

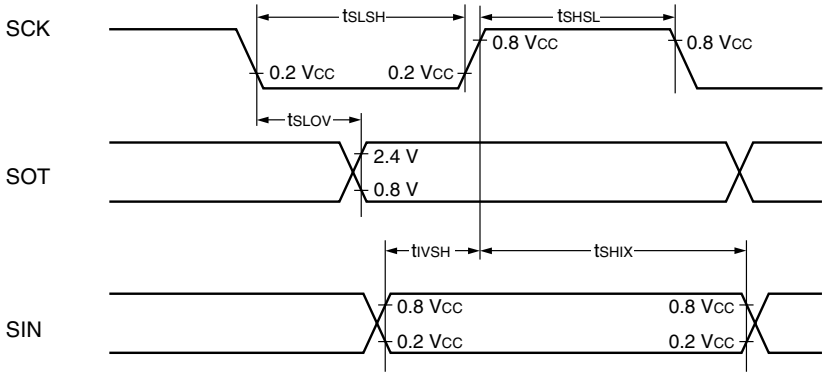
Parameter	Symbol	Pin name	Conditions	Value		Unit
				Min	Max	
Serial clock cycle time	t_{SCYC}	SCKx	Internal shift clock Mode output pin is C_L = 80 pF + 1 TTL	8 t_{CP}	—	ns
SCK ↓ → SOT delay time	t_{SLOV}	SCKx, SOTx		– 80	+ 80	ns
Valid SIN → SCK ↑	t_{IVSH}	SCKx, SINx		100	—	ns
SCK ↑ → valid SIN hold time	t_{SHIX}	SCKx, SINx		60	—	ns
Serial clock H pulse width	t_{SHSL}	SCKx, SINx	External shift clock Mode output pin is C_L = 80 pF + 1 TTL	4 t_{CP}	—	ns
Serial clock L pulse width	t_{SLSH}	SCKx, SINx		4 t_{CP}	—	ns
SCK ↓ → SOT delay time	t_{SLOV}	SCKx, SOTx		—	150	ns
Valid SIN → SCK ↑	t_{IVSH}	SCKx, SINx		60	—	ns
SCK ↑ → valid SIN hold time	t_{SHIX}	SCKx, SINx		60	—	ns

Notes :
- Above rating is the case of CLK synchronous mode.
- C_L is a load capacitance value on pins for testing.
- t_{CP} is the machine cycle period (unit : ns) . Refer to “ (1) Clock input timing”.

- Internal shift clock mode



- External shift clock mode



(5) I²C timing

(V_{CC} = 3.3 V ± 0.3 V, V_{SS} = 0.0 V, T_A = –40 °C to +85 °C)

Parameter	Symbol	Conditions	Value		Unit
			Min	Max	
SCL clock frequency	f_{SCL}	Power-supply of external pull-up resistor at 5.0 V R = 1.2 kΩ, C = 50 pF*2 Power-supply of external pull-up resistor at 3.6 V R = 1.0 kΩ, C = 50 pF*2	0	100	kHz
(Repeat) [start] condition hold time SDA ↓ → SCL ↓	t_{HDSTA}		4.0	—	µs
SCL clock “L” width	t_{LOW}		4.7	—	µs
SCL clock “H” width	t_{HIGH}		4.0	—	µs
Repeat [start] condition setup time SCL ↑ → SDA ↓	t_{SUSTA}		4.7	—	µs
Data hold time SCL ↓ → SDA ↓ ↑	t_{HDDAT}		0	3.45*3	µs
Data setup time SDA ↓ ↑ → SCL ↑	t_{SUDAT}	Power-supply of external pull-up resistor at 5.0 V f_{CP}*1 ≤ 20 MHz, R = 1.2 kΩ, C = 50 pF*2 Power-supply of external pull-up resistor at 3.6 V f_{CP}*1 ≤ 20 MHz, R = 1.0 kΩ, C = 50 pF*2	250*4	—	ns
		Power-supply of external pull-up resistor at 5.0 V f_{CP}*1 > 20 MHz, R = 1.2 kΩ, C = 50 pF*2 Power-supply of external pull-up resistor at 3.6 V f_{CP}*1 > 20 MHz, R = 1.0 kΩ, C = 50 pF*2	200*4	—	
[Stop] condition setup time SCL ↑ → SDA ↑	t_{SUSTO}	Power-supply of external pull-up resistor at 5.0 V R = 1.2 kΩ, C = 50 pF*2 Power-supply of external pull-up resistor at 3.6 V R = 1.0 kΩ, C = 50 pF*2	4.0	—	µs
Bus free time between [stop] condition and [start] condition	t_{BUS}		4.7	—	µs

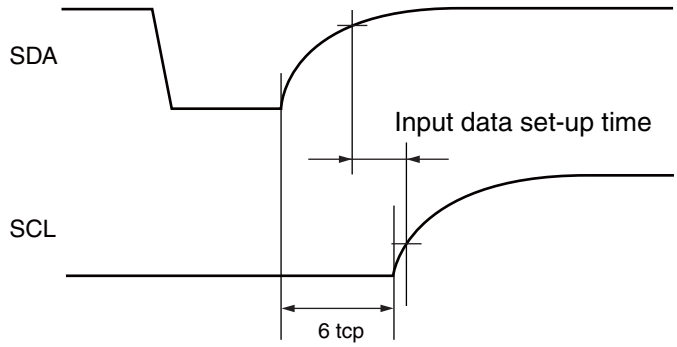
*1 : f_{CP} is internal operating clock frequency. Refer to “ (1) Clock input timing”.

*2 : R and C are pull-up resistance of SCL and SDA lines and load capacitance.

*3 : The maximum t_{HDDAT} only has to be met if the device does not stretch the “L” width (t_{LOW}) of the SCL signal.

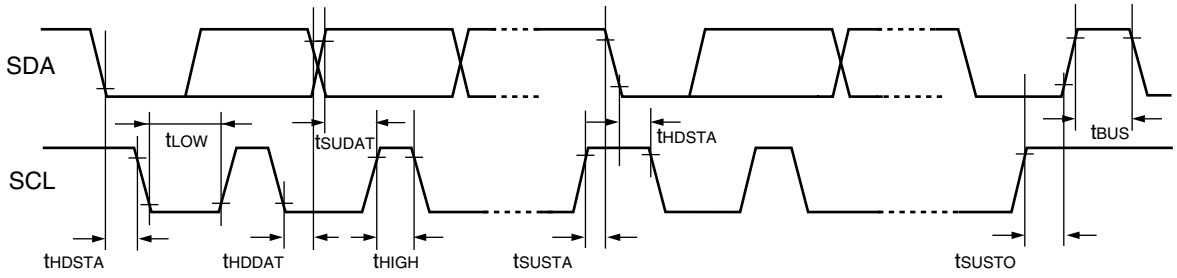
*4 : Refer to “• Note of SDA, SCL set-up time”.

•Note of SDA, SCL set-up time



Note : The rating of the input data set-up time in the device connected to the bus cannot be satisfied depending on the load capacitance or pull-up resistor.
Be sure to adjust the pull-up resistor of SDA and SCL if the rating of the input data set-up time cannot be satisfied.

•Timing definition

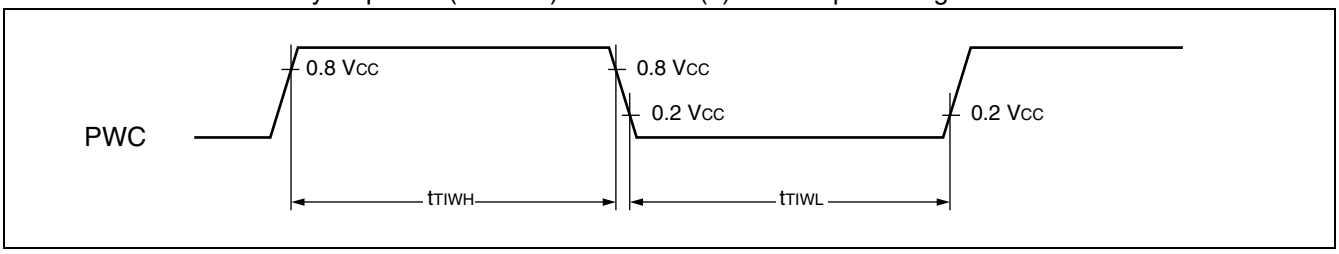


(6) Timer Input Timing

(V_{CC} = 3.3 V ± 0.3 V, V_{SS} = 0.0 V, T_A = –40 °C to +85 °C)

Parameter	Symbol	Pin name	Conditions	Value		Unit
				Min	Max	
Input pulse width	t_{TIWH} t_{TIWL}	PWC	—	4 t_{CP}	—	ns

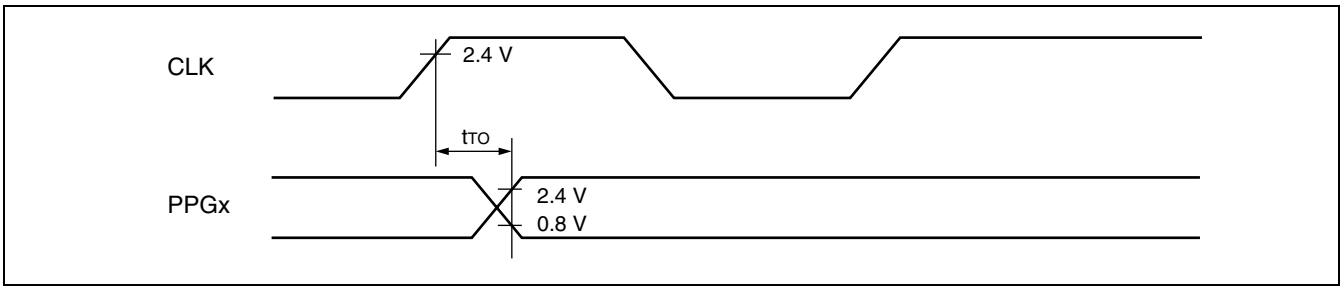
Note : t_{CP} is the machine cycle period (unit : ns) . Refer to " (1) Clock input timing".



(7) Timer output timing

(V_{CC} = 3.3 V ± 0.3 V, V_{SS} = 0.0 V, T_A = –40 °C to +85 °C)

Parameter	Symbol	Pin name	Conditions	Value		Unit
				Min	Max	
CLK ↑ → T_{OUT} change time PPG0 to PPG3 change time	t_{TO}	PPGx	—	30	—	ns

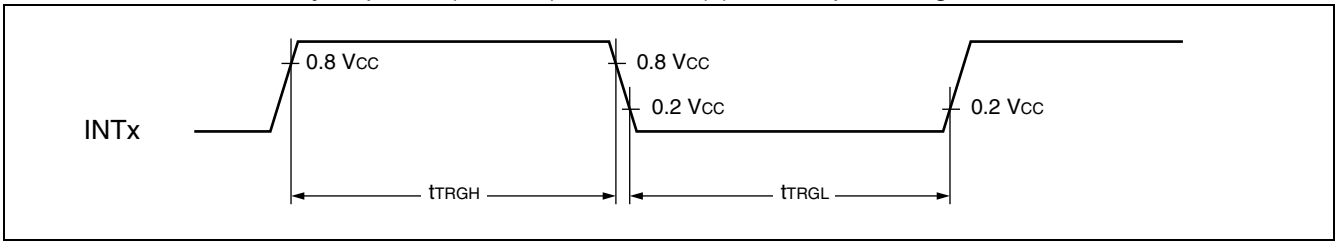


(8) Trigger Input Timing

(V_{CC} = 3.3 V ± 0.3 V, V_{SS} = 0.0 V, T_A = –40 °C to +85 °C)

Parameter	Symbol	Pin name	Conditions	Value		Unit	Remarks
				Min	Max		
Input pulse width	t_{TRGH} t_{TRGL}	INTx	—	5 t_{CP}	—	ns	At normal operating
				1	—	µs	At Stop mode

Note : t_{CP} is the machine cycle period (unit : ns) . Refer to " (1) Clock input timing".



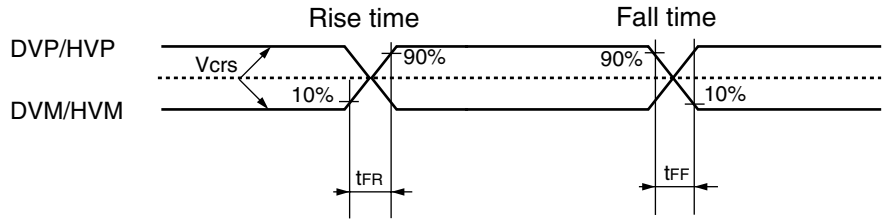
5. USB characteristics

(V_{CC} = 3.3 V ± 0.3 V, V_{SS} = 0.0 V, T_A = 0 °C to +70 °C)

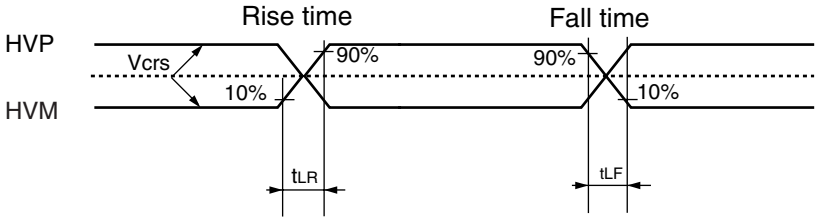
Parameter	Symbol	Sym-bol	Value		Unit	Remarks
			Min	Max		
Input characteristics	Input High level voltage	V_{IH}	2.0	—	V	
	Input Low level voltage	V_{IL}	—	0.8	V	
	Differential input sensitivity	V_{DI}	0.2	—	V	
	Differential common mode range	V_{CM}	0.8	2.5	V	
Output characteristics	Output High level voltage	V_{OH}	2.8	3.6	V	I_{OH} = –200 µA
	Output Low level voltage	V_{OL}	0.0	0.3	V	I_{OL} = 2 mA
	Cross over voltage	V_{CRS}	1.3	2.0	V	
	Rise time	t_{FR}	4	20	ns	Full Speed
		t_{LR}	75	300	ns	Low Speed
	Fall time	t_{FF}	4	20	ns	Full Speed
		t_{LF}	75	300	ns	Low Speed
	Rising/falling time matching	t_{RFM}	90	111.11	%	(T_{FR}/T_{FF})
		t_{RLM}	80	125	%	(T_{LR}/T_{LF})
	Output impedance	Z_{DRV}	28	44	Ω	Including Rs = 27 Ω
Series resistance		R_S	25	30	Ω	Recommended value = 27 Ω at using USB*

* : Arrange the series resistance RS values in order to set the impedance value within the output impedance ZSRV.

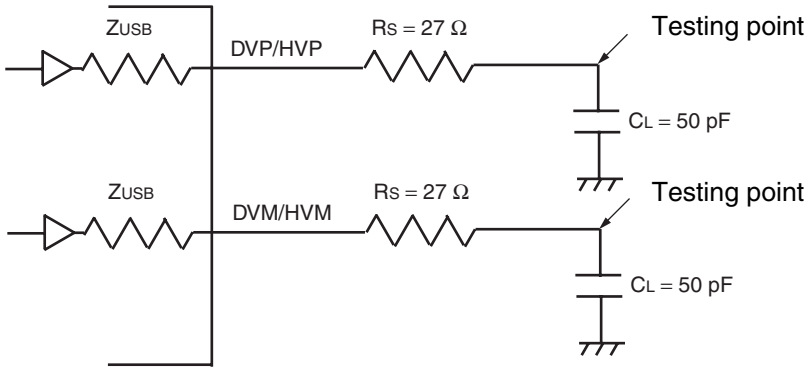
• Data signal timing (Full Speed)



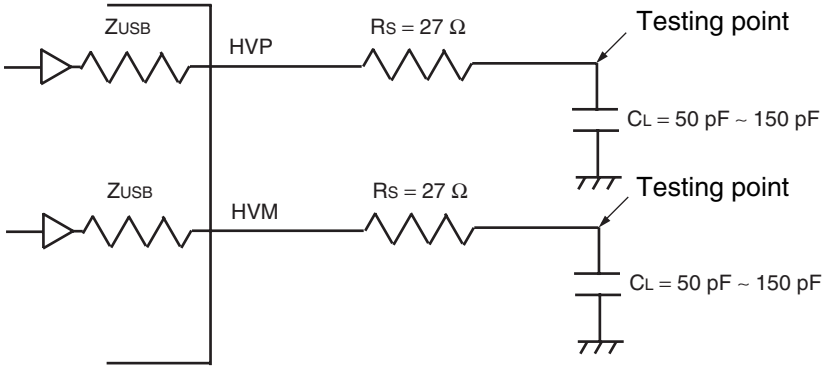
• Data signal timing (Low Speed)



• Load condition (Full Speed)



• Load condition (Low Speed)



6. Flash memory write/erase characteristics

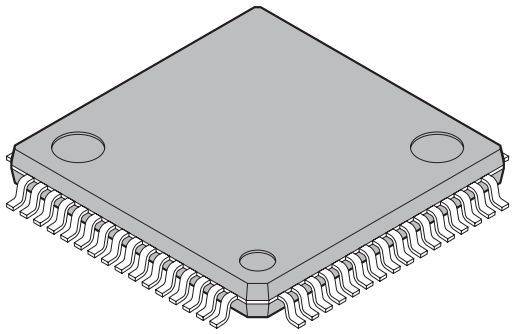
Parameter	Condition	Value			Unit	Remarks
		Min	Typ	Max		
Sector erase time (4 Kbytes sector)	T_A = + 25 °C V_{CC} = 3.0 V	—	0.2	0.5	s	Excludes 00_H programming prior to erasure.
Sector erase time (16 Kbytes sector)		—	0.5	7.5	s	Excludes 00_H programming prior to erasure.
Chip erase time		—	2.6	—	s	Excludes 00_H programming prior to erasure.
Word (8 bits width) programming time		—	16	3600	µs	Except for over head time of system
Program/erase cycle	—	10000	—	—	cycle	
Flash data retention time	Average T_A = + 85 °C	20	—	—	year	*

* : This value comes from the technology qualification. (using Arrhenius equation to translate high temperature measurements into normalized value at + 85 °C)

■ ORDERING INFORMATION

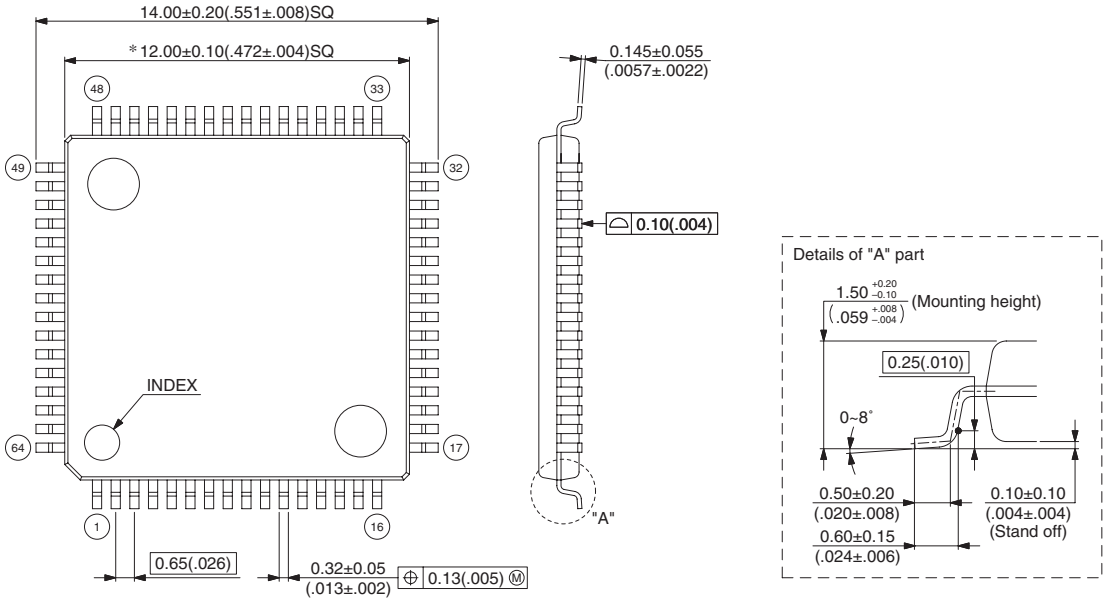
Part number	Package	Remarks
MB90F337PFM MB90337PFM	64-pin plastic LQFP (FPT-64P-M09)	
MB90V330A	299-pin ceramic PGA (PGA-299C-A01)	For evaluation

■ PACKAGE DIMENSION

64-pin plastic LQFP		
	Lead pitch	0.65 mm
	Package width × package length	12 × 12 mm
	Lead shape	Gullwing
	Sealing method	Plastic mold
	Mounting height	1.70 mm MAX
	Code (Reference)	P-LQFP64-12×12-0.65
(FPT-64P-M09)		

64-pin plastic LQFP
(FPT-64P-M09)

Note 1) * : These dimensions do not include resin protrusion.
Note 2) Pins width and pins thickness include plating thickness.
Note 3) Pins width do not include tie bar cutting remainder.



Dimensions in mm (inches).
Note: The values in parentheses are reference values.

Please confirm the latest Package dimension by following URL.
http://edevice.fujitsu.com/fj/DATASHEET/ef-ovpklv.html

■ MAIN CHANGES IN THIS EDITION

Page	Section	Change Results
4	■ PRODUCT LINEUP	Changed VBUS to UTEST.
5	■ PIN ASSIGNMENT	
7	■ PIN DESCRIPTION Pin no. 56, 57, 58	Changed the description; Data input pin for simple serial I/O → Data input pin for extended I/O serial interface
	Pin no. 1	For pin name, VBUS → UTEST For status at reset/ function, VBUS → UTEST input For function, " Status detection pin of USB cable (withstand voltage of 5 V)" → "USB test pin. Connect this to a pull-down resistor during normal usage."
10	■ HANDLING DEVICES 5. About crystal oscillator circuit	Added at the end of the section; Please ask the crystal maker to evaluate the oscillational characteristics of the crystal and this device.
12	■ BLOCK DIAGRAM	Changed VBUS to UTEST.
16	■ I/O MAP Address 000060_H	For the register, PWC Dividing Ratio Register → PWC Dividing Ratio Control Register
17	Address 000072_H	For the register, I^2C Bus Clock Selection Register → I^2C Bus Clock Control Register
	Address $0000A0_H$	For the register, Low Power Consumption Mode Register → Low Power Consumption Mode Control Register
	Address $0000A8_H$	For the register, Watchdog Control Register → Watchdog Timer Control Register
	Address $0000AE_H$	For the register abbreviation, FMCR → FMCS
18	Address $0000D1_H$	Prohibited → UDC Control Register
19	Address $0000D2_H$	For the initial value, $X1000000_B$ → 01000000_B
	Address $0000D3_H$	For the initial value, $XXXX000X_B$ → $XXXX0000_B$
	Address $0000DF_H$	For the initial value, 00000000_B → $XXXXX000_B$
	Address $0000E0_H$	For the initial value, 00000000_B → $XX000000_B$
	Address $0000E4_H$	For the initial value, $XXXXXXXX_B$ → $0XXXXXXX_B$
	Address $0000E5_H$	For the initial value, $100XX00X_B$ → $100XX000_B$
	Address $0000E9_H$, $0000EB_H$, $0000ED_H$, $0000EF_H$	For the initial value, $1000000X_B$ → 10000000_B
20	Address $00790C_H$	For the register, Flash Program Control Register 0 → Flash Memory Program Control Register 0
	Address $00790D_H$	For the register, Flash Program Control Register 1 → Flash Memory Program Control Register 1

(Continued)

Page	Section	Change Results
22	■ INTERRUPT SOURCES, INTERRUPT VECTORS, AND INTERRUPT CONTROL REGISTERS. USB function 2	For the μDMAC, “2 to 6” → “2 to 6*2”.
23		Added the footnote of *2.
	■ Content of USB Interruption Factor USB function 2	Added the “ * ” and its footnote.
	USB function 3	Deleted the VOFF, VON.
34	■ PERIPHERAL RESOURCES 5. Multifunction timer • 8/16-bit PPG timer	PPG control register (PPGC0 to PPGC3) → PPG operation mode control register (PPGC0 to PPGC3)
		PPG clock control register (PCS01, PCS23) → PPG output control register (PPG01, PPG23)
38	• PWC timer	Ratio of dividing frequency control register (DIVR) → PWC ratio of dividing frequency control register (DIVR)
41	6. UART	Serial input/output register (SIDR0, SIDR1/SODR0, SODR1) → Serial input/output data register (SIDR0, SIDR1/SODR0, SODR1)
		Serial data register (SSR0, SSR1) → Serial status register (SSR0, SSR1)
45	8. I^2C Interface	I^2C bus clock selection register (ICCR0) → I^2C bus clock control register (ICCR0)
47	9. USB Function	Deleted the following list; • Capable of detection of connection and disconnection by monitoring the USB bus power line.
		Changed the register list in UDC control register (UDCC) and EP0 control register (EP0C).
48		Changed the register list in Time stamp register (TMSP), UDC status register (UDCS), and UDC Interrupt enable register (UDCIE).
49		For EP0O status register (EP0OS), changed to “Reserved” for the bit8 and bit7 and changed the initial value.
		For EP1 status register (EP1S), changed to “Reserved” for the bit12 and changed (R/W) to (R) in the bit8 to bit0.
		For EP2/3/4/5 status register (EP2S to EP5S), changed to “Reserved” for bit12, bit8, bit7, (R/W) to (R) for the bit6 to bit0, and changed the initial values.
51	10. USB Mini-HOST	Deleted all of the “USB” from the register names. Changed the “USB retry timer setting register 0/1/2 (HRTIMER)” to “Retry timer setting register (HRTIMER)”.

(Continued)

(Continued)

Page	Section	Change Results
52	■ PERIPHERAL RESOURCES 10. USB Mini-HOST	Deleted all of the “USB” from the register names. Changed the “USB EOF setting register 0/1 (HEOF)” to “EOF setting register (HEOF)”.
		Changed the “USB token end point register (HTOKEN)” to “Host token end point register (HTOKEN)”.
65	19. 512 Kbits flash memory	Flash memory control register (FMCS) → Flash memory control status register (FMCS)
68	■ ELECTRICAL CHARACTERISTICS 1. Absolute Maximum Ratings	For “L” level average output current, I_{OLAV} “3” → I_{OLAV1} “4”, I_{OLAV2} “15/4.5”
		For “L" level maximum total output current, ΣI_{OL} “60” → ΣI_{OL} “100”
		For “L” level average total output current, ΣI_{OLAV} “30” → ΣI_{OLAV} “50”
		For “H” level average output current, I_{OHAV} “ – 3” → I_{OHAV1} “ – 4”, I_{OHAV2} “ – 15/ – 4.5”
		For “H” level maximum total output current, ΣI_{OH} “ – 60” → ΣI_{OH} “ – 100”
		For “H” level average total output current, ΣI_{OHAV} “ – 30” → ΣI_{OHAV} “ – 50”
		Changed the footnote *3 “Applicable to pins : P60 to P67, VBUS” to “Applicable to pins : P60 to P67, UTEST”
69		Changed the “VBUS” to “UTEST” in the footnote *4 “ • Note that analog system input/output pins other than P60 to P67, DVP,DVM, HVP, HVM, UTEST, $\overline{\text{HCON}}$”.
70	2. Recommended Operating Conditions	Deleted the “Series resistance”. Changed the “VBUS” to “UTEST” in the footnote.
72	3. DC Characteristics	Added the “USB I/O output impedance”.
76	4. AC Characteristics (3) Power-on reset	Changed the minimum value of the “Power supply rising time” : “—” → “0.05”
78	(5) I^2C timing	Added “*4” to the minimum value in the “Data setup time SDA ↓↑→ SCL↑ ” Added the footnote : *4 : Refer to “ • Note of SDA, SCL set-up time”.
81	5. USB characteristics	For the symbol of parameter, Output resistance of Output characteristics → Output impedance of Output characteristics. Added the “Series resistance”.
82		Changed the figures of “ • Load condition (Full Speed)” and “ • Load condition (Low Speed)”
84	■ ORDERING INFORMATION	Added the MB90V330A.

The vertical lines marked in the left side of the page show the changes.

MEMO

MEMO

MEMO

FUJITSU LIMITED

The contents of this document are subject to change without notice. Customers are advised to consult with sales representatives before ordering.

The information, such as descriptions of function and application circuit examples, in this document are presented solely for the purpose of reference to show examples of operations and uses of Fujitsu semiconductor device; Fujitsu does not warrant proper operation of the device with respect to use based on such information. When you develop equipment incorporating the device based on such information, you must assume any responsibility arising out of such use of the information. Fujitsu assumes no liability for any damages whatsoever arising out of the use of the information.

Any information in this document, including descriptions of function and schematic diagrams, shall not be construed as license of the use or exercise of any intellectual property right, such as patent right or copyright, or any other right of Fujitsu or any third party or does Fujitsu warrant non-infringement of any third-party's intellectual property right or other right by using such information. Fujitsu assumes no liability for any infringement of the intellectual property rights or other rights of third parties which would result from the use of information contained herein.

The products described in this document are designed, developed and manufactured as contemplated for general use, including without limitation, ordinary industrial use, general office use, personal use, and household use, but are not designed, developed and manufactured as contemplated (1) for use accompanying fatal risks or dangers that, unless extremely high safety is secured, could have a serious effect to the public, and could lead directly to death, personal injury, severe physical damage or other loss (i.e., nuclear reaction control in nuclear facility, aircraft flight control, air traffic control, mass transport control, medical life support system, missile launch control in weapon system), or (2) for use requiring extremely high reliability (i.e., submersible repeater and artificial satellite).

Please note that Fujitsu will not be liable against you and/or any third party for any claims or damages arising in connection with above-mentioned uses of the products.

Any semiconductor devices have an inherent chance of failure. You must protect against injury, damage or loss from such failures by incorporating safety design measures into your facility and equipment such as redundancy, fire protection, and prevention of over-current levels and other abnormal operating conditions.

Exportation/release of any products described in this document may require necessary procedures in accordance with the regulations of the Foreign Exchange and Foreign Trade Control Law of Japan and/or US export control laws.

The company names and brand names herein are the trademarks or registered trademarks of their respective owners.

Edited Strategic Business Development Dept.